

Reconciling truthfulness and relevance as epistemic and decision-theoretic utility

Theodore R. Sumers¹, Mark K. Ho¹, Thomas L. Griffiths^{1,2}, and Robert D. Hawkins³

¹Department of Computer Science, Princeton University

²Department of Psychology, Princeton University

³Princeton Neuroscience Institute, Princeton University

Author Note

We thank Xuechunzi Bai, Fred Callaway, Carlos Correa, Michael Franke, Adele Goldberg, and Noah Goodman for helpful discussions. TRS is supported by the NDSEG Fellowship Program and RDH is supported by the NSF (grant #1911835). This work was additionally supported by a John Templeton Foundation grant to TLG (grant #61454). We have no conflicts of interest to declare.

Experiment design and analyses were pre-registered at https://aspredicted.org/SPK_Z7Y and https://aspredicted.org/9MD_THB respectively. All materials, code, and data are available at <https://github.com/tsumers/relevance>. An early version of our model was presented at the 43rd Conference of the Cognitive Science Society. This manuscript is a draft (3/27/2023) and has not been peer-reviewed.

Correspondence should be addressed to Theodore Sumers. Email: sumers@princeton.edu.

Abstract

People use language to influence others' *beliefs* and *actions*. Yet models of communication have diverged along these lines, formalizing the speaker's objective in terms of *either* the listener's beliefs or actions. We argue that this divergence lies at the root of a longstanding controversy over the Gricean maxims of truthfulness and relevance. We first bridge the divide by introducing a speaker model which considers *both* the listener's beliefs (epistemic utility) and their actions (decision-theoretic utility). We show that formalizing truthfulness as an epistemic utility and relevance as a decision-theoretic utility reconciles the tension between them, readily explaining puzzles such as context-dependent standards of truthfulness. We then test a set of novel predictions generated by our combined model. We introduce a new signaling game which decouples utterances' truthfulness and relevance, then use it to conduct a pair of experiments. Our first experiment demonstrates that participants *jointly* maximize epistemic and decision-theoretic utility, rather than either alone. Our second experiment shows that when the two conflict, participants make a *graded tradeoff* rather than prioritizing one over the other. These results demonstrate that human communication cannot be reduced to influencing beliefs or actions alone. Taken together, our work provides a new foundation for grounding rational communication not only in what we *believe*, but in what those beliefs lead us to *do*.

Keywords: Gricean maxims, rational models of communication, truthfulness, relevance, pragmatics, decision theory

Reconciling truthfulness and relevance as epistemic and decision-theoretic utility

Language allows us to influence others' *beliefs* and *actions* (Austin, 1962; Clark, 1996; Grice, 1975; Lewis, 1969). Yet this flexibility creates a challenge: given such sway over others, how should a cooperative speaker choose what to say? Paul Grice (1957, 1975, 1989) studied this decision and outlined an influential set of principles—now known as Gricean maxims—governing everyday discourse. Two of these principles are *truthfulness* (“Do not say what you believe to be false”) and *relevance* (“Be relevant”; Grice, 1975). While formalizing truthfulness is relatively straightforward, relevance continues to pose serious difficulties for models of communication. Indeed, immediately after stating the maxim, Grice admitted that it “conceals a number of problems” (Grice, 1975, p. 46) and avowed a desire to clarify it. Nearly fifty years later, consensus on a definition of relevance remains stubbornly elusive (Grice, 1989; Merin, 1999; P. Parikh, 1992; Roberts, 2012; van Rooij, 2003; Sperber & Wilson, 1987), fueling controversy over the nature and primacy of different maxims.

Following Grice’s seminal work, classic formal models defined both truthfulness and relevance in terms of the listener’s belief states. These models assume that speakers’ basic objective is to induce true beliefs about the world (Frank & Goodman, 2012; Goodman & Frank, 2016; Lewis, 1969; Stalnaker, 1978), then use relevance to prioritize specific information (van Kuppevelt, 1995; Roberts, 2012). For example, consider approaching someone on the street and asking them for the time. This notion of relevance captures the expectation that the person would answer your question, rather than telling you what they ate for breakfast—even though either response would be informative about the true state of the world.

But would the person give you the *exact* time? Evidence suggests they would not. People often provide rounded times (e.g., saying 5:00pm when it is actually 4:57pm; van der Henst et al., 2002). This is an instance of “loose talk,” a broad phenomenon in which people produce and accept approximations that are “true enough” for a given context (Lewis, 1979; Sperber & Wilson, 1985). Critically, what is “true enough” varies depending on what the listener intends to *do* with the information. For example, speakers are significantly more likely to provide an exact time when asked in order to set a watch (Gibbs Jr & Bryant, 2008; van der Henst et al., 2002) or

when acting as a police witness (Mühlenbernd & Solt, 2022).¹ Because standards of precision are context-dependent, Relevance Theory rejects the maxim of truthfulness and instead advances “positive cognitive effects” as the fundamental objective of communication (Sperber & Wilson, 1986; Wilson & Sperber, 2002b). However, it has proven difficult to formalize this construct (for commentary, see Levinson, 1989; Merin, 1999; Sperber & Wilson, 1987).

Our definition of relevance instead draws on an *action*-oriented view of communication tracing back to Austin (1962). We extend the scope of our model to reflect how the information acquired within discourse affects behaviors outside of it. This approach, prevalent in game-theoretic pragmatics (Benz, 2006; Franke, 2009; van Rooij, 2003), experimental semiotics (Galantucci & Garrod, 2011; Lazaridou & Baroni, 2020) and artificial intelligence (Allen & Perrault, 1980; Cohen & Perrault, 1979), frames communication as an instrumental tool allowing the speaker to act through others (Clark, 1996). Yet action-oriented models are typically scoped to specialized subsets of language like instructions or questions and are not usually advanced as general-purpose theories of human communication (but see Cohen & Levesque, 1988; P. Parikh, 2001; Vanderveken, 1990).

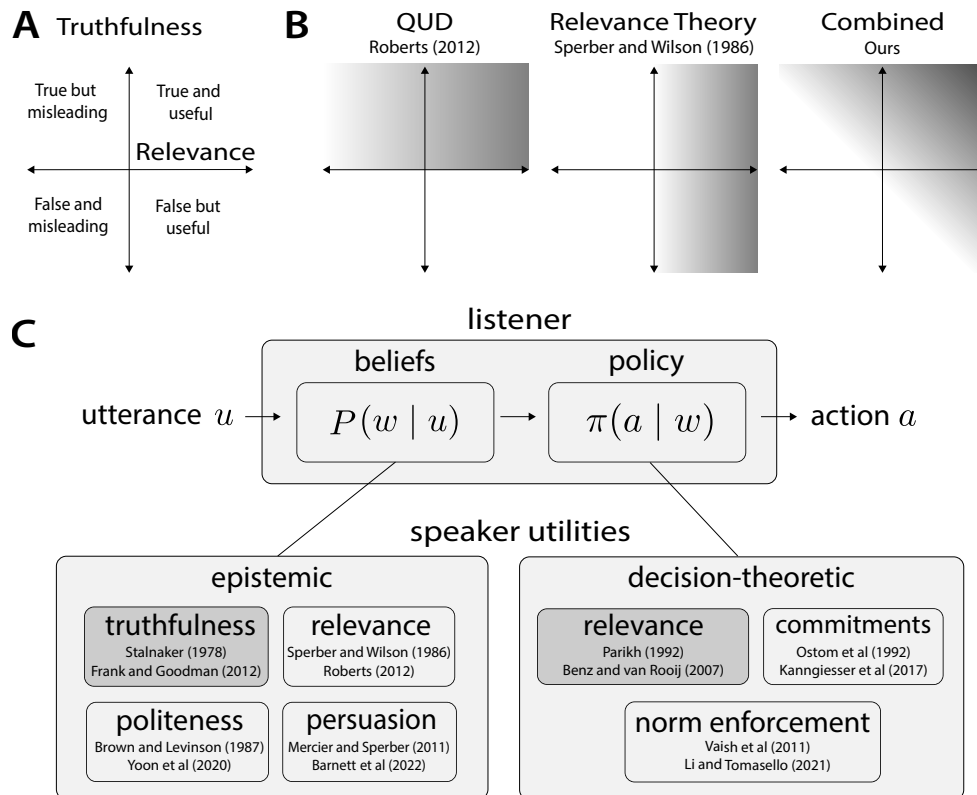
Thus, we reconcile truthfulness and relevance by integrating belief- and action-oriented approaches in a unified framework. Our computational model builds on the Rational Speech Act (RSA) framework (Frank & Goodman, 2012). The standard RSA model is *belief*-oriented, instantiating the maxims of truthfulness and relevance in an epistemic utility function (Goodman & Frank, 2016). We extend RSA by formalizing the listener as a rational agent who will *act* based on their beliefs. We then add a decision-theoretic utility function, quantifying relevance as the expected reward from the listener’s decision policy after hearing the utterance (Benz, 2006). Fig. 1 provides a schematic summary of these different models.

We first use this combined speaker model to explain classic examples from the literature. We show that the interaction between epistemic and decision-theoretic utility naturally focuses discourse (Roberts, 2012) while simultaneously predicting context-dependent deviations from truthfulness (van der Henst et al., 2002; Wilson & Sperber, 2002b). We then test novel

¹ Other classic examples include statements like “Holland is flat,” which would be acceptable when planning a cycling trip yet inappropriate in a geological survey (Wilson & Sperber, 2002b).

Figure 1

A schematic summary of theories.



Note. (A) We consider two dimensions of utterances: their truthfulness and their relevance. (B) Shading approximates the preference over utterances suggested by different models. The “question under discussion” (QUD; Roberts, 2012) assumes the speaker is truthful and favors utterances that are relevant. Relevance Theory (Sperber & Wilson, 1986) drops the constraint on truthfulness and suggests speakers will *only* produce relevant utterances (the “presumption of optimal relevance”). Our Combined model predicts a graded tradeoff between truthfulness and relevance. This captures a general preference for truthfulness while allowing for contextually-dependent “loose talk.” (C) Schematic of speaker utilities. Utterances affect the listener’s beliefs about the world $P(w | u)$, which in turn determine their policy for choosing actions $\pi(a | w)$. Previous approaches describe speaker objectives in terms of beliefs *or* actions. Our Combined speaker (dark gray boxes) considers both, formalizing truthfulness and relevance as epistemic and decision-theoretic utilities respectively. Beyond Grice’s maxims, a range of communicative motives—including politeness, persuasion, and enforcement of norms or commitments—can be seen as utilities over beliefs or actions. We return to extensions incorporating these utilities in the General Discussion.

predictions made by our model. To do so, we first introduce *signaling bandits*: a generalization of traditional Lewis signaling games (Lewis, 1969) to multi-armed bandit settings (Sutton & Barto, 2018). We report a pair of studies using this paradigm. Our first experiment shows that, as predicted by our combined model, participants follow *both* truthfulness and relevance rather than either alone. Our second experiment pits these two objectives against each other. We find that neither dominates. Instead, participants demonstrate a *graded tradeoff* between the two: they are willing to endorse false statements with sufficient decision-theoretic utility. This challenges the basic assumption shared by existing models that either truthfulness *or* relevance is the primary goal of communication. Instead, our work suggests that integrated models considering both beliefs and actions are needed to capture the interplay between these two distinct objectives.

Truthfulness, Relevance, and Speaker Goals

We begin by reviewing in depth the challenges facing existing modeling approaches. We first consider two *belief*-oriented approaches, which assume the speaker’s goals are epistemic but differ in whether they take truthfulness or relevance to be primary. We then discuss an alternative *action*-oriented approach, which considers goals grounded in real-world behaviors. We will argue these perspectives each capture important aspects of truthfulness and relevance, but fail to provide a suitably general framework for reconciling them.

Relevance to a “question under discussion”

Classical formal models of communication focus on the listener’s beliefs. They assume providing *truthful* information is the primary objective, and introduce *relevance* to focus discourse on particular facets of the true state of affairs. This view frames cooperative communication as information transfer between speaker and listener (De Saussure, 1916; Lewis, 1969; Shannon, 1948). The canonical setup assumes a set or distribution of possible world states, and specifies the goal of communication as aligning on the true state (Stalnaker, 1978). Perhaps the purest basis for this view is the central principle of “accuracy dominance” in epistemic utility theory (Caie, 2013; Carr, 2017; Greaves & Wallace, 2006; Joyce, 1998). For example, Pettigrew (2016) argues that accuracy is “the only fundamental epistemic virtue: all other epistemic virtues derive their

goodness from their ability to promote accuracy.” This truth-centric objective lies at the core of recent cognitive models: for example, informative speakers in the Rational Speech Act (RSA) framework (Frank & Goodman, 2012; Goodman & Frank, 2016) typically aim to reduce the listener’s uncertainty over the true world state.

But truthfulness alone is clearly a starting point rather than the complete picture: communicating the full state of the world is not a practical conversational goal. Speakers cannot know or express every detail of the true world state, and listeners would not care to know them. Thus, Grice’s maxim of relevance is invoked to focus discourse on some particular facet of the world. Belief-based accounts have typically brought in relevance by assuming the conversation is intended to answer a particular “Question Under Discussion” (QUD; Benz & Jasinskaja, 2017; van Kuppevelt, 1995; Roberts, 2012). The QUD *partitions* the set of possible worlds, where each cell of the partition contains worlds consistent with one answer to the question. The speaker then seeks to communicate which of these cells contains the true world state, rather than the precise identity of the world state itself. It effectively coarse-grains the set of possible worlds, allowing the speaker and listener to ignore irrelevant details. RSA-based models have integrated the notion of a QUD (Goodman & Lassiter, 2015) to explain interpretation of nonliteral or vague language in various forms (Hawkins et al., 2015; Kao & Goodman, 2015; Kao, Wu, et al., 2014; Lassiter & Goodman, 2017; Yoon et al., 2020).

Notably, the basic mechanics of the QUD formalism place the maxim of truthfulness *above* the maxim of relevance: speakers are assumed to produce utterances that select the cell containing the true state.² The assumption of truthfulness has proven impressively flexible, allowing listeners to derive a number of interesting implicatures from literally false utterances. For example, a listener hearing the hyperbolic statement “We waited years for a table” could make the statement truthful by constraining its meaning: in this case, inferring the speaker

² It may be objected that QUD-based speakers are not penalized for providing blatantly false information about irrelevant dimensions (Hoek, 2018), implicitly subordinating truthfulness about these dimensions. The important point is that the target cell under an epistemic QUD is determined solely in virtue of its relationship to *some* truthhood. Recent work outside the scope of our analysis has extended these techniques, allowing a speaker to be *underinformative* or *deceptive* in service of other conflicting non-epistemic goals, such as appearing competent (Yoon et al., 2018) or prosocial (Yoon et al., 2020), or being persuasive in service of a hidden agenda (Barnett et al., 2022).

intends to convey their annoyance about the event rather than literally describe its duration (Kao, Wu, et al., 2014). Similarly, given a metaphor like “John is a shark,” a listener may infer that John shares a relevant subset of characteristics with sharks—such as aggressiveness—rather than literally being a member of that species (Kao, Bergen, et al., 2014). In these cases, the background assumption of truthfulness with respect to *something*, together with structured world knowledge, can be used to constrain meaning appropriately. However, the underlying assumption that speakers attempt to communicate truthfully faces serious challenges.

Relevance as a “supermaxim”

An alternative proposal, Relevance Theory (Sperber & Wilson, 1986), posits that relevance alone is sufficient to explain human communication. Relevance theorists discard the maxim of truthfulness, holding that any tendency to say true things is an epiphenomenon deriving from relevance (Wilson & Sperber, 2002b).

A key piece of evidence in favor of this perspective is “loose talk”: the fact that people regularly produce approximate or even literally false statements—comments like “The lecture starts at 5:00pm” or “Holland is flat”—which are accepted as “true enough” (Lewis, 1979) for conversational purposes. Empirical evidence shows that manipulating the situational context and exact question asked can yield highly variable rates of loose talk (Gibbs Jr & Bryant, 2008; van der Henst et al., 2002; Mühlenbernd & Solt, 2022), undermining the idea that truthfulness is a universal law of cooperative communication. Relevance theorists instead propose that speakers choose utterances to maximize “positive cognitive effects,” described as “a worthwhile difference to the individual’s representation of the world” (Wilson & Sperber, 2002a). However, it has proven difficult to formalize these effects in purely cognitive terms, resulting in criticism that the theory is fundamentally under-determined (Levinson, 1989; Sperber & Wilson, 1987).

How, then, might we quantify a “worthwhile difference to the individual’s representation of the world”? We argue that worthwhile differences are best formalized in terms of decision making outcomes. We propose that mutual world knowledge (Gibbs Jr, 1987; Sanford & Garrod, 1981; Schank & Abelson, 1977)—most importantly, an understanding of conversational partners’ real-world goals and affordances—is integral to relevance. This is not theoretically controversial.

Belief-oriented theorists acknowledge that real-world circumstances ultimately drive relevance (Roberts, 2012) and even manipulate them to demonstrate contextual acceptance of loose talk (e.g., a generic query about the time, versus asking to set a watch; van der Henst et al., 2002). Similar real-world knowledge is required to understand examples used in the literature, from Grice’s description of a man stranded on a highway (Grice, 1975) to norms around lecture attendance (Wilson & Sperber, 2002b). Yet belief-oriented *models* are circumscribed to the information exchange within discourse and do not incorporate this real-world context. In the next section, we consider approaches that instead derive relevance from explicit models of a decision problem.

Relevance to a real-world decision problem

While traditional linguistics focuses on discourse itself, experimental semiotics (Galantucci & Garrod, 2011; Lazaridou & Baroni, 2020), classic AI research (Allen & Perrault, 1980; Cohen & Levesque, 1988; Litman & Allen, 1987, 1990), and game-theoretic pragmatics (Benz et al., 2005; Franke, 2009; P. Parikh, 2001) situate the communicative exchange within a larger context: the agents are assumed to have a set of real-world goals. Communication then serves as a means to these ends, allowing agents to act through others.

This instrumental view of communication is implicit in experimental semiotics (Galantucci & Garrod, 2011) and emergent language research (Lazaridou & Baroni, 2020). Studies in these paradigms typically place human or artificial agents in signaling games (Skyrms, 2010): tasks with common (Bard et al., 2020; Galantucci, 2005; Kang et al., 2020; Lazaridou et al., 2017; O’Connor, 2014; Steels, 2003; Vogel et al., 2013, *inter alia*) or mixed (Cao et al., 2018; Jaques et al., 2019) interests, which afford communication over a channel with no *a priori* semantics. The agents learn to communicate in order to maximize task rewards, and the resulting communication protocols are analyzed for theoretically important properties (Hockett, 1960) such as compositionality (e.g., Franke, 2016; Steinert-Threlkeld, 2020).

Similarly, a long line of mainsteam AI research assumes speakers possess a set of real-world goals and communicate in order to fulfill them (Gmytrasiewicz & Doshi, 2005; Gmytrasiewicz & Durfee, 2001; Tambe, 1997). Task-oriented dialogue systems are the most

prominent example: these systems embed conversations within a planning module that reasons about external goals and available actions when interpreting or producing speech acts (Allen, 1983; Allen & Perrault, 1980; Cohen & Levesque, 1988; Cohen & Perrault, 1979; Perrault et al., 1978; Seneff & Polifroni, 2000; Young et al., 2013). Unfortunately, these systems’ strength is also their weakness: committing to a task-specific decision problem restricts their language understanding to that domain. Thus, while linguistic principles have been employed in AI research (Andreas & Klein, 2016; Dale & Reiter, 1995; Fried, Andreas, et al., 2018; Fried et al., 2021; Fried, Hu, et al., 2018; Golland et al., 2010; Monroe & Potts, 2015; Nie et al., 2020; Shen et al., 2019; Sumers, Ho, et al., 2021; Wang et al., 2016), these applications have not themselves been used to drive general theories of speech acts.

Unlike AI, game-theoretic pragmatics uses this instrumental view of communication to explain actual human discourse (P. Parikh, 2001). This leads naturally to *decision-theoretic utility* as a measure of relevance: utterances are relevant if they improve the expected utility of the listener’s real-world actions (Benz, 2006; Benz & Van Rooij, 2007; P. Parikh, 1991, 1992; R. Parikh, 1994). Decision-theoretic relevance offers two advantages over the set-theoretic “Question Under Discussion” approach (Roberts, 2012). First, it can be seen as deriving the QUD from the real-world decision context (Benz & Jasinskaja, 2017; Litman & Allen, 1987; van Rooij, 2003), formalizing the idea that real-world “domain goals” lie at the root of “discourse goals” (Roberts, 2012).³ Second, the decision-theoretic formulation assigns each utterance a scalar preference. It is therefore strictly more expressive than the set-theoretic one, which expresses a binary preference over partitions (see Appendix A for a formal presentation of the QUD framework and its relationship to our proposed model).

To date, however, decision-theoretic relevance has been used primarily in the context of question asking (van Rooij, 2003) and answering (Benz, 2006, 2011; Benz & Van Rooij, 2007). We

³ Roberts noted that “we usually have goals in the real world, things we want to achieve quite apart from inquiry, *domain goals*. And our domain goals, in the form of deontic priorities, generally direct the type of inquiry which we conduct in conversation, the way we approach the question of how things are. We are, naturally, most likely to inquire first about those matters that directly concern the achievement of our domain goals” (Roberts, 2012, p. 7, emphasis in original).

instead instantiate this measure of relevance as a utility function in the Rational Speech Act framework (Frank & Goodman, 2012; Goodman & Frank, 2016). This casts decision-theoretic utility as a general objective in human communication and allows us to empirically determine its relationship with the maxim of truthfulness.⁴ This decision-theoretic objective grounds speech acts into real-world behaviors, allowing belief- and action-based objectives to co-exist. In the next section, we detail this combined model.

A Framework to Reconcile Truthfulness and Decision-theoretic Relevance

Theorists from Grice (1975) onwards have recognized that human communication is guided by principles of truthfulness and relevance (but see Sperber & Wilson, 1986, 1987; Wilson & Sperber, 2002b), yet it has been challenging to incorporate both maxims in a sufficiently flexible formal model. Our approach builds on the Rational Speech Act (RSA) framework (Frank & Goodman, 2012; Goodman & Frank, 2016). We begin with the canonical RSA model optimizing for truthfulness: it proposes speakers choose informative utterances that yield true beliefs. We then extend RSA to account for actions by reformulating the listener as a rational actor who forms an action policy conditioned on their beliefs (Savage, 1954). Finally, we define a *combined* speaker model which chooses utterances that balance two independent utilities: belief-oriented *truthfulness*, which reflects the accuracy of the listener’s resulting beliefs, and action-oriented *relevance*, which reflects the decision-theoretic utility of the listener’s resulting actions (Benz, 2006). See Fig. 1C for a schematic of our model.

The Rational Speech Act framework

RSA (Frank & Goodman, 2012; Goodman & Frank, 2016) formalizes cooperative communication as recursive Bayesian inference. RSA models follow a standard structure, assuming that the lexical meaning of words are known to both speaker and listener. The pragmatic speaker is assumed to be cooperative and knowledgeable, and to choose utterances u rationally to induce beliefs about the true world state w . Upon hearing an utterance, a pragmatic listener can then invert a model of the speaker to make stronger inferences about the state of the

⁴ Following classical belief-oriented models, the Optimal Answer model (Benz, 2006) assumes the speaker is truthful.

world w based on their choice of utterance relative to alternatives.

Formally, speakers have access to some fixed set of utterances. They choose one proportional to a utility function $U(u, w)$, where β_S is a soft-max parameter controlling speaker optimality:

$$P_S(u | w) \propto \exp\{ \beta_S \cdot U(u, w) \}. \quad (1)$$

The basic RSA speaker utility function emphasizes truthfulness: speakers choose utterances to maximize the probability the listener assigns to the true world state. Formally, the utility of an utterance is defined as the literal listener’s information gain about the true world state w after hearing the utterance:

$$U(u | w) = \log P_{L_0}(w | u). \quad (2)$$

Literal listeners are typically assumed to begin with a uniform prior over possible world states. L_0 then denotes their posterior beliefs after hearing the utterance. This requires the speaker to reason about the literal listener’s expected beliefs after hearing the utterance:

$$P_{L_0}(w | u) \propto \delta_{\llbracket u \rrbracket(w)} P(w), \quad (3)$$

where $\delta_{\llbracket u \rrbracket(w)}$ represents the meaning of u , evaluating to one when utterance u is true of w and zero otherwise. L_0 is referred to as a *literal* listener because it interprets utterances strictly according to their lexical meanings. To formalize Gricean pragmatics, RSA then defines a *pragmatic* listener, L_1 . This listener recursively embeds a speaker model (which in turn embeds a literal listener, L_0):

$$P_{L_1}(w | u) \propto P_S(u | w)P(w) \quad (4)$$

Recursively reasoning about a speaker allows the listener to derive inferences beyond the literal semantics of an utterance. Much of the existing work within RSA studies pragmatic inference by modeling these L_1 listeners. Our work, however, focuses on the speaker: we ask what their objective function ought to be. Crucially, because a L_1 pragmatic listener embeds the speaker model, changing the speaker can have drastic effects on the listener’s inference—an effect we demonstrate after extending this model to a decision-theoretic framework.

Truthfulness as epistemic utility

The original RSA belief objective (Eq. 2) imposes a *constraint* that rules out false utterances, since a literal listener given a false utterance would ascribe zero probability to the true world. To allow the possibility of *loose talk* (van der Henst et al., 2002; Wilson & Sperber, 2002b), we replace this absolute interpretation of truthfulness with a scalar utility resembling the penalty on false utterances suggested by Franke (2009):

$$U_{\text{Truthfulness}}(u | w) = \begin{cases} 1 & \text{if } \delta_{\llbracket u \rrbracket}(w) = 1 \\ -1 & \text{if } \delta_{\llbracket u \rrbracket}(w) = 0 \end{cases} \quad (5)$$

Eq. 5 sets the epistemic utility of true utterances to 1 and false ones to -1. The speaker’s soft-max optimality then controls their degree of truthfulness: when $\beta_S \approx 1$, this models a preference for true utterances (Abeler et al., 2019; Franke, 2009); as $\beta_S \rightarrow \infty$, this recovers a more typical RSA constraint to true utterances⁵

Relevance as decision-theoretic utility

To quantify the relevance of an utterance, we *ground* it into a decision problem. We formalize the decision problem by assuming the listener is a noisy-rational agent choosing from a set of possible *actions* \mathcal{A} . At a given point in time, a subset of those actions are available to the listener, which we refer to as an *decision problem* $A \subseteq \mathcal{A}$ (van Rooij, 2003). The utility of each action is defined by a *reward function* (Sutton & Barto, 2018), where the scalar reward value for an action is defined by the world state: $R : \mathcal{A} \times W \rightarrow \mathbb{R}$. Utterances inform the listener about the world state, and thus the payoffs associated with actions. Formally, the listener conditions their beliefs about the world state on the utterance (Eq. 3), then marginalizes over worlds to estimate the reward for taking an action a :

$$R_L(a, u) = \sum_{w \in W} R(a, w) P_L(w | u). \quad (6)$$

R_L represents the listener’s posterior beliefs about their decision problem: it specifies the listener’s expected reward for action a after hearing utterance u . We model the listener’s decision

⁵ The exact scalar values used here do not affect qualitative model predictions. We used symmetric +1/-1 values for simplicity and interpretability, and return to this choice in the General Discussion.

policy π_L as a softmax (Savage, 1954) over these beliefs. The listener chooses from actions A according to their expected utility:

$$\pi_L(a \mid u, A) \propto \exp\{ \beta_L \cdot R_L(a, u) \}, \quad (7)$$

where β_L is the listener’s softmax optimality.

Utterances are then *relevant* if they induce beliefs that improve the listener’s decision making. Formally, the relevance of an utterance is defined as the expected utility of the listener’s decision policy after hearing it:

$$U_{\text{Relevance}}(u \mid w, A) = \sum_{a \in A} \pi_L(a \mid u, A) R(a, w). \quad (8)$$

This formulation unifies and generalizes prior work from game-theoretic pragmatics and RSA. It generalizes the game-theoretic Optimal Answer model of relevance (Benz, 2006, 2011; Benz & Stevens, 2018; Benz & Van Rooij, 2007), which can be recovered as the special case when the listener acts optimally ($\beta_L \rightarrow \infty$). It also generalizes previous action-oriented models in the RSA framework (Qing & Franke, 2015; Smith et al., 2013), which are the special case where the reward function is the classic Lewis (1969) payoff structure⁶

Formulating the listener as a rational actor provides a principled link from the speaker’s utterances to the listener’s behaviors (Fig. 1C). The speaker’s utterance first affects the listener’s beliefs about the world (Eq. 3). These beliefs determine the utility they ascribe to different actions (Eq. 6); the listener then chooses actions they believe are high reward (Eq. 7). Cooperative speakers choose utterances that maximize the true rewards of these actions (Eq. 8). Notably, this definition of relevance requires that the speaker knows the listener’s decision problem (i.e., has access to the set of possible actions A). We return to this assumption in the General Discussion and consider extensions including speaker uncertainty over the decision problem.

⁶ Eq. 8 reflects the expected utility of the listener’s decision policy after hearing the utterance, rather than the *change* in expected utility (van Rooij, 2003). However, due to the speaker’s softmax decision policy (Eq. 1) these formulations are equivalent: subtracting a constant does not affect the speaker’s choice of utterance.

Reconciling Truthfulness and Relevance

The formalisms above disentangle listeners’ *beliefs* about the world, $P_L(w | u)$ and their subsequent *actions* $\pi_L(a | u, A)$ while preserving a principled link between the two. We then propose a *combined* speaker model which ascribes utility to both beliefs and actions. Truthfulness is quantified as epistemic accuracy (Eq. 5) and relevance as decision-theoretic utility (Eq. 8). The speaker’s utility function is a convex combination of the two, plus a cost term $C(u)$:

$$U_{\text{Combined}}(u | w, A) = \lambda \cdot U_{\text{Relevance}} + (1 - \lambda) \cdot U_{\text{Truthfulness}} + C(u). \quad (9)$$

The cost term is a standard component of RSA (Goodman & Frank, 2016) allowing for variable production or processing effort. We assume uniform costs over utterances unless otherwise noted.

The λ parameter has an intuitive interpretation: it determines the relative weight placed on truthfulness and decision-theoretic objectives. When $\lambda \rightarrow 1$, speakers choose utterances solely to maximize the expected rewards from the listener’s behavior. Such a speaker will readily produce false utterances to induce desirable behaviors. When $\lambda \rightarrow 0$, we recover a purely informative speaker that chooses utterances solely based on their epistemic value. Intermediate values of λ will cause the speaker to blend truthfulness and relevance, choosing utterances that are both truthful and likely to yield good decisions. We next demonstrate how this framework explains puzzles from the literature.

Explaining Phenomena via Decision-Theoretic Utility

A satisfactory account of the interplay between truthfulness and relevance must explain at least three distinct phenomena. First, following Grice, assumptions of relevance should allow listeners to use real-world context to enrich the literal content of an utterance (Grice, 1975). Second, relevance should determine context-dependent standards of truthfulness. This means that under certain circumstances, incorporating relevance should have the opposite effect and instead relax the literal content of an utterance (Wilson & Sperber, 2002b). Finally, the framework must account for “loose talk”: it should capture when and why a speaker might produce a false utterance that is intended to be taken literally (van der Henst et al., 2002; Wilson & Sperber, 2002b). In the following sections, we use a series of classic examples from the literature to

Table 1

Formalizing relevance from Grice (1957).

Garage State w		None	Closed	Open
Prior Probability $P(w)$.8	.1	.1
Reward $R(a, w)$	Leave car	-1	-1	1
	Stay at car	-.5	-.5	-.5

illustrate how our synthesis of epistemic and decision-theoretic utility satisfies these desiderata.

Decision-theoretic relevance can strengthen pragmatic inferences

Our first example shows how formalizing decision-theoretic relevance can strengthen pragmatic inference. To motivate the maxim of relevance, Grice (1975) described the following real-world scenario.⁷ A is standing by an immobilized car; B approaches, and the following exchange occurs:

A (Listener): I am out of petrol.

B (Speaker): There is a garage round the corner.

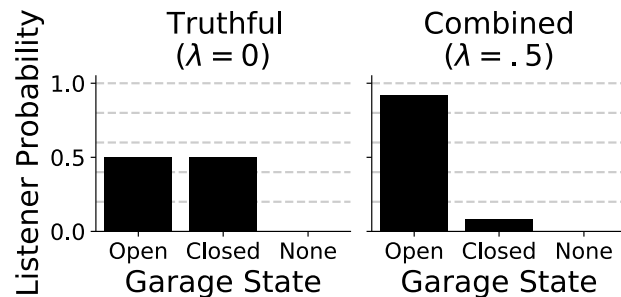
Grice justifies this brevity with the maxim of relevance. He suggests that B’s statement *implies* the garage is open. Note that the statement literally communicates only the garage’s existence: it is equally consistent with the garage being open or closed. Yet intuitively, we expect that the speaker is trying to help the listener. If the speaker believed the garage was closed, it would not help the listener, and so they would not mention its existence. Thus, a pragmatic listener—given such a vague utterance—should infer that the garage is likely to be open. We now show how decision-theoretic relevance formalizes this intuition.

We first define the world states w and payoff matrix $R(a, w)$ shown in Table 1. We assume that *a priori* it is relatively unlikely that a garage exists around the corner, but given its existence, it is equally likely to be open or closed. We then assume A has two available actions: to stay with their car, or leave it in search of gas. We assign payoffs to each possible world-action

⁷ See Benz (2006) for a game-theoretic analysis and Thomason (1990) for a plan-based analysis of this example.

Figure 2

Relevance can strengthen pragmatic inference.



Note. After hearing the utterance “There’s a garage round the corner,” different assumptions about the speaker’s objectives yield different posteriors over the world state. Left: a pragmatic listener assuming a purely truthful speaker draws no additional inference beyond the literal interpretation, contradicting human intuition. Right: assuming a decision-theoretic speaker yields the intuitive inference that the garage is open. This asymmetry is driven by the assumption that the speaker mentions the garage because they believe it can resolve the listener’s current predicament. See Fig. [B1](#) for a sensitivity analysis exploring different parameter settings.

pair. A successful search for gas is the most desirable outcome (reward of 1); staying with the car is undesirable (reward of -.5), but better than an unsuccessful search for gas (which would leave the car abandoned; reward of -1). A listener with no information thus prefers to stay with their car, as a successful search for gas is unlikely.

In order to model the interaction, we assume the speaker could produce four distinct utterances u , each corresponding to a possible knowledge state: one uninformative (“Sorry”); one vague (“There is a garage round the corner”); and two precise (“...and it is open/closed”). These correspond to the speaker’s possible knowledge states. To compare the effects of pragmatic inference with and without decision-theoretic utility, we define two speakers: a “Truth-only” speaker and a “Combined” speaker. We set the “Truth-only” $\lambda = 0$, the “Combined” $\lambda = .5$, and $\beta_S = \beta_L = 10$ for both.⁸

To explore the effects of the speaker’s objective on pragmatic inference, we define a pair of

⁸ Across all examples, we choose parameter settings that yield intuitive effect sizes. However, the qualitative effects of interest hold across a range of parameter space; see Appendix [B](#) for sensitivity analyses.

Table 2

Formalizing relevance from Wilson and Sperber (2002a).

Lecture Start w	5:00	5:05
Prior Probability $P(w)$.5	.5
Reward $R(a, w)$	Arrive 5:00	.9
	Arrive 5:05	1

pragmatic listeners (Eq. 4) each embedding one of these speakers. Finally, we analyze the listeners’ posteriors over the world state w after hearing the vague utterance “There is a garage round the corner.” Fig. 2 shows the effect of the different speaker models on the listener’s posterior. If the listener assumes the speaker is purely guided by epistemic truthfulness, there is no reason to favor either the open or closed states. However, if the listener assumes the speaker is trying to provide information to resolve their underlying predicament, they can infer the garage is likely open.

Decision-theoretic relevance can relax pragmatic inferences

Our previous example demonstrates that decision-theoretic relevance can strengthen pragmatic inference. However, proponents of Relevance Theory (Sperber & Wilson, 1986; Wilson & Sperber, 2002b) have noted that expectations of relevance can also have the *opposite* effect: listeners may take a precise statement and loosen its meaning. For example, a statement such as “The lecture starts at five o’clock” is generally taken to mean “starts at five o’clock *or shortly after*” (Wilson & Sperber, 2002a, p. 596, emphasis ours).⁹ We again formalize the listener’s decision context and show how expectations of decision-theoretic relevance can drive such loosening of meaning.

⁹ Wilson and Sperber (2002a) use this example as part of a larger point that *start* and *end* times yield different interpretations. We address this broader point in our following example, so for simplicity we analyze only the start time; however, the same logic applies to the end time. Wilson and Sperber (2002a) also consider more complex utterances and variable costs, but these are not needed to derive the basic effects of interest here. Finally, see P. Parikh (1992) for a game-theoretic analysis based on this example.

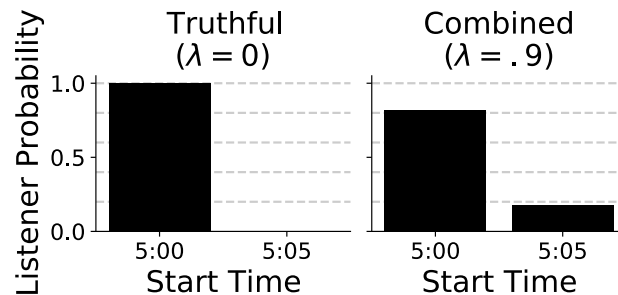
As noted by Wilson and Sperber (2002a), a key insight is that the costs of arriving early versus late are asymmetric: arriving a few minutes early is preferable to arriving a few minutes late. Again, we formalize this with a payoff matrix (shown in Table 2): arriving whenever the lecture starts is optimal (with a reward of 1); arriving early is nearly as good (reward of .9) while arriving late is costly (reward of -1). We consider a pair of utterances: “The lecture starts at 5:00pm” or “The lecture starts at 5:05pm.” As before, we define a pair of speaker models—a “Truth-only” speaker ($\lambda = 0$) and a “Combined” speaker concerned primarily with relevance ($\lambda = .9$), with $\beta_S = \beta_L = 5$ for both. We assume a “precise” literal semantics of number, such that an utterance is true only when it exactly matches the true value.¹⁰ Again, we consider a pair of pragmatic listeners (Eq. 4) each embedding one each of these speakers, and analyze their beliefs after hearing the utterance “The lecture starts at 5:00pm.”

Fig. 3 shows the resulting pragmatic listener posteriors over w , and Fig. B2 gives a parameter sensitivity analysis. In this case, because the speaker’s utterance is literally precise (it specifies an exact world state), a pragmatic listener embedding a “Truth-only” speaker assumes the literal interpretation is correct and the lecture is certain to start at 5:00pm. However, expectations of decision-theoretic relevance can *loosen* the literal meaning. In particular, because arriving early is nearly as good as arriving precisely on time, a speaker believing the lecture is likely to start at 5:05pm may still say it starts at 5:00pm. A pragmatic listener embedding such a speaker derives the colloquial interpretation “starts at 5:00pm or shortly after.” Formalizing the asymmetric decision-theoretic utility associated with early versus late arrival explains why such loose language may be “true enough” (Lewis, 1979) in such a context.

¹⁰ This assumption oversimplifies a vast literature grappling with the complexity of number semantics. We do not intend this as a standalone account; for example, earlier RSA models (Kao, Wu, et al., 2014) handle numerical imprecision by introducing uncertainty over whether one’s partner uses a ‘precise’ or ‘fuzzy’ literal semantics for number and derives rounded interpretations as a cost implicature, consistent with Krifka (2007). This account clearly distinguishes between mere imprecision (where rounding is still literally true under a “fuzzy” semantics) and outright lying (where giving a time that is hours off is true under no number semantics). Because we are interested in the *context-sensitivity* of imprecision with respect to the decision problem, our analysis goes through under a more sophisticated treatment.

Figure 3

Relevance can loosen literal meanings.



Note. Pragmatic inference after hearing “The lecture starts at 5:00pm” using different speaker models. Left: pragmatic inference assuming a purely truthful speaker results in certainty that the lecture will start at 5:00pm. Right: pragmatic inference assuming a “Combined” speaker yields the intuitive inference that the lecture may actually start at 5:05pm. This is because arriving early is a relatively innocuous outcome.

Relevance can explain loose talk

The previous examples show that a pragmatic listener embedding a “Combined” speaker model can explain intuitive patterns of inference. However, the most direct test is explaining *speaker* data: can our framework account for empirically-observed instances of loose talk?

An elegant experiment by van der Henst et al. (2002) provides particularly interesting data. Individuals on the street were asked the time, and responses were analyzed to determine what fraction of responses were rounded (a multiple of 5, such as 12:00 or 12:05). If speakers were following a “Truth-only” objective (under precise number semantics), exactly 20% of all responses should be rounded: speakers should only give a rounded time when it is literally true. However, van der Henst et al. find this is emphatically not the case: instead, the prevalence of rounding varies significantly depending on how the question is asked.

In particular, their Experiment 2 shows how manipulating the decision context systematically affects rounding behavior. Control participants were simply asked the time (“Do you have the time please?”), while Experimental participants were asked the time for the purpose of setting a watch (“My watch is going wrong. Do you have the time please?”). Participants asked the generic question almost always rounded (95.5%), while those asked the watch-setting

Table 3

Formalizing Relevance from van der Henst et al. (2002).

Utterance u		:00	:01	:02	:03	:04	:05
Relevance $U_R(u w, A)$	Control	1	1	1	-1	-1	-1
	Watch	.5	.75	1	.75	.5	.25
Truth $U_T(u w)$		-1	-1	1	-1	-1	-1
Cost $C(u)$.5	1	1	1	1	.5

Note. This table shows example utilities given a true time of 2 minutes past the hour (:02). We formalize the arguments advanced by van der Henst et al. by quantifying the decision-theoretic utility of utterances (Eq. 8), under the “Control” and “Watch” conditions respectively.

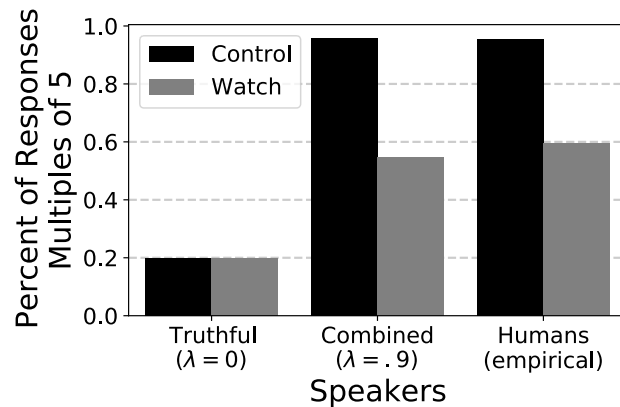
question did so significantly less often (59.5%). Why might this be the case?

The authors suggest that when the inquirer’s decision problem is not explicit (as in the Control condition), speakers fall back to their general world knowledge to determine relevance. Since most activities (“appointments, TV programs, or university courses”) are scheduled to begin at a multiple of five, a person asking the time for unspecified purposes “will not be worse off” given a rounded time (van der Henst et al., 2002, p. 459). We formalize this intuition by defining a “Control” decision context, A_{Control} , with a positive payoff on the listener’s policy when told a time that lies within 5 minutes of the true time ($U_{\text{Relevance}} = 1$), and a negative payoff otherwise (-1). These utilities could be derived from a real-world decision problem that—for example—required the listener to arrive within a five minute window of a specified appointment time. In contrast, when setting one’s watch, knowing the time precisely *is* useful. In the A_{Watch} context, we assume the decision-theoretic utility declines linearly as the answer becomes less accurate. Finally, van der Henst et al. (2002) suggest that rounded times require less processing effort; we formalize this by assigning them a lower cost $C(u)$ than unrounded times. An example payoff matrix is shown in Table 3 under the assumption that the true time is :02.

We then compare the distribution over utterances from two speaker models to that produced by human speakers. A purely truthful speaker always produces the precise time

Figure 4

Decision-theoretic relevance can explain contextual acceptance of loose talk.



Note. Purely truthful speakers will always give the precise time, resulting in 20% of their responses being a multiple of five. A “Combined” speaker primarily optimizing for decision-theoretic relevance ($\lambda = .9$) will nearly always round the time under normal circumstances. However, when asked for the purpose of setting the listener’s watch (where a precise time has value), the percentage of rounding drops substantially. This pattern provides a close fit to empirical human data from van der Henst et al. (2002).

(yielding 20% of utterances which are multiples of 5), while a Combined speaker with $\lambda = .9, \beta_S = \beta_L = 10$ produces a human-like distribution: it chooses a rounded utterance 96% of the time under “Control” condition and 55% of the time under the “Watch” condition. Fig. 4 shows the results, and Fig. B3 provides a parameter sensitivity analysis.

Summary

These results demonstrate that our framework can explain a number of seemingly contradictory results in the literature. Expanding our formal model of communication to incorporate the listener’s decision-making process allows this external context to determine appropriate standards of truthfulness. This, in turn, leads to context-dependent pragmatic strengthening or weakening of speakers’ literal meanings; and explains the variable acceptability of loose talk. In addition to explaining these outstanding theoretical puzzles, our framework makes a number of unique predictions about speaker’s behaviors when the two objectives diverge. In the next section, we introduce a novel extension to classic signaling games which allows us to

directly test these predictions.

Signaling Bandits: decoupling truthfulness and relevance

To determine how speakers weigh truthfulness and relevance, we need a controlled setting that decouples the epistemic and decision-theoretic utility associated with an utterance. Put simply, we need to create a diverse set of utterances: some that are true and relevant, some that are *false* and relevant, some that are true and *irrelevant*, and so on. We can then ask speakers to choose or endorse utterances with varying utilities to determine whether truthfulness or relevance (or some combination of the two) best explains their preferences.

In this section, we define a new signaling game (Skyrms, 2010) which satisfies this desideratum. We first review the structure of classic Lewis signaling games (Lewis, 1969), showing that they are not sufficient: epistemic and decision-theoretic utility are synonymous in these settings. We then describe contextual bandits, a decision setting studied in reinforcement learning (Lattimore & Szepesvari, 2020; Sutton & Barto, 2018). Finally, we combine Lewis games and contextual bandits to produce a new class of games, *signaling bandits*. Signaling bandits decouple the world state from the decision problem and fix the signal semantics to provide information about the world state. This allows us to independently vary the truthfulness (epistemic utility) and relevance (decision-theoretic utility) of utterances in order to test different theories.

Lewis Signaling Games

Lewis signaling games (Lewis, 1969) are two-player collaborative settings with a speaker and a listener (Fig. 5A). Following the notation introduced previously, such games are defined by a world state w , a set of actions available to the listener, $A \subseteq \mathcal{A}$, and a set of utterances available to the speaker, \mathcal{U} . There is one action $a^* \in A$ with a positive reward; other actions have zero reward. The world state w implies the correct action a^* . The speaker knows w but the listener does not. During gameplay, the speaker chooses an utterance $u \in \mathcal{U}$ and sends it to the listener. The listener updates their beliefs, $P_L(w | u)$, and uses the posterior to choose an action, $\pi_L(a | u, A)$.

Lewis signaling games formalize the coordination problem underlying communication (Frank & Goodman, 2012; Krahmer & Van Deemter, 2012). However, the interplay of beliefs,

actions, and rewards is highly constrained. The state of the world w is synonymous with the correct action a^* , and players are indifferent over other actions. This means that epistemic and decision-theoretic utility are perfectly correlated. As a result, it is not possible to discriminate the speaker objectives defined above (Eq. 5, 8, or 9): all predict the same distribution over utterances (Sumers, Hawkins, Ho, & Griffiths, 2021)¹¹. For a richer decision-making setting, we turn to contextual bandits.

Contextual Bandits

Contextual bandits are an extension to the classic *multi-armed bandit* problem. Multi-armed bandits are single-player sequential games. In each round, the player takes an action and receives a scalar reward (Lattimore & Szepesvari, 2020; Sutton & Barto, 2018). Players seek to maximize their rewards, but are initially ignorant of the reward structure. Over multiple rounds, they must balance exploration (choosing a new action to learn its reward) with exploitation (choosing the most valuable known action). Contextual bandits extend this to a setting where actions are characterized by features, and rewards are defined with respect to these features.

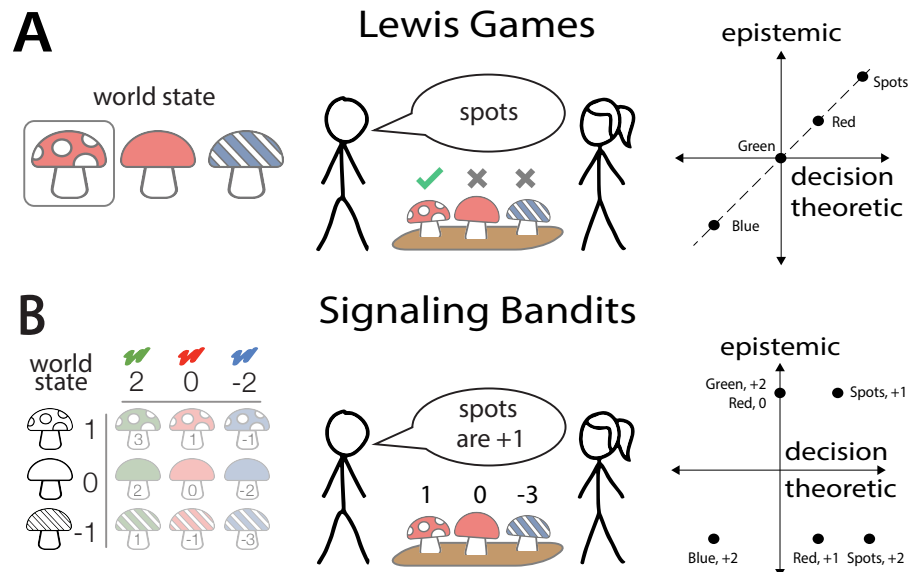
For example, imagine learning to forage for mushrooms. Different varieties might be more or less tasty: green species might tend be delicious, while blue tend to be bitter. After eating a mushroom, associating payoffs with the color of the mushroom (a feature) rather than the mushroom itself (a specific action) allows knowledge to transfer to new settings (the next mushroom patch). Thus, unlike classic Lewis games, the payoff structure is correlated across contexts. The player must learn and exploit this correlation in order to choose optimal actions.

Formally, a function ϕ associates features with each action: $\phi : A \rightarrow \mathbb{R}^K$. Rewards are then defined as a function of these features: $R : \phi(a) \rightarrow \mathbb{R}$. Thus, rather than learn about the reward of a specific action, players can learn about the reward of a *feature* which applies to many actions. Contextual bandits have been studied extensively in reinforcement learning (Abbasi-Yadkori et al., 2011; Chu et al., 2011; Li et al., 2010; Riquelme et al., 2018) and to a lesser degree for emergent communication (Donaldson et al., 2007). Here, we use them to study

¹¹ But see Qing and Franke (2015) for evidence in favor of action-oriented speakers in such settings.

Figure 5

Comparing Lewis signaling games to signaling bandits.



Note. (A) In classic Lewis signaling games (Frank & Goodman, 2012; Lewis, 1969), the world state is defined as the correct action (left). Speakers then use language to *refer* to this action (center). Knowledge of the world state is synonymous with knowledge of the correct action. Epistemic utility is thus perfectly correlated with decision-theoretic utility (right). (B) Signaling bandits defines an abstract world state in the form of feature-value pairings, which determine scalar payoffs associated with each action (left). Speakers use language to *inform* the listener about this world state (center). This breaks the correlation between epistemic and decision-theoretic utility: utterances may be false but useful, or true but not useful (right). Note that in this context, the utterance that maximizes decision-theoretic utility is false (“Spots are +2”).

human communication employing signals with fixed semantics. In the next section, we introduce a two-player version of this game.

Signaling Bandits

We combine the communication of Lewis games with the reward structure of contextual bandits to create a new class of games, *signaling bandits* (Fig. 5B). Unlike Lewis games, speakers no longer communicate concrete information (which action is correct). Instead, they communicate abstract information (how much features are worth). We now describe basic gameplay.

As in Lewis games, signaling bandits are two-player games with a speaker and a listener.

Each game is defined by a world state w , a set of all possible actions \mathcal{A} and a set of speaker utterances \mathcal{U} . In each round, the listener faces a decision context $A \subseteq \mathcal{A}$. However, *unlike* Lewis games, there is no single “correct” action. Instead, as in contextual bandits, each action has a scalar utility defined by a reward function which is independent of (and consistent across) contexts. While the reward function may be arbitrarily complex, in this work we use binary features and a linear reward function. Concretely, we assume features are indicator variables over actions:

$$\phi : A \rightarrow \{0, 1\}^K \tag{10}$$

and rewards R are linear over these features, parameterized by w :

$$R(a, w) = w^\top \phi(a). \tag{11}$$

This means the world state w is a vector encoding the reward associated with each feature.

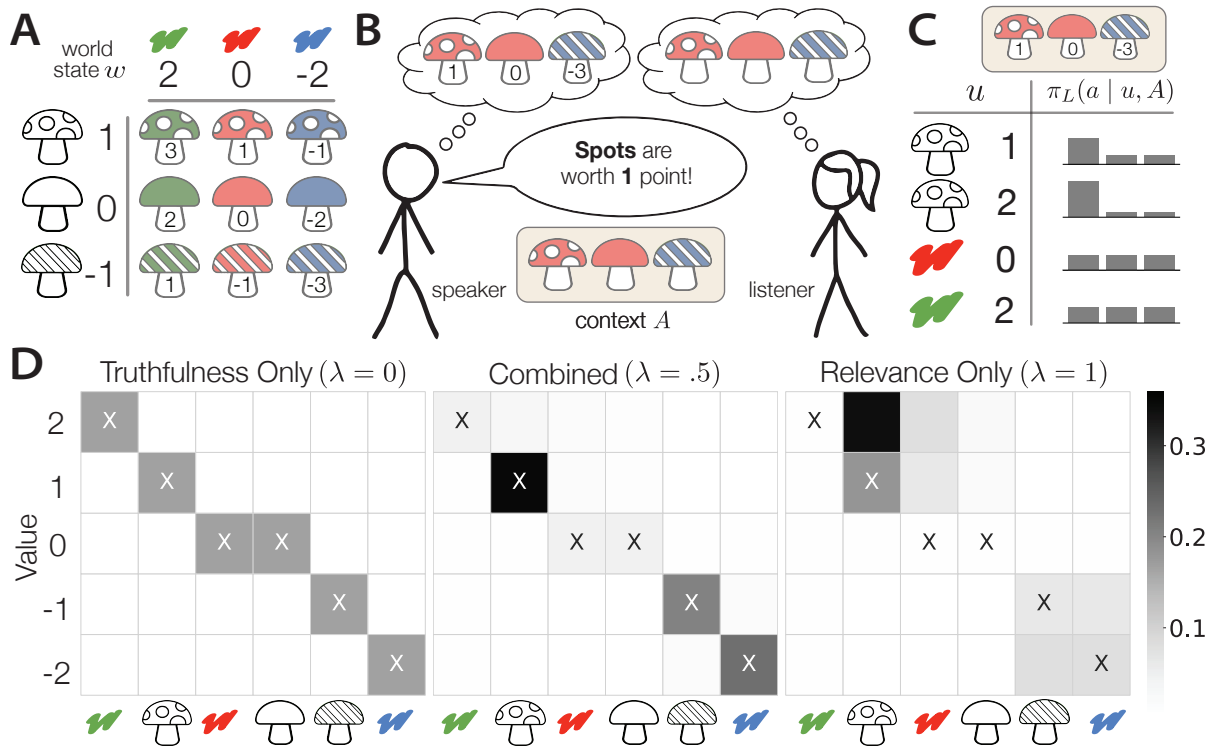
Fig. 6A depicts this visually: w defines the value of individual colors and textures (table margins), which in turn determines the reward for each possible action in \mathcal{A} (table contents). A listener with full world knowledge (every element of w) can calculate the exact rewards of every action and select the optimal action in any context. The value of an individual feature (one element of w) constitutes *partial* knowledge about the world.

The speaker helps the listener by providing such partial knowledge (Fig. 6B). In this work, we fix the semantics of signals: we take \mathcal{U} to be a set of tuples of the form $\langle \mathbf{1}_K, \mathbb{R} \rangle$ which specify a given feature and scalar value. As shown in Fig. 6C, these are messages like $\langle \text{Spots}, 1 \rangle$ or $\langle \text{Red}, 0 \rangle$. Speakers choose utterances and send them to the listener. The listener updates their beliefs according to Eq. 3, ruling out possible worlds where the feature takes on other values. The listener then chooses an action from the context A according to their posterior belief over rewards (Fig. 6C, Eqs. 6 and 7). This decouples the epistemic and decision-theoretic utility associated utterances, such that the two objectives yield different preferences over utterances (Fig. 6D).

Signaling bandits, like contextual bandits, are a class of games spanning a range of complexity. Lewis signaling games, which can be instantiated within signaling bandits (Sumers, Hawkins, Ho, & Griffiths, 2021), lie at the simplest end of this spectrum. More complex settings can incorporate imperative utterances and multiple decision contexts (Sumers et al., 2022). The

Figure 6

Signaling bandits formalities.



Note. Signaling bandits combine Lewis signaling games with contextual multi-armed bandits. (A) The world w is defined by correspondences between features and rewards (table margins), which combine additively to create possible actions A (table contents). In this world, green mushrooms tend to be tasty, while blue ones tend to be bitter. (B) One example context drawn from the world. A knowledgeable, cooperative speaker may produce an utterance before the listener takes an action. (C) Different utterances and their effects on the listener’s policy, $\pi_L(a|u, A)$ for $\beta_L = 1$. In this context, $\langle \text{Spots}, +1 \rangle$ is true and relevant: it makes the listener likely to choose the spotted red mushroom. $\langle \text{Spots}, +2 \rangle$ is false and relevant: exaggerating the value of spots increases the probability that the listener will choose it. Finally, $\langle \text{Green}, +2 \rangle$ and $\langle \text{Red}, 0 \rangle$ are true and irrelevant: they do not affect the listener’s policy. (D) Distribution over all 30 possible utterances induced by different speaker objectives for the decision context shown in B. Features (on the x-axis) are ordered in descending value; X’s on the diagonal mark true utterances. The purely truthful speaker ($\lambda = 0$, left) is insensitive to context and does not prioritize among true utterances, while the pure relevance speaker ($\lambda = 1$, right) readily exaggerates to obtain better actions. Combining the two ($\lambda = .5$, center) prioritizes utterances that are both truthful and relevant.

setting described here is a minimal extension to Lewis games, adding just enough complexity for meaningful differences to emerge between truthfulness and relevance. We describe these differences in more detail below, and return to future work using more complex signaling bandit settings in the General Discussion.

Using signaling bandits to study truthfulness and relevance

Why do signaling bandits—unlike Lewis’ signaling games—create a distinction between truthfulness and relevance? And how can this difference be used to test existing theories of communication? We now examine these questions in detail, highlighting how game dynamics create divergent predictions.

The basic innovation is that a single world state (the margins of the table in Fig. 6A) can be used to construct many decision contexts (any set of the actions from \mathcal{A} , the contents of the table in Fig. 6A). Utterance semantics are then fixed, and *describe* this abstract world state (they provide information about w , i.e., “Green is worth +2”) rather than simply *referring* to a concrete action (c.f. “Green”, Frank & Goodman, 2012). Thus, utterances are true or false regardless of the context: their epistemic utility depends only on the world state w (Eq. 5). However, their relevance is context-dependent: their decision-theoretic utility depends on the specific decision problem A (Eq. 8). This decouples truthfulness and relevance (Fig. 5).

To see this, consider the context and utterances shown in Fig. 6C. The utterance $\langle \text{Spots}, 1 \rangle$ is both true and relevant: the listener’s decision policy skews towards the spotted red mushroom, improving it over a random choice. However, utterances can also be *false* and relevant: for example, the utterance $\langle \text{Spots}, 2 \rangle$ exaggerates the value of spots. This utterance induces false beliefs about the underlying world w (and thus has negative epistemic utility), but yields a high probability of the listener choosing the optimal action (and thus has positive decision-theoretic utility). Finally, utterances may be true and *irrelevant*. It is straightforward to see that $\langle \text{Green}, 2 \rangle$ is not relevant, because the green feature is not present in this context. A more subtle example is the utterance $\langle \text{Red}, 0 \rangle$. Red is the most common feature in this context, and so its value could plausibly be considered important. However, under the assumption of a uniform prior over feature values, learning that a feature is worth 0 does not change its expected utility. As a result, it too is

irrelevant: hearing this utterance does not affect the listener’s policy. In this decision context, both $\langle \text{Green}, 2 \rangle$ and $\langle \text{Red}, 0 \rangle$ reduce the listener’s uncertainty about the world w (positive epistemic utility), but do not affect the listener’s actions (zero decision-theoretic utility).¹²

How does this decoupling help us test competing theories? Fig. 6D illustrates how speaker objectives now induce different preferences over utterances. Each grid represents the 30 possible utterances (6 features \times 5 values), with X’s indicating true utterances: $\langle \text{Green}, 2 \rangle$ is a true utterance, while $\langle \text{Green}, 1 \rangle$ and $\langle \text{Spots}, 2 \rangle$ are not. Shading indicates the distribution over utterances resulting from each objective in the context shown in Fig. 6B. A purely truthful speaker weighs only the epistemic utility of utterances. Thus, it eschews false utterances but is indifferent over true ones, placing a uniform probability over them. At the other extreme, a pure relevance speaker chooses utterances proportional to their decision-theoretic utility, with no regard for truthfulness. Thus it favors exaggerating the “Spots” or “Stripes” features, or ascribing positive utility to the neutral “Red” feature. Combining the two objectives yields an entirely new prediction: a strong emphasis on the $\langle \text{Spots}, 1 \rangle$ utterance, which compromises between truthfulness and decision-theoretic relevance.¹³ These distinctions are not possible in traditional Lewis signaling games, which align the two objectives (Sumers, Hawkins, Ho, & Griffiths, 2021).

In the following sections, we use behavioral experiments to test these theoretical predictions. Our first experiment gives participants access to the full utterance space. We hypothesized that both truthfulness and relevance are important constraints on communication, such that our Combined model would predict response patterns better than either alone. Our second experiment focuses on the phenomenon of “loose talk,” asking participants to endorse *false but relevant* utterances. This affords a strong test of the primacy of these different objectives:

¹² Note that these particular decision-theoretic utilities are a function of the context. To see this, we can consider a context consisting of three spotted mushrooms: one red, one green, and one blue. In this context, both $\langle \text{Spots}, 1 \rangle$ and $\langle \text{Spots}, 2 \rangle$ are irrelevant (because they do not disambiguate between actions), while the true utterance $\langle \text{Green}, 2 \rangle$ is now relevance-maximizing.

¹³ Similar tension between truthfulness and relevance is evident even in real-world information about mushrooms. Textbooks on mycology bias towards truthfulness, providing a comprehensive but academic perspective on fungi (Deacon, 1997). In contrast, practical foraging guides bias towards relevance, dramatically simplifying the underlying biology in favor of useful heuristics to avoid getting sick (Hyman, 2021).

Relevance Theory (Sperber & Wilson, 1986; Wilson & Sperber, 2002b) suggests that participants should always endorse these; truth-based formalisms (Goodman & Frank, 2016; Lewis, 1969) suggest they should never; and our Combined model predicts that endorsement will vary as a function of decision-theoretic utility.

Experiment 1: Is truthfulness or relevance alone sufficient?

Our first experiment asks whether truthfulness or relevance alone can explain participants’ utterance choices. We give speakers access to the full semantic space in the signaling bandits game introduced in the previous section, allowing them to choose from 30 possible utterances. While previous approaches have emphasized either truthfulness *or* relevance, we hypothesized that participants would be sensitive to both, such that their pattern of responses would be best explained by our combined objective (Eq. 9).¹⁴

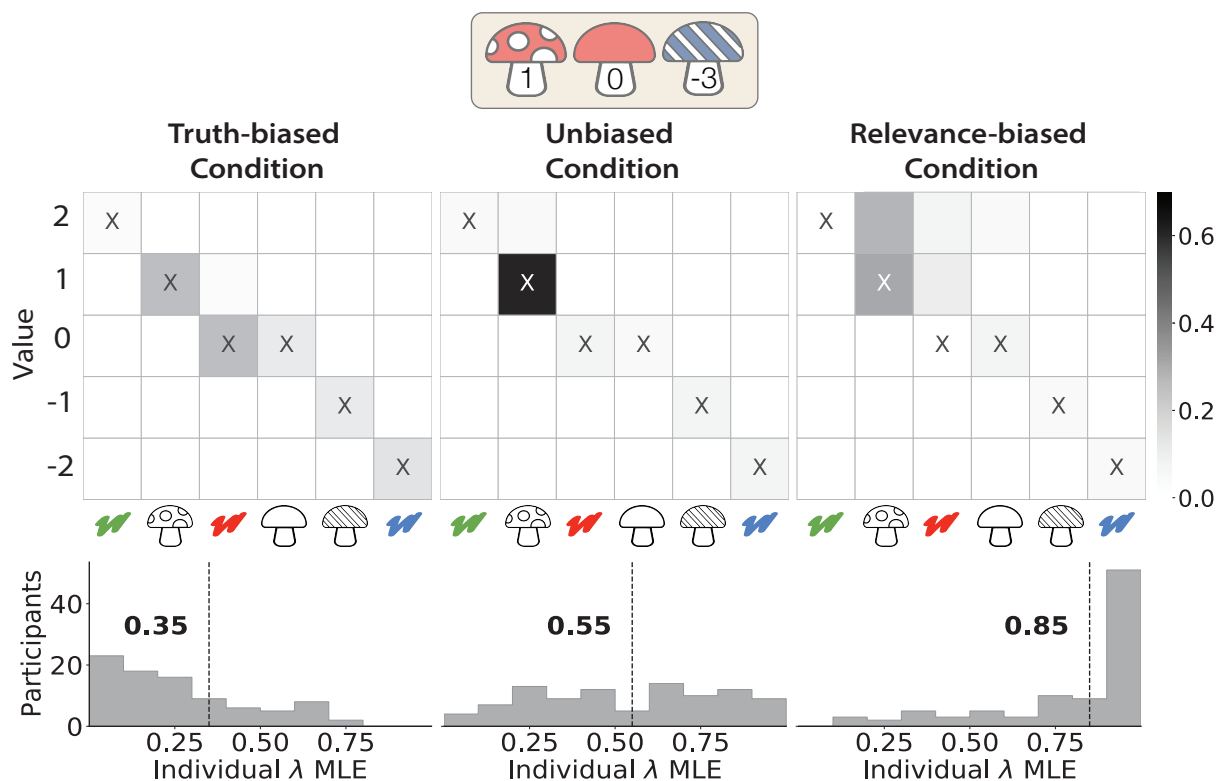
To put the participant in the role of a cooperative and knowledgeable speaker, we used a cover story situating them as a tour guide giving visitors information about local mushroom species. Participants were first trained and tested on the world state (Fig. 6A) which was randomized across participants (Fig. C1). After passing a comprehension check, participants then provided advice to tourists in different decision contexts (Fig. 6B), instantiated as visiting different mushroom patches (Fig. C2).

We used two control conditions and one experimental condition in a fully between-subjects design. Our control conditions manipulated participants’ objectives to test their understanding of epistemic and decision-theoretic utility respectively. Participants in the “Truth-biased” condition were instructed to provide true facts only, testing whether participants understood the truthfulness of utterances. Participants in the “Relevance-biased” condition were instructed to ensure tourists picked good mushrooms (and that lying was allowed), thus testing whether the participants’ model of the listener’s decision-making matched ours (Eq. 7). Finally, the experimental “Unbiased” condition was used to test participants’ default behavior. Participants

¹⁴ This study was approved by the Princeton IRB (protocol #10859). Experiment design and analyses were pre-registered at https://aspredicted.org/SPK_Z7Y. All materials, code, and data are available at <https://github.com/tsumers/relevance>. The experiment can be seen at <https://signaling-bandits.herokuapp.com>.

Figure 7

Results from Experiment 1.



Note. Top: participant responses across conditions for the example context. X's indicate true utterances. Unbiased participants were sensitive to both truthfulness and relevance: they strongly favored the (Spots, 1) utterance, which is both true and relevant. In contrast, Truth-biased participants additionally favored the (Red, 0) utterance (true but not relevant), while Relevance-biased participants chose the (Spots, 2) utterance (false but highly relevant). Bottom: to visualize the distribution of the λ parameter within each condition, we fit the Combined model to individual participants. Histograms show participant-level λ MLEs, while dashed lines and bold text show condition-level MLEs. Participant-level MLEs confirm that virtually all Unbiased participants considered both utilities; instructing participants to follow either biased them towards that theoretical model.

in this condition were given no instructions about their objective. Our key hypothesis was that these Unbiased participants would optimize for *both* truthfulness (epistemic utility) and relevance (decision-theoretic utility), and thus be best explained by the “Combined” model.

Methods

Participants

We recruited 301 participants using Prolific (www.prolific.co). Participants were required to be fluent in English, possess an approval rating of 95%, and be located within the United States, United Kingdom, or Ireland. They were paid \$2, with an additional completion bonus of \$2 if they passed a pre-experiment comprehension check. 16 participants failed this comprehension check and 12 failed attention checks during the experiment, leaving a final sample size of 273. On average, participants spent about 15 minutes on the experiment ($M=15.71$, $SD=6.02$) and earned an hourly wage of \$14.87.

Stimuli

The experiment was designed as a direct implementation of signaling bandits as described above. We thus used the reward structure shown in Fig. 6A (see Fig. C1 for screenshots).

Our experimental trials used decision contexts consisting of 3 distinct actions, $A \in [\mathcal{A}]^3$, for a total of 84 different contexts. We divided these into 3 sets of 28 and randomly assigned participants to one set. On each of these trials, participants were shown a tourist visiting a particular mushroom patch (i.e. a decision context A). They were asked to choose an utterance of the form “<feature> is <value>,” using drop-down menus to select one of six features (Green, Red, Blue, Spotted, Solid, Striped) and one of five values (-2, -1, 0, 1, 2). The feature-value mapping, trial ordering, and menu ordering were randomized (see Appendix C for details).

Procedure

Participants began with an instruction phase, where they were given the cover story about providing advice to tourists. They were first taught the true world state w (Fig. 6A). They were then taught signaling bandits dynamics. Specifically, they were told that tourists always visited a single mushroom patch (consisting of three mushrooms) and chose a single mushroom from it. Tourists knew nothing about the mushrooms, but the participant could produce a single utterance (chosen from the 30 possible feature-value tuples) before the tourist picked one. The tourists’ decision-making process (Eq. 7) was not specified.

Participants in the Truth- and Relevance-biased control conditions were shown an additional page specifying their responsibilities as a tour guide. Truth-biased participants were told their job was “teach tourists facts about mushroom features,” and instructed that “it does not matter what mushrooms they choose.” In contrast, Relevance-biased participants were told their job was to “ensure tourists choose tasty mushrooms,” and that “it does not matter if you tell the truth or not” (see Fig. C3 for screenshots). Finally, in the experimental Unbiased condition, participants were given no instructions about their objective.

After reading the instructions, participants took a comprehension quiz consisting of sixteen multiple choice questions. To ensure participants had learned the world state w , they were required to correctly provide the value of all six individual feature values and three specific actions. To ensure they understood the game dynamics, they were asked seven questions about the experiment itself. Two questions were condition-dependent: Truth- and Relevance-biased participants were asked about their objective, while Unbiased participants were asked neutral questions about the game dynamics. Participants were required to answer all 16 questions correctly, but were given three opportunities to do so and could review the instructions between each attempt. If they failed three times, the experiment ended early.

Participants who passed began the experiment itself, consisting of 28 trials and 8 attention checks (for details, see Appendix C). To avoid memory confounds, participants could view the full world state at any time (Fig. C1).

Results

Analysis of participant behavior shows that our objective manipulation strongly affected participants’ behaviors. Across all contexts, rates of truth-telling varied significantly by condition ($F(2, 270) = 49.40, p < .0001$). Truth-biased participants chose truthful utterances 95% of the time; Unbiased 85%, and Relevance-biased just 67% of the time.

Control conditions biased participants towards their respective theoretical models, confirming that participants understood and could independently optimize epistemic and decision-theoretic utility. Crucially—and as predicted—Unbiased participants jointly optimized truthfulness and relevance, rather than either alone. Fig. 7 shows the empirical distribution of

Table 4*Maximum likelihood estimates in Experiments 1 and 2.*

Experiment	Condition	N	MLE		
			λ	β_S	β_L
1: Free Choice	Truth-biased	87	.35	3	1
	Unbiased	95	.55	3	3
	Relevance-biased	91	.85	4	2
2: Forced Choice	Truth-biased	71	.15	3	1
	Unbiased	78	.75	3	1
	Relevance-biased	79	.90	3	2

utterances chosen by participants for the example context. Qualitative comparison with Fig. 6D highlights several important trends. First, control conditions affected participants’ choice of utterances in this context. For example, Relevance-biased participants readily used false utterances to achieve a desired action: they sent ⟨Spots, +2⟩ as well as ⟨Red, +1⟩ and ⟨Red, +2⟩. This demonstrates that participants understood and could optimize for decision-theoretic utility independent of epistemic utility. Second, Unbiased participants clearly followed a combination of the two objectives: they overwhelmingly favored an utterance that was truthful and relevant, but not necessarily relevance-maximizing: ⟨Spots, +1⟩.

Parameter estimates across conditions

We now analyze the λ parameter, which determines the relative weight of the truthfulness and relevance objectives in Eq. 9. Higher values ($\lambda \approx 1$) indicate that participants’ response patterns were best explained by relevance (decision-theoretic utility), while lower values ($\lambda \approx 0$) indicate their responses were best explained by truthfulness (epistemic utility).

We implement our model in WebPPL (Goodman & Stuhlmüller, 2014) and use a grid search to infer model parameters. Our full grid consisted of $\lambda \in [0, 1]$ in steps of .05 and $\beta_S, \beta_L \in [1, 10]$ in steps of 1. Maximum likelihood estimates across conditions (Table 4) show the effect of our manipulation: $\lambda_{\text{Truth-biased}} = .35$, $\lambda_{\text{Unbiased}} = .55$, $\lambda_{\text{Relevance-biased}} = .85$. A model

Table 5

Model comparison for the Unbiased condition.

Model	Log Bayes Factor	
	Experiment 1	Experiment 2
Combined	-	-
Truthfulness Only	1475	846
Relevance Only	1508	276

comparison across conditions confirmed these differences are significant (see Appendix C). In addition to these condition-level comparisons, we separately fit participant-level MLEs to visualize the distribution of the λ parameter within conditions (Fig. 7 bottom).

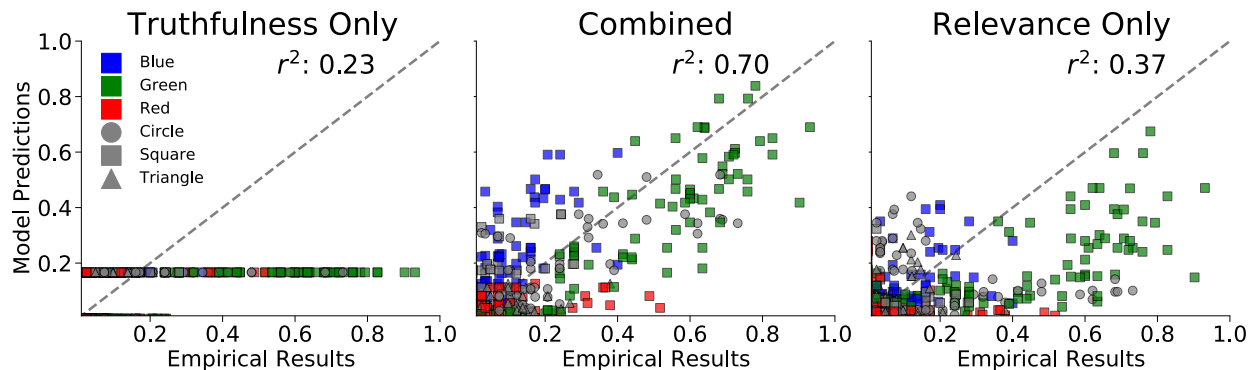
Successful manipulation of the λ parameter confirms that participants understood epistemic and decision-theoretic objectives, and could optimize them independently. Having established this, we focus on the Unbiased condition and ask whether the two component models (truthfulness or relevance alone) are sufficient to explain participant responses.

Model comparisons for Unbiased participants

Our primary hypothesis is that response patterns in the Unbiased condition will be best explained by a combination of epistemic truthfulness and decision-theoretic relevance. We perform a model comparison using the grid search described above, restricting our results to $\lambda = 1$ to obtain the “Relevance only” model and $\lambda = 0$ to obtain the “Truthfulness only” model. We use Bayes factors to compare marginal likelihoods for these models. Evidence for the “Combined” model is extremely strong, with Bayes factors in favor of the “Combined” model $> 1 \times 10^{1400}$; we report log Bayes factors in Table 5. Likelihood ratio tests comparing the “Combined” model to the two nested models yield similar results (vs. “Relevance only”: $\chi^2(1) = 2956.62, p < .0001$); vs. “Truthfulness only”: $\chi^2(2) = 3026.66, p < .0001$). These results confirm our hypothesis: evidence overwhelmingly favors the Combined model to explain Unbiased participants’ utterance choices. These participants followed a combination of epistemic truthfulness and decision-theoretic relevance, rather than either objective independently.

Figure 8

Model performance for Unbiased condition in Experiment 1.



Note. Variance explained for Unbiased condition. We compare component models (“Truthfulness” and “Relevance” only) to the full model (“Combined”). Predictions are made with MLE parameters in Table C1. Independently, truthfulness and relevance are insufficient constraints to explain humans’ preferred choice of utterance. Fitting an additional cost term improves r^2 to .81 (Fig. C6).

We next use the MLE parameters (as well as parameters estimated for the two component models, Table C1) to generate predictions for each model and compare them against human behavior (Fig. 8). It is clear that both truthfulness and relevance are important constraints: neither component alone is sufficient to explain response patterns. Inspection of the residuals (Fig. C5) shows that the model overpredicts usage of negative utterances such as ⟨Blue, -2⟩, and underpredicts usage of positive ones such as ⟨Green, +2⟩. This suggests that negative utterances may be more costly to produce or comprehend: intuitively, they tell the listener what to *avoid*, rather than what to *choose*. This suggests participants balanced “processing effort” against decision-theoretic utility (Jara-Ettinger & Rubio-Fernandez, 2021b; Sperber & Wilson, 1986; Wilson & Sperber, 2002a). Following standard practice in RSA models (Goodman & Frank, 2016), we added a cost term based on the utterance valence, which improved the model fit (see Appendix C, Figs. C6 and C7).

Finally, we hypothesized that maximizing the listener’s decision-theoretic utility would require cognitive effort. To test this, we predicted individual participants’ per-trial response times ($M=12.29$ seconds, $SD=11.14$) from their estimated λ parameter. We used a mixed-effects linear

regression, with a fixed effect for the participant’s inferred λ and random effects for each participant (Barr et al., 2013). The effect of λ was positive and significant ($\beta = 2.99, t(271) = 3.32, p < .01$; see Table C2). This suggests that maximizing the listener’s utility took more effort than simply choosing a truthful utterance.

Discussion

Our results provide strong evidence that participants’ decisions were guided by a combination of truthfulness and decision-theoretic relevance. Our control conditions (Truth- and Relevance-biased) demonstrate that participants understood these distinct objectives and were capable of optimizing them independently: for example, Relevance-biased participants condition readily sent false messages exaggerating features’ values. However, few participants in the Unbiased condition did so: instead, they preferred *true* utterances that maximized utility.

Additionally, we find evidence that reasoning about the listener’s decision problem may be cognitively expensive. Maximizing decision-theoretic utility correlated with longer response times (Table C2), and residual analysis suggests that participants favored positive-valued utterances which may require less “processing effort” (Figs. C5-C7). We return to more nuanced formulations of decision-theoretic processing costs, such as the entropy of the listener’s decision policy, in the General Discussion.

Experiment 1 establishes that truthfulness and relevance may be effectively combined to explain participants’ production patterns. However, this leaves an important question unanswered: how, exactly, do the two objectives relate to each other? Does one take priority over the other? Experiment 2 was designed to address this question by putting the two objectives in conflict.

Experiment 2: Are false utterances ever acceptable?

Experiment 1 demonstrated that truthfulness and relevance operate as independent constraints on participants’ utterance choices. Combining these objectives with a simple convex model produces strong quantitative fits to participant behaviors. However, while these results validate the importance of both truthfulness and relevance, they cannot determine which is

primary. Does one maxim outweigh the other?

Asking participants to endorse false but useful utterances (which lie in the lower-right quadrant of Fig. 1) provides a particularly strong litmus test of different formal models. Pure truth-oriented models (Goodman & Frank, 2016; Stalnaker, 1978) predict that participants should never endorse them. In contrast, Relevance Theory suggests that relevance is primary and truthfulness is an epiphenomenon (Sperber & Wilson, 1986; Wilson & Sperber, 2002b). Under this perspective, participants should endorse relevant utterances irrespective of their truthfulness. Contrary to both of these theories, our “Combined” model predicts that participants will exhibit a graded tradeoff between the two objectives. Concretely, we hypothesized that participants would refuse to endorse false utterances that provide little decision-theoretic utility, but that endorsement rates should rise monotonically as decision-theoretic utility increases.

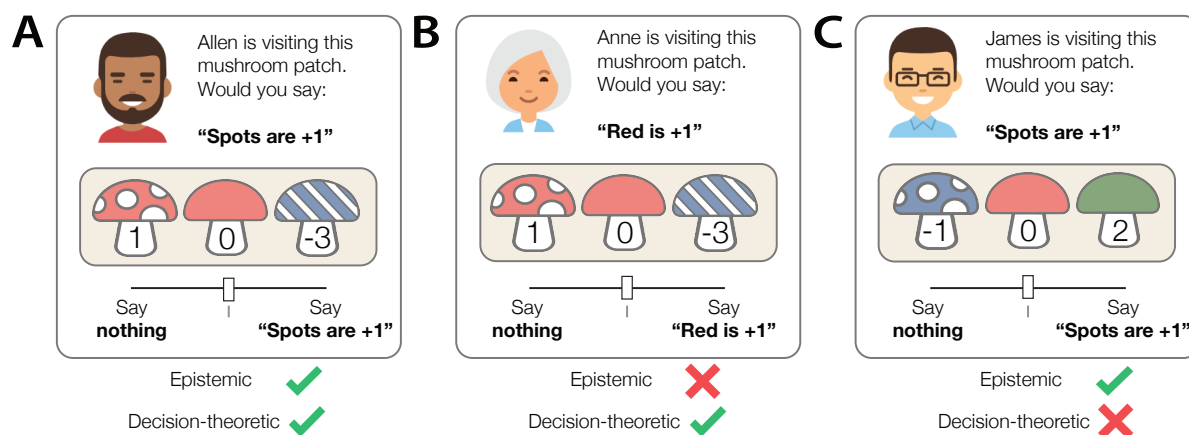
We designed Experiment 2 to test this hypothesis. We asked participants to endorse true and false utterances while systematically varying their decision-theoretic utility. We predicted that participants would endorse a false utterance when—and only when—that lie carried sufficient decision-theoretic utility (and conversely, decline to endorse a true utterance if it had sufficiently negative decision-theoretic utility). As with Experiment 1, such a response pattern would be best explained by our “Combined” model.¹⁵

Methods

Participants

Experiment 2 used the same qualification and compensation structure as Experiment 1. We recruited 300 participants; 25 failed the comprehension quiz and 47 failed attention checks, leaving a final sample size of 228. On average, participants spent about 16 minutes on the experiment (M=16.47, SD=6.84) and earned an hourly wage of \$13.96.

¹⁵ This study was approved by the Princeton IRB (protocol #10859). Experiment design and analyses were pre-registered at https://aspredicted.org/9MD_THB.

Figure 9*Schematic of Experiment 2 trials.*

Note. Experiment 2 trial structure. In each trial, participants were given a specific utterance-context pair and used a slider to indicate their preference between saying it or staying silent. (A) An “aligned” utterance that is true and has positive decision-theoretic utility. (B) A “conflicted” utterance that is false but has positive decision-theoretic utility: “Red” is worth 0, but hearing this utterance makes the listener less likely to choose the negative blue mushroom. (C) A “conflicted” utterance that is true but has negative decision-theoretic utility. The “Spots” feature is actually worth +1, but here co-occurs with the highly negative “Blue” feature. Hearing “Spots are +1” induces true beliefs that lead the listener to take a suboptimal action, reducing their expected utility below random chance. See Fig. [D1](#) for screenshots of the experiment.

Stimuli

The basic stimuli were the same as Experiment 1. However, the trial structure was changed from selecting an utterance to endorsement of a specific utterance. On each trial, participants were given an utterance (for example, “Spots are +1”) and chose between saying it or saying nothing. Participants used a slider to indicate their response: the left side was labeled “Definitely stay silent” and the right “Definitely say <utterance>” (Fig. [9](#)). Slider responses were recorded as integer values ranging from [0, 100].

Each trial consisted of a context-utterance pair. We first identified 72 pairs that put the two objectives in *conflict*. These consisted of false utterances (negative epistemic utility) that—in the paired context—were relevant (positive decision-theoretic utility); or true utterances (positive

epistemic utility) which were not (negative decision-theoretic utility). We balanced this with a sample of 72 *aligned* pairs (i.e. negative epistemic and decision-theoretic utility; or positive epistemic and decision-theoretic utility). Fig. 9 shows example aligned and conflicted trials. This gave a total of 144 possible trials. We grouped these trials by feature and truthfulness, then sorted each group by decision-theoretic utility. We then round-robin assigned them into four sets of 36. This ensured that each participant saw a comparable distribution of utterances, features, and corresponding utilities, mitigating the risk of individual participants seeing sustained spurious correlations (such as the negative “blue” feature consistently correlating with the positive “spotted” feature, Fig. 9C). We then randomly assigned participants to a set, and randomized the trial ordering for each participant. As in Experiment 1, we included 8 attention checks which were held constant across all participants. Appendix D contains additional details.

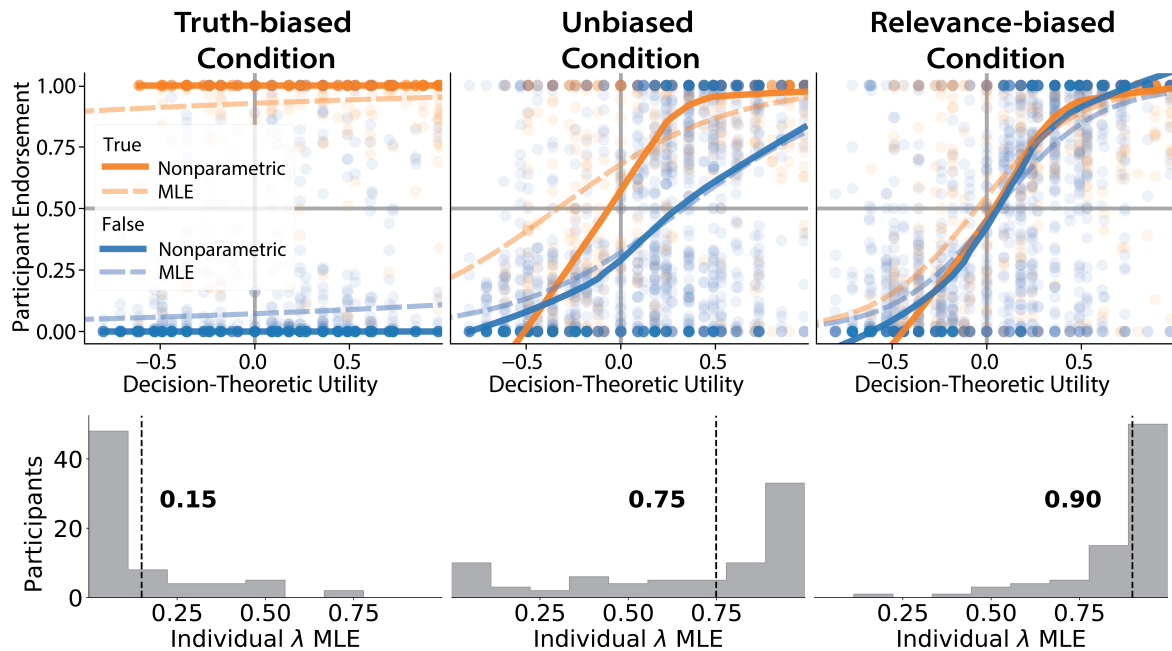
Procedure

Our procedure was identical to Experiment 1, except that the interface was changed to the slider endorsement described above and participants gave judgments for 36 experimental trials instead of 28.

Results

As anticipated, the endorsement paradigm forced a sharper separation of speaker objectives. Our control conditions illustrate this: Truth- and Relevance-biased participants adhered closely to the respective theoretical models. Truth-biased participants always endorsed true statements and refused to endorse false ones, while Relevance-biased participants endorsed statements proportional to their decision-theoretic utility while ignoring their truthfulness (Fig. 10, top left and right). This confirms that participants were unambiguously aware of the epistemic utility (truth or falsehood) of utterances and sensitive to even small fluctuations in their decision-theoretic utility across contexts.

As predicted, Unbiased participants did *not* simply prioritize one objective over the other. Instead, they demonstrated sensitivity to both: endorsement primarily followed decision-theoretic utility, but clearly distinguished between true and false utterances. Their preference for true

Figure 10*Results from Experiment 2.*

Note. Experiment 2 asked participants to endorse utterances with varying truthfulness and relevance. Top: response patterns across conditions. Scatterplots show individual responses, solid lines are locally-weighted regressions, and dashed lines are MLE predictions. Truth- and Relevance-biased participants endorsed utterances proportional to their epistemic or decision-theoretic utility alone. This confirmed that they understood the truthfulness of utterances and their effects on listener behaviors. As predicted, Unbiased participants followed a mix of epistemic and decision-theoretic objectives. Participants endorsed *true* utterances proportional to their decision-theoretic utility. They were less willing to endorse *false* utterances, indicating a sensitivity to epistemic utility—but endorsement nonetheless increased steadily with decision-theoretic utility. Thus, *neither* objective strictly dominates: when put in conflict, participants made a graded tradeoff between the two. Our MLE captures these trends, although it overpredicts endorsement of true-but-misleading utterances. This suggests that epistemic utility may in fact be asymmetric (see the General Discussion). Bottom: MLEs for the λ parameter across conditions. Histograms show the distribution of participant-level MLEs within each condition (estimated by fitting the Combined model to each participant independently), while dashed lines and bold text show the condition-level MLEs (estimated by fitting the Combined model to the condition as a whole). The endorsement paradigm made it difficult to satisfy both objectives.

utterances is visible as the horizontal distance between true and false endorsement curves in the top center panel of Fig. 10. Participants were willing to forego decision-theoretic utility to avoid telling a lie, indicating that they valued truthfulness independent of relevance.

To assess quantitative results, we first adapt our model to the endorsement paradigm, then follow the same model comparison procedure as Experiment 1. We formalize the choice of *not* saying anything by modeling a “silent” utterance with no effect on the listener’s beliefs. We modify the “truthfulness” objective (Eq. 5) and set the epistemic utility of the “silent” choice to zero. The “relevance” objective naturally (Eq. 8) reduces to the expected utility of a random choice from the context. We then model each trial as a binary choice between two utterances: the presented utterance and this “silent” utterance. To account for noise in the participants’ slider-based judgments, we add Gaussian noise $\epsilon \sim \mathcal{N}(0, 30)$ around the model prediction before evaluating model likelihood with respect to the slider judgment. We set the variance of this noise distribution based on pilot data.

Parameter estimates across conditions

We again use a gridsearch over model parameters and analyze the the λ parameter to assess which objectives participants followed. We used the same grid as Experiment 1: $\lambda \in [0, 1]$ in steps of .05 and $\beta_S, \beta_L \in [1, 10]$ in steps of 1. Maximum likelihood estimates (Table 4) for control conditions confirm that Experiment 2’s forced-choice paradigm provides a stronger separation of the two objectives: $\lambda_{\text{Relevance-biased}} = .90$, $\lambda_{\text{Truth-biased}} = .15$. Our forced-choice paradigm particularly affected the Belief-biased condition, as participants no longer had the flexibility to choose utterances that were truthful and *also* optimized relevance. Remarkably, participants in the Unbiased condition still balanced the two: $\lambda_{\text{Unbiased}} = .75$. As with Experiment 1, manipulation checks confirmed our manipulation had significant effects on participants’ response patterns (Appendix D). Again, following Experiment 1, we then fit the Combined model to individual participants in order to visualize the distribution of λ across participants within each condition. Unbiased participants’ MLEs followed a roughly bimodal distribution, with more concentration at the extremes (Fig. 10, bottom center)—notably different from Experiment 1, which followed a more uniform distribution (Fig. 7, bottom center). While

many individual participants were best explained by the “Combined” model, a nontrivial fraction did adhere strongly to one objective.

Model comparisons for Unbiased participants

We followed the same procedure as Experiment 1 to perform a model comparison. Our results again provided extremely strong evidence for the “Combined” model, with Bayes factors exceeding 1×10^{200} (Table 5). Likelihood ratio tests comparing the “Combined” model to the two nested models yield similar results (vs. “Relevance only”: $\chi^2(1) = 556.36$, $p < .0001$; vs. “Truthfulness only”: $\chi^2(2) = 1701.03$, $p < .0001$).

There are two possible reasons for the “Combined” model’s success. The first is that individual participants followed one of the component models (truthfulness- or relevance-only), but differed in which utility they prioritized. The “Combined” model would then be the best explanation for the condition-level results, but any individual participant would be better explained by a simpler truth- or relevance-only model. In contrast, it might be that individual participants followed the “Combined” model and made a graded tradeoff between the two utilities. To test these two hypotheses, we conducted an additional model comparison allowing the λ parameter to vary by participant¹⁶. We compared a simpler “Bimodal” model assuming $\lambda \sim \{0, 1\}$ against a more complex “Combined” model allowing $\lambda \sim \text{Uniform}(0, 1)$. The “Bimodal” model instantiates the hypothesis that individuals followed one of the component models, whereas the “Combined” model suggests that individuals weighed both utilities. We used annealed importance sampling to compare the two (Grosse et al., 2016) and found extremely strong evidence that the “Combined” model provided a better fit to the data (Bayes factor 6.27×10^{13} ; see Appendix D for details). This confirms that individual participants made a graded tradeoff between truthfulness and relevance: the “Combined” model reflects the actual utility function followed by individuals, not simply an overall trend from mixing heterogeneous populations.

¹⁶ We thank an anonymous reviewer for suggesting this analysis.

Discussion

The forced-choice paradigm allowed us to pit truthfulness directly against relevance. Our control conditions reflect this: biasing participants to focus on either truthfulness or relevance moved them strongly towards that objective. Most importantly, Unbiased participants followed the graded tradeoff predicted by our Combined model: participants showed a *willingness* to endorse false utterances, but a *preference* for true ones. This preference—visible as a horizontal offset between endorsement of true and false statements in Fig. 10—captures the “price” that participants put on falsehoods, measured in decision-theoretic utility. This graded tradeoff combines a sensitivity to decision-theoretic utility with a preference for truthfulness (Abeler et al., 2019)—highlighting the need for integrated models considering both utilities.

General Discussion

In this work, we introduced a new speaker model synthesizing *belief*- and *action*-based theories of communication. Expanding the scope of belief-oriented models to encompass real-world action allows a speaker to value both the epistemic and decision-theoretic consequences of speech acts. This framework allowed us to reconcile formal definitions of truthfulness and relevance, capturing a range of examples discussed in the literature. To test our theory, we introduced a new signaling game (Lewis, 1969; Skyrms, 2010) and conducted a pair of experiments. Experiment 1 confirmed that speakers follow both truthfulness and relevance, while Experiment 2 showed that participants make a quantitative, graded tradeoff between the two. This graded tradeoff challenges central tenets of both belief- and action-oriented theories of communication, which hold that one utility is primary. Instead, we find that epistemic and decision-theoretic utilities must be considered in tandem (Franke, 2009).

Implications for psychology

What, then, are the implications of our work? First, our results suggest that speaker behavior results from an interaction between different objectives rather than a single primary goal. Truthfulness can be seen as a preference (Abeler et al., 2019) rather than the foundation of human communication. Formal models emphasizing truthfulness (Lewis, 1969; Stalnaker, 1978)

may be best understood as normative or deontological accounts, with real-world speakers deviating for a variety of reasons—such as rounding times to reduce processing costs (Gibbs Jr & Bryant, 2008; van der Henst et al., 2002), or spreading fake news as a result of failing to fact-check (Pennycook et al., 2021; Pennycook & Rand, 2021).

Similarly, our approach challenges several claims from Relevance Theory. Sperber and Wilson (1986) describe relevance in purely cognitive terms, but our theoretical framework derives it from external decision-theoretic utility (P. Parikh, 1992; R. Parikh, 1994; van Rooij, 2003). Further, our empirical findings show that participants independently value the truthfulness of an utterance, undermining the idea that communication is best understood in terms of relevance alone (Wilson & Sperber, 2002b). Despite these discrepancies, we suggest that our framework may be understood as an extension of the ideas proposed by relevance theorists. Expanding the scope of our formal theory beyond discourse allowed us to quantify “positive cognitive effects” in terms of real-world behaviors. Viewed in this light, our results support the basic claim that relevance is a crucial consideration which may outweigh truthfulness under some circumstances.

Finally, deriving relevance from decision theory may explain the origin of the “question under discussion” (QUD, Benz & Jasinskaja, 2017; van Kuppevelt, 1995; Roberts, 2012). As noted by Roberts (2012), “discourse goals” are often determined by external “domain goals.” Decision theory formalizes this process: question-asking agents can use the “value of information” (Savage, 1954) to prioritize inquiry about decision-relevant information (P. Parikh, 1992; R. Parikh, 1994; van Rooij, 2003). Conversely, speakers can use the same principles to select information that maximally improves the listener’s decision-making (Benz, 2006; Benz & Van Rooij, 2007). This can be seen when speakers “go beyond” the literal content of a question and supply additional decision-relevant knowledge (Hawkins et al., 2015). For example, asked if they accepted credit cards, restaurant owners answered the question and then spontaneously informed the caller about unexpected closures: “Uh, yes, we accept credit cards. But tonight we are closed” (Clark, 1979, p. 466). The restaurant’s open hours are *irrelevant* to the caller’s literal question, yet clearly relevant to the questioner’s implicit plan to come for a meal.

Decision-theoretic relevance thus formalizes the real-world goals atop the QUD hierarchy (Benz & Jasinskaja, 2017; Roberts, 2012).

Implications for artificial intelligence

Beyond psychology, our work offers a new perspective for AI systems. Autonomous agents that understand language (Luketina et al., 2019; Tellex et al., 2020) and reason pragmatically (Fisac et al., 2020; Golland et al., 2010; Hadfield-Menell et al., 2016; Jeon et al., 2020; Milli et al., 2017; Sumers et al., 2022; Wang et al., 2016) are an active research area, but these works typically assume that humans act to maximize decision-theoretic utility alone. Our findings suggest that humans prefer to produce utterances that are relevant *and* true, suggesting that pragmatic speaker models should reflect these biases (Shah et al., 2019).

A second line of AI research develops large language models (LLMs; T. Brown et al., 2020; Chowdhery et al., 2022; Thoppilan et al., 2022). LLMs are trained on massive corpora scraped from the internet, leading them to produce fluent but often harmful language (Bender et al., 2021; Weidinger et al., 2021). This has led to calls to integrate Gricean maxims into such systems to promote normative cooperative discourse (Kasirzadeh & Gabriel, 2022). Computational models of human communication, such as the one presented here, can help bridge the gap. For example, future work could integrate decision-theoretic relevance into LLMs by asking them to reason through the real-world behavioral consequences of an utterance (Ahn et al., 2022; Huang et al., 2022) and evaluate the resulting utilities (Jin et al., 2022) prior to producing it.

How do speakers model listener decision making?

Measures of decision theoretic utility (Eq. 8) typically assume speakers know both the listener’s decision problem (A , the set of available actions) and reason perfectly about their decision-making process (Benz, 2006; Benz & Van Rooij, 2007; Gmytrasiewicz & Durfee, 2001; P. Parikh, 1992; R. Parikh, 1994; Qing & Franke, 2015, *inter alia*). Are these assumptions reasonable? We first consider justifications for making them, then discuss how they may break down in real-world communication.

First, it has long been recognized that language comprehension relies on “common sense” knowledge about real-world scenarios (Sanford & Garrod, 1981; Schank & Abelson, 1977). This is equivalent to our assumption that the speaker knows the listener’s decision problem: for example, Grice’s classic “out of petrol” example of relevance (Grice, 1975) presumes that the speaker and

listener know that cars need petrol to drive, and garages typically sell petrol¹⁷ Second, both adults (Baker et al., 2017; Baker et al., 2009; Jara-Ettinger et al., 2016) and children (Gergely et al., 2002; Gergely et al., 1995) use expectations of rational action together with situational constraints to drive sophisticated social inference. This theory of mind supports both learning (Aboody et al., 2022) and teaching (Bass et al., 2019; Ho, Saxe, et al., 2022), allowing even young children to select task-relevant communicative acts (Gweon & Schulz, 2019) which maximize the listener’s decision-theoretic utility (Bridgers et al., 2020; Gweon, 2021). Decision-theoretic relevance applies the same theory of mind to everyday discourse, assuming the speaker models the listener as a rational agent. Implicit world knowledge supplies the set of possible actions and associated utilities, while theory of mind supplies the listener’s decision process (Davis & Jara-Ettinger, 2022).

The speaker’s knowledge need not be perfect. Just as RSA has been extended to account for lexical uncertainty (Degen et al., 2020; Smith et al., 2013; Wang et al., 2016), our formulation can incorporate uncertainty by marginalizing over decision problems, listener belief states, or true world states. This allows a speaker to reason about—for example—decision problems that might arise in the future (Sumers et al., 2022). And in everyday discourse, a speaker may have partial (Vélez & Gweon, 2021) or incorrect (R. Parikh, 1994) information about the listener’s decision problem. If they produce an irrelevant utterance, the listener might infer the lack of information (Jara-Ettinger & Rubio-Fernandez, 2021a) and initiate a repair (Clark & Marshall, 1981).

To see how such imperfect information might play out in real-world discourse, one could imagine two friends finishing dinner at a restaurant (inspired by Grice’s “out of petrol” example):

(A): There’s an ice cream shop round the corner.

(B): Ah, I’m lactose intolerant.

(A): Well, they have great sorbet!

What is happening here? Intuitively, the real-world context creates an implicit QUD (Benz & Jasinskaja, 2017; van Kuppevelt, 1995): “What should we do next?” A’s first comment implies a

¹⁷ In artificial agents, such information can be supplied as an external knowledge base (Gmytrasiewicz & Durfee, 2001; Tambe, 1997) which is used to derive situation-specific payoff matrices.

desire to get dessert together. However, their proposal suggests they lack knowledge of B’s food allergies (formally, A’s knowledge of the true world state w is incomplete, leading to an incorrect model of B’s payoffs). B repairs this by stating their dietary limitations. A responds by updating B’s beliefs about the decision problem (formally, expanding the set of actions A at the ice cream shop beyond typical dairy-based options). Such an exchange leverages expectations of decision-theoretic relevance (Benz & Van Rooij, 2007) in conjunction with prior knowledge about the world (Schank & Abelson, 1977) to construct a mutually acceptable plan (Clark, 1996).

Lastly, due to cognitive limitations, speakers may not fully reason through the listener’s decision-making process. Indeed, results from Experiment 1 suggest such reasoning may be cognitively expensive: optimizing for decision-theoretic utility correlated with longer response times (Table C2). Speakers also displayed a bias towards positive-valued utterances and away from negative ones (Figs. C5, C6). Positive-valued utterances may be preferred because they direct the listener *towards* the optimal action, rather than *away* from suboptimal ones. A boundedly-rational (Hawkins et al., 2021; Lieder & Griffiths, 2020; Simon, 1957) formulation of relevance could potentially capture this effect by incorporating the listener’s planning complexity into utterance costs (Jara-Ettinger & Rubio-Fernandez, 2021b). This would bias the speaker towards utterances that produce relatively simple decision policies.

Our formulation of decision-theoretic relevance is undeniably simplistic relative to the complexity and uncertainty inherent in real-world communication. However, we are optimistic that can serve as a foundation for future work. We next discuss extensions to more nuanced utility functions and applications to more complex decision problems.

Extensions to the speaker’s utility function

Combining belief- and action-based objectives opens several important research directions. We first discuss our present model of truthfulness and relevance, then suggest extensions investigating the relationships between other belief- and action-based objectives.

The present work used a simple linear weighting of truthfulness and relevance (Eq. 9). However, this weighting is likely nonlinear and context-dependent. Our experiment tested a single type of decision context in a particular online population; future work should explore how

situational and cultural factors may affect it (Gibbs Jr & Colston, 2020; Mühlenbernd & Solt, 2022). We hypothesized that speaker uncertainty could be one such factor, with uncertainty over the listener’s decision context increasing truthfulness. Our pre-registered experiment failed to find an effect (Appendix E), but we believe exploring such context dependence is an important line of future work. For example, speakers may place greater value on truthfulness if they expect to interact with the listener again, or when describing more permanent aspects of the world versus more transient ones. Indeed, telling the time (Gibbs Jr & Bryant, 2008; van der Henst et al., 2002) may be a relatively extreme situation: the time is transient but important for planning actions. In such a domain, speakers may rightfully emphasize relevance over literal truthfulness. Our formulation of truthfulness was also simplistic: we used a symmetric epistemic utility (Eq. 5). However, corroborating results from the literature on deception (van Swol et al., 2012), Experiment 2 suggests that this function may be asymmetric, with a greater penalty placed on outright falsehoods than being under-informative by remaining silent. Exploring the precise form of the truthfulness utility function—or potentially deriving it from decision-theoretic relevance, by implicitly considering future decisions—is an important direction for future work.

Another direction could consider mixed-motive settings, relaxing the assumption that speaker and listener share a reward function (Cao et al., 2018; Franke et al., 2012; Jaques et al., 2019; Noukhovitch et al., 2021; Ostrom et al., 1992; Wagner, 2015). Various epistemic goals may then be derived from differing preferences over real-world actions. Persuasion (Barnett et al., 2022; Mercier & Sperber, 2011) or deception (Oey et al., 2022) could emerge as short-term strategies to achieve speaker-serving actions, while truthfulness (Sbardolini, 2022) or politeness (P. Brown & Levinson, 1987) could signal aligned interests (Yoon et al., 2018; Yoon et al., 2020) to preserve long-term cooperation (Baxter, 1984).¹⁸ Finally, humans use language to enforce social norms (Li & Tomasello, 2021; Vaish et al., 2011) and commitments (Kanngiesser et al., 2017; Ostrom et al., 1992). Norms and commitments could both be modeled as socially-induced utility functions over actions (Fig. 1C), capturing preferences over behaviors beyond intrinsic rewards.

¹⁸ Returning to the “ice cream shop” example, one could imagine it taking place on a first date instead. Recast in this light, the participants’ motives are less certain: B might be lying about having a lactose intolerance in an attempt to end the evening early while saving face. Unfortunately, A is not taking the hint.

Extensions to more complex decision settings

Building on classic signaling games (Lewis, 1969), our experiments used a single-context, fully-observable decision problem (Lattimore & Szepesvari, 2020). More complex settings could help explain different forms of language: for example, Summers et al. (2022) used a multiple-context setting to compare the use of imperative and informative language. Communication in sequential (Puterman, 1994) or partially-observable (Kaelbling et al., 1998) decision problems could explain transmission of procedural knowledge (McCarthy et al., 2021; Thompson et al., 2022) or task representations (Ho, Abel, et al., 2022).

Sequential decision settings would also allow interleaved communication and action (Khani et al., 2018). Speakers could infer the listener’s belief states from their actions (Baker et al., 2017; Jara-Ettinger et al., 2016), relaxing the assumption of perfect speaker knowledge. Finally, a fully embodied model of joint action (Clark, 1996) would allow agents to act physically *or* communicatively in service of a shared goal (Fisac et al., 2020; Hadfield-Menell et al., 2016).

Conclusion

Taken together, our work establishes and evidences a new theoretical framework encompassing both epistemic and decision-theoretic utilities. Reconciling these divergent perspectives on communication allowed us to model the Gricean maxims of truthfulness and relevance as independent and equal objectives. In doing so, we aim to fulfill Grice’s longstanding desire to generalize his theory by expanding the purpose of communication from an exchange of information to “allow for such general purposes as influencing or directing the actions of others” (Grice, 1975, p. 47).

References

- Abbasi-Yadkori, Y., Pál, D., & Szepesvári, C. (2011). Improved algorithms for linear stochastic bandits. *Advances in Neural Information Processing Systems*, (24).
- Abeler, J., Nosenzo, D., & Raymond, C. (2019). Preferences for truth-telling. *Econometrica*, 87(4), 1115–1153.
- Aboody, R., Huey, H., & Jara-Ettinger, J. (2022). Preschoolers decide who is knowledgeable, who to inform, and who to trust via a causal understanding of how knowledge relates to action. *Cognition*, 228, 105212.
- Ahn, M., Brohan, A., Brown, N., Chebotar, Y., Cortes, O., David, B., Finn, C., Gopalakrishnan, K., Hausman, K., Herzog, A., et al. (2022). Do as i can, not as i say: Grounding language in robotic affordances. *arXiv preprint arXiv:2204.01691*.
- Allen, J. F. (1983). Recognizing intentions from natural language utterances. In M. Brady & R. C. Berwick (Eds.), *Computational models of discourse* (pp. 107–166).
- Allen, J. F., & Perrault, C. R. (1980). Analyzing intention in utterances. *Artificial Intelligence*, 15(3), 143–178.
- Andreas, J., & Klein, D. (2016). Reasoning about pragmatics with neural listeners and speakers. *Proceedings of the 2016 Conference on Empirical Methods in Natural Language Processing*, 1173–1182.
- Austin, J. L. (1962). *How to do things with words*. Oxford University Press.
- Baker, C. L., Jara-Ettinger, J., Saxe, R., & Tenenbaum, J. B. (2017). Rational quantitative attribution of beliefs, desires and percepts in human mentalizing. *Nature Human Behaviour*, 1(4), 1–10.
- Baker, C. L., Saxe, R., & Tenenbaum, J. B. (2009). Action understanding as inverse planning. *Cognition*, 113(3), 329–349.
- Bard, N., Foerster, J. N., Chandar, S., Burch, N., Lanctot, M., Song, H. F., Parisotto, E., Dumoulin, V., Moitra, S., Hughes, E., et al. (2020). The Hanabi challenge: A new frontier for AI research. *Artificial Intelligence*, 280, 103216.
- Barnett, S. A., Griffiths, T. L., & Hawkins, R. D. (2022). A Pragmatic Account of the Weak Evidence Effect. *Open Mind*, 6, 1–14.

- Barr, D. J., Levy, R., Scheepers, C., & Tily, H. J. (2013). Random effects structure for confirmatory hypothesis testing: Keep it maximal. *Journal of memory and language*, *68*(3), 255–278.
- Bass, I., Gopnik, A., Hanson, M., Ramarajan, D., Shafto, P., Wellman, H., & Bonawitz, E. (2019). Children’s developing theory of mind and pedagogical evidence selection. *Developmental psychology*, *55*(2), 286.
- Baxter, L. A. (1984). An investigation of compliance-gaining as politeness. *Human communication research*, *10*(3), 427–456.
- Bender, E. M., Gebru, T., McMillan-Major, A., & Shmitchell, S. (2021). On the dangers of stochastic parrots: Can language models be too big? *Proceedings of the 2021 ACM conference on fairness, accountability, and transparency*, 610–623.
- Benz, A. (2006). Utility and relevance of answers. *Game theory and pragmatics* (pp. 195–219). Springer.
- Benz, A. (2011). How to set up normal optimal answer models. *Language, Games, and Evolution: Trends in Current Research on Language and Game Theory*, 14–39.
- Benz, A., Jäger, G., & Van Rooij, R. (2005). *Game theory and pragmatics*. Springer.
- Benz, A., & Jasinskaja, K. (2017). Questions under discussion: From sentence to discourse. *Discourse Processes*, *54*, 177–186.
- Benz, A., & Stevens, J. (2018). Game-theoretic approaches to pragmatics. *Annual Review of Linguistics*, *4*, 173–191.
- Benz, A., & Van Rooij, R. (2007). Optimal assertions, and what they implicate. a uniform game theoretic approach. *Topoi*, *26*(1), 63–78.
- Bridgers, S., Jara-Ettinger, J., & Gweon, H. (2020). Young children consider the expected utility of others’ learning to decide what to teach. *Nature Human Behaviour*, *4*(2), 144–152.
- Brown, P., & Levinson, S. C. (1987). *Politeness: Some universals in language usage* (Vol. 4). Cambridge University Press.
- Brown, T., Mann, B., Ryder, N., Subbiah, M., Kaplan, J. D., Dhariwal, P., Neelakantan, A., Shyam, P., Sastry, G., Askell, A., Agarwal, S., Herbert-Voss, A., Krueger, G., Henighan, T., Child, R., Ramesh, A., Ziegler, D., Wu, J., Winter, C., . . . Amodei, D.

- (2020). Language models are few-shot learners. In H. Larochelle, M. Ranzato, R. Hadsell, M. Balcan, & H. Lin (Eds.), *Advances in neural information processing systems* (pp. 1877–1901). Curran Associates, Inc.
- Caie, M. (2013). Rational probabilistic incoherence. *Philosophical Review*, 122(4), 527–575.
- Cao, K., Lazaridou, A., Lanctot, M., Leibo, J. Z., Tuyls, K., & Clark, S. (2018). Emergent communication through negotiation. *International Conference on Learning Representations*.
- Carr, J. R. (2017). Epistemic utility theory and the aim of belief. *Philosophy and Phenomenological Research*, 95(3), 511–534.
- Chowdhery, A., Narang, S., Devlin, J., Bosma, M., Mishra, G., Roberts, A., Barham, P., Chung, H. W., Sutton, C., Gehrmann, S., et al. (2022). PaLM: Scaling language modeling with pathways. *arXiv preprint arXiv:2204.02311*.
- Chu, W., Li, L., Reyzin, L., & Schapire, R. (2011). Contextual bandits with linear payoff functions. *International Conference on Artificial Intelligence and Statistics*, 15.
- Clark, H. H. (1979). Responding to indirect speech acts. *Cognitive psychology*, 11(4), 430–477.
- Clark, H. H. (1996). *Using Language*. Cambridge University Press.
- Clark, H. H., & Marshall, C. R. (1981). Definite reference and mutual knowledge. In A. K. Joshi, B. L. Webber, & I. A. Sag (Eds.), *Elements of discourse understanding* (pp. 10–63). Cambridge University Press, Cambridge, UK.
- Cohen, P. R., & Levesque, H. J. (1988). *Rational interaction as the basis for communication* (tech. rep.). SRI International, Menlo Park CA.
- Cohen, P. R., & Perrault, C. R. (1979). Elements of a plan-based theory of speech acts. *Cognitive Science*, 3(3), 177–212.
- Dale, R., & Reiter, E. (1995). Computational interpretations of the gricean maxims in the generation of referring expressions. *Cognitive Science*, 19(2), 233–263.
- Davis, I., & Jara-Ettinger, J. (2022). Hierarchical task knowledge constrains and simplifies action understanding. *Proceedings of the Annual Meeting of the Cognitive Science Society*, 44(44).
- De Saussure, F. (1916). *Course in General Linguistics*. Columbia University Press.

- Deacon, J. W. (1997). *Modern mycology* (Vol. 3). Blackwell Science Oxford.
- Degen, J., Hawkins, R. D., Graf, C., Kreiss, E., & Goodman, N. D. (2020). When redundancy is useful: A bayesian approach to “overinformative” referring expressions. *Psychological Review*, *127*(4), 591.
- Donaldson, M. C., Lachmann, M., & Bergstrom, C. T. (2007). The evolution of functionally referential meaning in a structured world. *Journal of Theoretical Biology*, *246*(2), 225–233.
- Fisac, J. F., Gates, M. A., Hamrick, J. B., Liu, C., Hadfield-Menell, D., Palaniappan, M., Malik, D., Sastry, S. S., Griffiths, T. L., & Dragan, A. D. (2020). Pragmatic-pedagogic value alignment. *Robotics Research* (pp. 49–57). Springer.
- Frank, M. C., & Goodman, N. D. (2012). Predicting pragmatic reasoning in language games. *Science*, *336*(6084), 998–998.
- Franke, M. (2009). *Signal to act: Game theory in pragmatics*. Institute for Logic, Language; Computation Amsterdam.
- Franke, M. (2016). The evolution of compositionality in signaling games. *Journal of Logic, Language and Information*, *25*, 355–377.
- Franke, M., De Jager, T., & Van Rooij, R. (2012). Relevance in cooperation and conflict. *Journal of Logic and Computation*, *22*(1), 23–54.
- Fried, D., Andreas, J., & Klein, D. (2018). Unified pragmatic models for generating and following instructions. *Proceedings of the 2018 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 1 (Long Papers)*, 1951–1963.
- Fried, D., Chiu, J., & Klein, D. (2021). Reference-centric models for grounded collaborative dialogue. *Proceedings of the 2021 Conference on Empirical Methods in Natural Language Processing*, 2130–2147.
- Fried, D., Hu, R., Cirik, V., Rohrbach, A., Andreas, J., Morency, L.-P., Berg-Kirkpatrick, T., Saenko, K., Klein, D., & Darrell, T. (2018). Speaker-follower models for vision-and-language navigation. *Advances in Neural Information Processing Systems*.
- Galantucci, B. (2005). An experimental study of the emergence of human communication systems. *Cognitive science*, *29*(5), 737–767.

- Galantucci, B., & Garrod, S. (2011). Experimental semiotics: A review. *Frontiers in human neuroscience*, 5, 11.
- Gergely, G., Bekkering, H., & Király, I. (2002). Rational imitation in preverbal infants. *Nature*, 415(6873), 755–755.
- Gergely, G., Nádasdy, Z., Csibra, G., & Biró, S. (1995). Taking the intentional stance at 12 months of age. *Cognition*, 56(2), 165–193.
- Gibbs Jr, R. W. (1987). Mutual knowledge and the psychology of conversational inference. *Journal of Pragmatics*, 11(5), 561–588.
- Gibbs Jr, R. W., & Bryant, G. A. (2008). Striving for optimal relevance when answering questions. *Cognition*, 106(1), 345–369.
- Gibbs Jr, R. W., & Colston, H. L. (2020). Pragmatics always matters: An expanded vision of experimental pragmatics. *Frontiers in Psychology*, 11, 1619.
- Gmytrasiewicz, P. J., & Doshi, P. (2005). A framework for sequential planning in multi-agent settings. *Journal of Artificial Intelligence Research*, 24, 49–79.
- Gmytrasiewicz, P. J., & Durfee, E. H. (2001). Rational communication in multi-agent environments. *Autonomous Agents and Multi-Agent Systems*, 4(3), 233–272.
- Golland, D., Liang, P., & Klein, D. (2010). A game-theoretic approach to generating spatial descriptions. *Proceedings of the 2010 Conference on Empirical Methods in Natural Language Processing*, 410–419.
- Goodman, N. D., & Frank, M. C. (2016). Pragmatic language interpretation as probabilistic inference. *Trends in Cognitive Sciences*, 20(11), 818–829.
- Goodman, N. D., & Lassiter, D. (2015). Probabilistic semantics and pragmatics: Uncertainty in language and thought. *The Handbook of Contemporary Semantic Theory*, 2nd Ed.
- Goodman, N. D., & Stuhlmüller, A. (2014). The Design and Implementation of Probabilistic Programming Languages.
- Greaves, H., & Wallace, D. (2006). Justifying conditionalization: Conditionalization maximizes expected epistemic utility. *Mind*, 115(459), 607–632.
- Grice, H. P. (1957). Meaning. *Philosophical Review*, 66(3), 377–388.

- Grice, H. P. (1975). Logic and conversation. *Syntax and Semantics: Vol. 3: Speech Acts* (pp. 41–58). Academic Press.
- Grice, H. P. (1989). *Studies in the way of words*. Harvard University Press.
- Grosse, R. B., Ancha, S., & Roy, D. M. (2016). Measuring the reliability of mcmc inference with bidirectional monte carlo. *Advances in Neural Information Processing Systems*, 29.
- Gweon, H. (2021). Inferential social learning: Cognitive foundations of human social learning and teaching. *Trends in Cognitive Sciences*, 25(10), 896–910.
- Gweon, H., & Schulz, L. (2019). From exploration to instruction: Children learn from exploration and tailor their demonstrations to observers' goals and competence. *Child development*, 90(1), e148–e164.
- Hadfield-Menell, D., Russell, S. J., Abbeel, P., & Dragan, A. (2016). Cooperative inverse reinforcement learning. *Advances in Neural Information Processing Systems*.
- Hawkins, R. D., Gweon, H., & Goodman, N. D. (2021). The division of labor in communication: Speakers help listeners account for asymmetries in visual perspective. *Cognitive science*, 45(3), e12926.
- Hawkins, R. D., Stuhlmüller, A., Degen, J., & Goodman, N. D. (2015). Why do you ask? Good questions provoke informative answers. *Proceedings of the 39th Annual Conference of the Cognitive Science Society*.
- van der Henst, J.-B., Carles, L., & Sperber, D. (2002). Truthfulness and relevance in telling the time. *Mind & Language*, 17(5), 457–466.
- Ho, M. K., Abel, D., Correa, C. G., Littman, M. L., Cohen, J. D., & Griffiths, T. L. (2022). People construct simplified mental representations to plan. *Nature*, 606(7912), 129–136.
- Ho, M. K., Saxe, R., & Cushman, F. (2022). Planning with theory of mind. *Trends in Cognitive Sciences*.
- Hockett, C. F. (1960). The origin of speech. *Scientific American*, 203(3), 88–97.
- Hoek, D. (2018). Conversational exculpation. *Philosophical Review*, 127(2), 151–196.
- Huang, W., Xia, F., Xiao, T., Chan, H., Liang, J., Florence, P., Zeng, A., Tompson, J., Mordatch, I., Chebotar, Y., et al. (2022). Inner monologue: Embodied reasoning through planning with language models. *arXiv preprint arXiv:2207.05608*.

- Hyman, F. (2021). *How to forage for mushrooms without dying: An absolute beginner's guide to identifying 29 wild, edible mushrooms*. Storey Publishing, LLC.
- Jaques, N., Lazaridou, A., Hughes, E., Gulcehre, C., Ortega, P., Strouse, D., Leibo, J. Z., & De Freitas, N. (2019). Social influence as intrinsic motivation for multi-agent deep reinforcement learning. *International Conference on Machine Learning*, 3040–3049.
- Jara-Ettinger, J., Gweon, H., Schulz, L. E., & Tenenbaum, J. B. (2016). The naive utility calculus: Computational principles underlying commonsense psychology. *Trends in Cognitive Sciences*, 20(8), 589–604.
- Jara-Ettinger, J., & Rubio-Fernandez, P. (2021a). Quantitative mental state attributions in language understanding. *Science advances*, 7(47), eabj0970.
- Jara-Ettinger, J., & Rubio-Fernandez, P. (2021b). The social basis of referential communication: Speakers construct physical reference based on listeners' expected visual search. *Psychological review*.
- Jeon, H. J., Milli, S., & Dragan, A. (2020). Reward-rational (implicit) choice: A unifying formalism for reward learning. *Advances in Neural Information Processing Systems*.
- Jin, Z., Levine, S., Adauto, F. G., Kamal, O., Sap, M., Sachan, M., Mihalcea, R., Tenenbaum, J. B., & Schölkopf, B. (2022). When to make exceptions: Exploring language models as accounts of human moral judgment. In A. H. Oh, A. Agarwal, D. Belgrave, & K. Cho (Eds.), *Advances in neural information processing systems*.
- Joyce, J. M. (1998). A nonpragmatic vindication of probabilism. *Philosophy of science*, 65(4), 575–603.
- Kaelbling, L. P., Littman, M. L., & Cassandra, A. R. (1998). Planning and acting in partially observable stochastic domains. *Artificial intelligence*, 101(1-2), 99–134.
- Kang, Y., Wang, T., & de Melo, G. (2020). Incorporating pragmatic reasoning communication into emergent language. *Advances in Neural Information Processing Systems*, 33, 10348–10359.
- Kanngiesser, P., Köymen, B., & Tomasello, M. (2017). Young children mostly keep, and expect others to keep, their promises. *Journal of Experimental Child Psychology*, 159, 140–158.

- Kao, J., Bergen, L., & Goodman, N. D. (2014). Formalizing the pragmatics of metaphor understanding. *Proceedings of the 36th Annual Conference of the Cognitive Science Society*.
- Kao, J., & Goodman, N. D. (2015). Let's talk (ironically) about the weather: Modeling verbal irony. *Proceedings of the 37th Annual Conference of the Cognitive Science Society*.
- Kao, J., Wu, J. Y., Bergen, L., & Goodman, N. D. (2014). Nonliteral understanding of number words. *Proceedings of the National Academy of Sciences*, *111*(33), 12002–12007.
- Kasirzadeh, A., & Gabriel, I. (2022). In conversation with artificial intelligence: Aligning language models with human values. *arXiv preprint arXiv:2209.00731*.
- Khani, F., Goodman, N. D., & Liang, P. (2018). Planning, inference and pragmatics in sequential language games. *Transactions of the Association for Computational Linguistics*, *6*, 543–555.
- Krahmer, E., & Van Deemter, K. (2012). Computational generation of referring expressions: A survey. *Computational Linguistics*, *38*(1), 173–218.
- Krifka, M. (2007). Approximate interpretation of number words: A case for strategic communication. In I. K. J. Z. G. Bouma (Ed.), *Cognitive foundations of interpretation* (pp. 111–126). Koninklijke Nederlandse Akademie van Wetenschappen.
- van Kuppevelt, J. (1995). Discourse structure, topicality and questioning. *Journal of Linguistics*, *31*(1), 109–147.
- Lassiter, D., & Goodman, N. D. (2017). Adjectival vagueness in a Bayesian model of interpretation. *Synthese*, *194*(10), 3801–3836.
- Lattimore, T., & Szepesvari, C. (2020). *Bandit algorithms*. Cambridge University Press.
- Lazaridou, A., & Baroni, M. (2020). Emergent multi-agent communication in the deep learning era. *arXiv preprint arXiv:2006.02419*.
- Lazaridou, A., Peysakhovich, A., & Baroni, M. (2017). Multi-agent cooperation and the emergence of (natural) language. *International Conference on Learning Representations*.
- Levinson, S. C. (1989). A review of Relevance. *Journal of Linguistics*, *25*(2), 455–472.
- Lewis, D. (1969). *Convention: A Philosophical Study*. John Wiley & Sons.

- Lewis, D. (1979). Scorekeeping in a language game. *Semantics from Different Points of View* (pp. 172–187). Springer.
- Li, L., & Tomasello, M. (2021). On the moral functions of language. *Social Cognition*, 39(1), 99–116.
- Li, L., Chu, W., Langford, J., & Schapire, R. E. (2010). A contextual-bandit approach to personalized news article recommendation. *Proceedings of the 19th International Conference on the World Wide Web*, 661–670.
- Lieder, F., & Griffiths, T. L. (2020). Resource-rational analysis: Understanding human cognition as the optimal use of limited computational resources. *Behavioral and brain sciences*, 43, e1.
- Litman, D. J., & Allen, J. F. (1987). A plan recognition model for subdialogues in conversations. *Cognitive Science*, 11(2), 163–200.
- Litman, D. J., & Allen, J. F. (1990). Discourse processing and commonsense plans. In P. R. Cohen, J. L. Morgan, & M. E. Pollack (Eds.), *Intentions in Communication*. MIT Press.
- Luketina, J., Nardelli, N., Farquhar, G., Foerster, J., Andreas, J., Grefenstette, E., Whiteson, S., & Rocktäschel, T. (2019). A survey of reinforcement learning informed by natural language. *International Joint Conference on Artificial Intelligence*.
- McCarthy, W. P., Hawkins, R. D., Wang, H., Holdaway, C., & Fan, J. E. (2021). Learning to communicate about shared procedural abstractions. *Proceedings of the Annual Conference of the Cognitive Science Society*.
- Mercier, H., & Sperber, D. (2011). Why do humans reason? arguments for an argumentative theory. *Behavioral and brain sciences*, 34(2), 57–74.
- Merin, A. (1999). Information, relevance, and social decisionmaking: Some principles and results of decision-theoretic semantics. *Logic, Language, and computation*, 2, 179–221.
- Milli, S., Hadfield-Menell, D., Dragan, A., & Russell, S. (2017). Should robots be obedient? *International Joint Conference on Artificial Intelligence*.
- Monroe, W., & Potts, C. (2015). Learning in the rational speech acts model. *arXiv preprint arXiv:1510.06807*.

- Mühlenbernd, R., & Solt, S. (2022). Modeling (im) precision in context. *Linguistics Vanguard*, 8(1), 113–127.
- Nie, A., Cohn-Gordon, R., & Potts, C. (2020). Pragmatic issue-sensitive image captioning. *Findings of the Association for Computational Linguistics: EMNLP 2020*, 1924–1938.
- Noukhovitch, M., LaCroix, T., Lazaridou, A., & Courville, A. (2021). Emergent communication under competition. *Proceedings of the 20th International Conference on Autonomous Agents and MultiAgent Systems*, 974–982.
- O'Connor, C. (2014). The evolution of vagueness. *Erkenntnis*, 79, 707–727.
- Oey, L. A., Schachner, A., & Vul, E. (2022). Designing and detecting lies by reasoning about other agents. *Journal of Experimental Psychology: General*.
- Ostrom, E., Walker, J., & Gardner, R. (1992). Covenants with and without a sword: Self-governance is possible. *American political science Review*, 86(2), 404–417.
- Parikh, P. (1991). Communication and strategic inference. *Linguistics and Philosophy*, 14(5), 473–514.
- Parikh, P. (1992). A game-theoretic account of implicature. *Proceedings of the 4th Conference on Theoretical Aspects of Reasoning about Knowledge*, 85–94.
- Parikh, P. (2001). *The Use of Language*. CSLI Publications, Stanford, CA.
- Parikh, R. (1994). Vagueness and utility: The semantics of common nouns. *Linguistics and Philosophy*, 521–535.
- Pennycook, G., Epstein, Z., Mosleh, M., Arechar, A. A., Eckles, D., & Rand, D. G. (2021). Shifting attention to accuracy can reduce misinformation online. *Nature*, 592(7855), 590–595.
- Pennycook, G., & Rand, D. G. (2021). The psychology of fake news. *Trends in Cognitive Sciences*, 25(5), 388–402.
- Perrault, C. R., Allen, J., & Cohen, P. R. (1978). Speech acts as a basis for understanding dialogue coherence. *American Journal of Computational Linguistics*, 32–39.
- Pettigrew, R. (2016). *Accuracy and the laws of credence*. Oxford University Press.
- Puterman, M. L. (1994). *Markov decision processes: Discrete stochastic dynamic programming*. John Wiley & Sons, Inc.

- Qing, C., & Franke, M. (2015). Variations on a Bayesian theme: Comparing Bayesian models of referential reasoning. *Bayesian Natural Language Semantics and Pragmatics* (pp. 201–220). Springer.
- Riquelme, C., Tucker, G., & Snoek, J. (2018). Deep Bayesian bandits showdown: An empirical comparison of Bayesian deep networks for Thompson sampling. *International Conference on Learning Representations*.
- Roberts, C. (2012). Information structure: Towards an integrated formal theory of pragmatics. *Semantics and Pragmatics*, 5, 6–1.
- van Rooij, R. (2003). Questioning to resolve decision problems. *Linguistics and Philosophy*, 26(6), 727–763.
- Sanford, A., & Garrod, S. (1981). *Understanding Written language: Explorations of Comprehension Beyond the Sentence*. Wiley.
- Savage, L. J. (1954). *The foundations of statistics*. John Wiley Sons.
- Sbardolini, G. (2022). Is honesty rational? *The Philosophical Quarterly*, 72(4), 979–1001.
- Schank, R. C., & Abelson, R. P. (1977). *Scripts, plans, goals, and understanding: An inquiry into human knowledge structures*. Psychology Press.
- Seneff, S., & Polifroni, J. (2000). Dialogue management in the mercury flight reservation system. *ANLP-NAACL 2000 Workshop: Conversational Systems*.
<https://aclanthology.org/W00-0303>
- Shah, R., Gundotra, N., Abbeel, P., & Dragan, A. (2019). On the feasibility of learning, rather than assuming, human biases for reward inference. *International Conference on Machine Learning*, 5670–5679.
- Shannon, C. E. (1948). A mathematical theory of communication. *The Bell System Technical Journal*, 27(3), 379–423.
- Shen, S., Fried, D., Andreas, J., & Klein, D. (2019). Pragmatically informative text generation. *Proceedings of the Annual Conference of the North American Chapter of the Association for Computational Linguistics - Human Language Technologies*, 4060–4067.
- Simon, H. A. (1957). Models of man; social and rational.
- Skyrms, B. (2010). *Signals: Evolution, learning, and information*. OUP Oxford.

- Smith, N. J., Goodman, N., & Frank, M. (2013). Learning and using language via recursive pragmatic reasoning about other agents. *Advances in neural information processing systems*, 26.
- Sperber, D., & Wilson, D. (1985). Loose talk. *Proceedings of the Aristotelian society*, 86, 153–171.
- Sperber, D., & Wilson, D. (1986). *Relevance: Communication and Cognition* (Vol. 142). Harvard University Press Cambridge, MA.
- Sperber, D., & Wilson, D. (1987). Précis of Relevance: Communication and Cognition. *Behavioral and Brain Sciences*, 10(4), 697–710.
- Stalnaker, R. C. (1978). Assertion. *Pragmatics* (pp. 315–332). Brill.
- Steels, L. (2003). Evolving grounded communication for robots. *Trends in Cognitive Sciences*, 7(7), 308–312.
- Steinert-Threlkeld, S. (2020). Toward the emergence of nontrivial compositionality. *Philosophy of Science*, 87(5), 897–909.
- Sumers, T. R., Hawkins, R. D., Ho, M. K., & Griffiths, T. L. (2021). Extending rational models of communication from beliefs to actions. *Proceedings of the 43rd Annual Conference of the Cognitive Science Society*.
- Sumers, T. R., Hawkins, R. D., Ho, M. K., Griffiths, T. L., & Hadfield-Menell, D. (2022). How to talk so AI will learn: Instructions, descriptions, and autonomy. *Advances in Neural Information Processing Systems*.
- Sumers, T. R., Ho, M. K., Hawkins, R. D., Narasimhan, K., & Griffiths, T. L. (2021). Learning rewards from linguistic feedback. *Proceedings of the AAAI Conference on Artificial Intelligence*, 35(7), 6002–6010.
- Sutton, R. S., & Barto, A. G. (2018). *Reinforcement Learning: An Introduction*. MIT press.
- van Swol, L. M., Malhotra, D., & Braun, M. T. (2012). Deception and its detection: Effects of monetary incentives and personal relationship history. *Communication Research*, 39(2), 217–238.
- Tambe, M. (1997). Towards flexible teamwork. *Journal of artificial intelligence research*, 7, 83–124.

- Tellex, S., Gopalan, N., Kress-Gazit, H., & Matuszek, C. (2020). Robots that use language. *Annual Review of Control, Robotics, and Autonomous Systems*, 3(1), 25–55.
- Thomason, R. H. (1990). Accomodation, meaning, and implicature. In P. R. Cohen, J. L. Morgan, & M. E. Pollack (Eds.), *Intentions in Communication*. MIT Press.
- Thompson, B., Van Opheusden, B., Sumers, T., & Griffiths, T. (2022). Complex cognitive algorithms preserved by selective social learning in experimental populations. *Science*, 376(6588), 95–98.
- Thoppilan, R., De Freitas, D., Hall, J., Shazeer, N., Kulshreshtha, A., Cheng, H.-T., Jin, A., Bos, T., Baker, L., Du, Y., et al. (2022). LaMDA: Language models for dialog applications. *arXiv preprint arXiv:2201.08239*.
- Vaish, A., Missana, M., & Tomasello, M. (2011). Three-year-old children intervene in third-party moral transgressions. *British Journal of Developmental Psychology*, 29(1), 124–130.
- Vanderveken, D. (1990). On the unification of Speech Act Theory and formal semantics. In P. R. Cohen, J. L. Morgan, & M. E. Pollack (Eds.), *Intentions in Communication*. MIT Press.
- Vélez, N., & Gweon, H. (2021). Learning from other minds: An optimistic critique of reinforcement learning models of social learning. *Current Opinion in Behavioral Sciences*, 38, 110–115.
- Vogel, A., Bodoia, M., Potts, C., & Jurafsky, D. (2013). Emergence of Gricean maxims from multi-agent decision theory. *Proceedings of the Annual Conference of the North American Chapter of the Association for Computational Linguistics - Human Language Technologies*, 1072–1081.
- Wagner, E. O. (2015). Conventional semantic meaning in signalling games with conflicting interests. *The British Journal for the Philosophy of Science*.
- Wang, S. I., Liang, P., & Manning, C. D. (2016). Learning language games through interaction. *Proceedings of the 54th Annual Meeting of the Association for Computational Linguistics (Volume 1: Long Papers)*, 2368–2378.
- Weidinger, L., Mellor, J., Rauh, M., Griffin, C., Uesato, J., Huang, P.-S., Cheng, M., Glaese, M., Balle, B., Kasirzadeh, A., et al. (2021). Ethical and social risks of harm from language models. *arXiv preprint arXiv:2112.04359*.

- Wilson, D., & Sperber, D. (2002a). Relevance Theory. In G. Ward & L. Horn (Eds.), *Handbook of pragmatics*. Blackwell.
- Wilson, D., & Sperber, D. (2002b). Truthfulness and relevance. *Mind*, *111*(443), 583–632.
- Yoon, E. J., MacDonald, K., Asaba, M., Gweon, H., & Frank, M. C. (2018). Balancing informational and social goals in active learning. *Proceedings of the 40th Annual Conference of the Cognitive Science Society*.
- Yoon, E. J., Tessler, M. H., Goodman, N. D., & Frank, M. C. (2020). Polite speech emerges from competing social goals. *Open Mind*, *4*, 71–87.
- Young, S., Gašić, M., Thomson, B., & Williams, J. D. (2013). POMDP-based statistical spoken dialog systems: A review. *Proceedings of the IEEE*, *101*(5), 1160–1179.
- <https://doi.org/10.1109/JPROC.2012.2225812>

Appendix A

The formal relationship between QUDs and decision problems.

Let's begin by working out the decision-theoretic relevance (Eq. 8) for the case with exactly two world states and two actions:

$$\begin{bmatrix} R(a, w) & R(\neg a, w) \\ R(a, \neg w) & R(\neg a, \neg w) \end{bmatrix} = \begin{bmatrix} r & s \\ s & r \end{bmatrix}$$

$$\begin{aligned} U_{Relevance}(u | w) &= \sum_{a \in A} \pi_L(a | u) R(a, w) \\ &= \pi_L(a | u) R(a, w) + \pi_L(\neg a | u) R(\neg a, w) \\ &= r \cdot \frac{\exp\{\beta_L \sum_W R(a, w) P_L(w | u)\}}{\sum_A \exp\{\beta_L \sum_W R(a, w) P_L(w | u)\}} + s \cdot \frac{\exp\{\beta_L \sum_W R(\neg a, w) P_L(w | u)\}}{\sum_A \exp\{\beta_L \sum_W R(a, w) P_L(w | u)\}} \\ &= \frac{1}{Z} [r \cdot \exp\{\beta_L (s + (r - s) \cdot P_L(w | u))\} + s \cdot \exp\{\beta_L (r + (s - r) \cdot P_L(w | u))\}] \end{aligned}$$

where the normalization constant is given by

$$Z = \exp\{\beta_L [s + (r - s) P_L(w | u)]\} + \exp\{\beta_L [r + (s - r) P_L(w | u)]\}$$

Now, intuitively, suppose there's a unique action in each world with arbitrarily high reward r . Assume further that taking the wrong action is arbitrarily costly, $s < r$. Then if we know the true world is w , we should expect the decision-theoretic utility of an utterance to reduce to some function of epistemic utility, since the listener's belief about which world they are in maps one-to-one to which action they will take. We begin by showing that there does, in fact, exist a special case of a decision problem where an exact equivalence holds. We will call this case the "identity" decision problem.

Theorem 1. *There exists an "identity" decision problem \mathcal{D}_0 that is equivalent to the epistemic objective.*

Proof. Note that the utility only depends upon the ratio of s and r , not their absolute values. Then without loss of generality, we may fix $r = 0$ and $s < 0$ such that the utility simplifies to:

$$\begin{aligned}
U_{Relevance}(u | w) &= \frac{s}{Z} \cdot \exp\{s\beta_L P_L(w|u)\} \\
&= \frac{s \cdot \exp\{s\beta_L P_L(w|u)\}}{\exp\{s\beta_L P_L(w|u)\} + \exp\{s\beta_L(1 - P_L(w|u))\}} \\
&= \frac{s}{1 + \exp\{s\beta_L[1 - 2P_L(w|u)]\}}
\end{aligned}$$

In other words, we observe that $U_{Relevance}(u|w)$ takes the functional form of a logistic function on the listener's beliefs, with asymptote s , slope $s\beta_L$ and midpoint $P_L(w|u) = 0.5$.

Now, we will show that there exists some $s < 0$ such that $U_{Relevance}(u|w, A) = \ln P_L(w|u)$.

To declutter the calculation, we will set $\beta_L = 1$ and let $p = P_L(w|u)$ and define

$A(p) = W_0(p^{1-2p}(2p-1)\ln p)$ where W_0 is the principal branch of the Lambert W-function (i.e.

the unique function such that $Ae^A = p^{1-2p}(2p-1)\ln p$). Then consider the decision problem

given by

$$s = \frac{\ln[A/((2p-1)\ln p)]}{1-2p} \quad (\text{A1})$$

yielding the utility

$$\begin{aligned}
U_{Relevance}(u | w) &= \frac{s}{1 + \exp\{s[1 - 2p]\}} \\
&= \frac{\ln A - \ln[(2p-1)\ln p]}{(1-2p)(1 + \frac{A}{(2p-1)\ln p})}.
\end{aligned}$$

By definition of the W-function, we have

$$\begin{aligned}
Ae^A &= p^{1-2p}(2p-1)\ln p \\
\Rightarrow \ln A + A &= \ln p^{1-2p} + \ln[(2p-1)\ln p] \\
\Rightarrow \ln A - \ln[(2p-1)\ln p] &= (1-2p)\ln p - A
\end{aligned}$$

Then, if we substitute the right side into the numerator of the utility, we obtain

$$\begin{aligned}
U_{Relevance}(u|w) &= \frac{(1-2p)\ln p - A}{(1-2p)(1 + \frac{A}{(2p-1)\ln p})} \\
&= \frac{(1-2p)(\ln p + \frac{A}{2p-1})}{(1-2p)(1 + \frac{A}{(2p-1)\ln p})} \\
&= \frac{\ln p \cdot (1 + \frac{A}{(2p-1)\ln p})}{1 + \frac{A}{(2p-1)\ln p}} \\
&= \ln p
\end{aligned}$$

obtaining the standard information-theoretic objective.

It only remains to check whether s as defined in Eq. [A1](#) is real-valued for all $p \in [0, 1]$ (i.e. that it does not have any singularities in the relevant domain). Our first concern is whether $A(p) = W_0(p^{1-2p}(2p-1)\ln p)$ even exists over $p \in [0, 1]$ or whether it vanishes or blows up at some point. Note that the principal branch of the Lambert W -function is known to have real-valued solutions for $x \geq -1/e$, and it can be shown by taking the derivative that $\min\{p^{1-2p}(2p-1)\ln p\} \approx -0.17 > -0.36 \approx -1/e$ (where the minimum is obtained at $p = e^{W_0(e/2)-1} \approx 0.73$). Thus, A itself is well-behaved over $p \in [0, 1]$.

Now we are ready to consider the full function $s = f(p)$. It is not obvious, but this function can be shown to be continuous over the unit interval, with $s \rightarrow -\infty$ as $p \rightarrow 0$ and $s \rightarrow 0$ as $p \rightarrow 1$. Naively, we may expect a singularity at $p = 0.5$, since the denominator is 0, but we may check that the limits are well defined (specifically, as $p \rightarrow 0.5$, we can calculate that $s \rightarrow -\log 4 \approx -1.38629$; intuitively, the numerator gets big precisely where the denominator gets big so the ratio is well-behaved).

□

An important consequence of this theorem is that the rewards r and s associated with different actions under the identity decision problem are determined purely as a function of the listener's updated beliefs about the world after hearing the utterance, which are determined *a priori* by the semantics of the language without reference to actions (otherwise any definition of an identity decision problem would be circular).

Given our definition of the identity decision problem, we are ready to consider the relationship to the question-under-discussion (QUD) framework proposed by Roberts ([2012](#)). Intuitively, the primary formal innovation of our model can be viewed as a way of relaxing the 'hard' Boolean notion of a QUD partition to a more graded notion derived from decision-theoretic principles. Rather than assigning each state to a cell of a partition, we assign each state a continuous value. In this section, we consider a basic theorem that sketches out the formal relationship between these constructs. This theorem says that grounding relevance in continuous decision problems is a strict generalization of the discrete partitions used as QUDs: we lose none of the formal expressiveness of QUDs, as any QUD can be translated to an equivalent decision

problem (specifically, a generalization of the identity decision problem from Theorem 1).

Theorem 2. *Any partition-based QUD is equivalent to some decision problem.*

Proof. Let \sim_Q be an equivalence relation on possible worlds $w \in \mathcal{W}$. This relation defines a *canonical projection* $f_Q : w \rightarrow [w]_Q$, where $[w]_Q = \{w' \in \mathcal{W} : w' \sim_Q w\}$ is the equivalence class of an element w . Note that the set of equivalence classes form a partition on \mathcal{W} . Under the RSA formulation (e.g. Kao, Wu, et al., 2014), a speaker aiming to be relevant with respect to Q uses the following utility:

$$U_{QUD}(u; w^*, Q) = \ln P_L([w^*]_Q | u) \quad (\text{A2})$$

where w^* is the (known) true world state and P_L is the probability assigned to the cell of the partition containing the true world:

$$P_L([w^*]_Q | u) = \sum_{w \in [w^*]_Q} P_L(w | u) \quad (\text{A3})$$

Now, consider the following extension of the identity decision problem:

$$R(a_1, w) = \begin{cases} r & \text{if } w \in [w^*]_Q \\ s & \text{o.w.} \end{cases}$$

$$R(a_2, w) = \begin{cases} s & \text{if } w \in [w^*]_Q \\ r & \text{o.w.} \end{cases}$$

where the listener obtains reward r upon taking action a_1 in the cell of the partition containing the true world and a_2 in any other cell. Then

$$\begin{aligned} U_{Relevance}(u | w^*) &= \sum_{a \in A} \pi_L(a | u) R(a, w^*) \\ &= \pi_L(a_1 | u) R(a_1, w^*) + \pi_L(a_2 | u) R(a_2, w^*) \\ &= r \frac{\exp\{\beta_L \sum_w R(a_1, w) P_L(w|u)\}}{\sum_a \exp\{\beta_L \sum_w R(a, w) P_L(w|u)\}} + s \frac{\exp\{\beta_L \sum_w R(a_2, w) P_L(w|u)\}}{\sum_a \exp\{\beta_L \sum_w R(a, w) P_L(w|u)\}} \\ &= \frac{1}{Z} [r \exp\{\beta_L r P_L([w]_Q | u) + s P_L([\neg w]_Q | u) \\ &\quad + s \exp\{\beta_L r P_L([\neg w]_Q | u) + s P_L([w]_Q | u) \end{aligned}$$

The rest of the proof follows the same calculation used in Theorem 1; we show that under the identity decision problem, the decision-theoretic utility given by Eq. 8 is equivalent to the epistemic utility under the QUD, given by Eq. A2.

□

While the decision-theoretic formulation may be more theoretically satisfying for problems that arise in cognitive science, it can also be seen that the decision-theoretic approach is equivalent to an extension of the traditional set-theoretic formulation known as a *value-weighted* partition, where a real number is associated with each cell and a corresponding term is added to the speaker utility. Thus, the converse does not necessarily hold: there exist decision problems that cannot be expressed as partition-based QUDs.

Appendix B

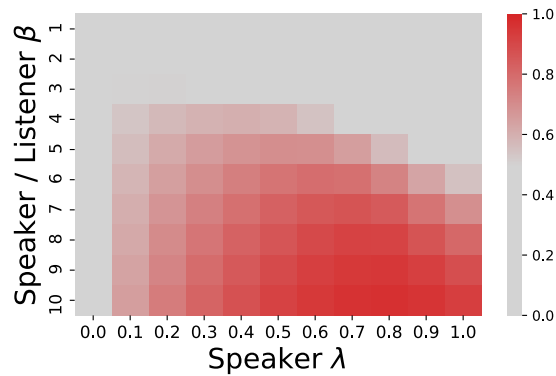
Simulation Parameter Sensitivity

Our simulations of existing theoretical puzzles are intended to provide insight into how decision-theoretic relevance affects speakers' choice of utterance and listeners' inferences about their meanings. Our approach was to write down simple and intuitive payoff matrices, then use a gridsearch to identify plausible effect sizes in each case. In this section, we include the results of the grid searches to provide intuition about the sensitivity of the effects of interest to model parameters. In general, the effect for the first simulation (Grice's "Out of Petrol" example) holds across a wide range of parameter space, while the second two simulations (the time-based examples) require relatively high λ values.

It is important to emphasize that these simulations should be taken qualitatively rather than quantitatively. They illustrate that the combined model is necessary to drive intuitive effects, but the examples have many degrees of freedom (e.g., payoff matrices and utterance costs) and are not intended as evidence about actual parameter values. For example, incorporating utterance costs into all of the examples would expand the regions of parameter space in which the theoretically desired effects are found.

Figure B1

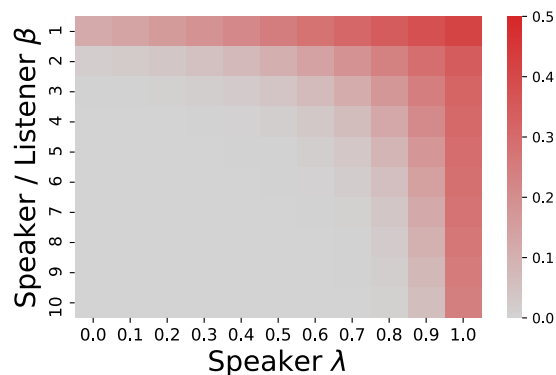
Parameter sensitivity in Grice’s “Out of Petrol” example.



Note. Heatmap showing the listener’s posterior probability that the garage is open (as opposed to closed or nonexistent). The theoretically important contrast is between the “Truth-only” model ($\lambda = 0$) and the “Combined” model ($0 > \lambda > 1$); the “truth-only” model can never derive the implicature that the garage is likely to be open. When the speaker is assumed to be noisy (low β) or epistemically unreliable ($\lambda \gg .5$), the listener maintains some probability that the gas station simply does not exist.

Figure B2

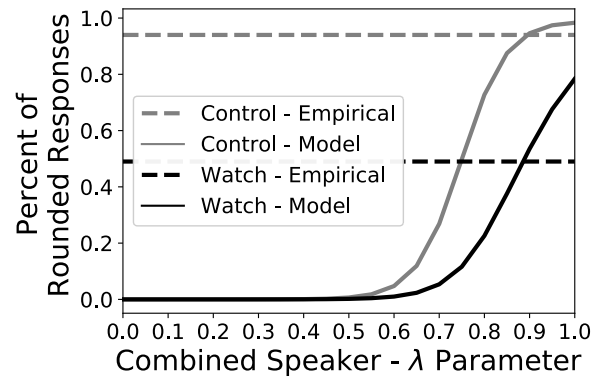
Parameter sensitivity in the “Lecture Start Time” example.



Note. Heatmap showing the listener’s posterior probability that the lecture will start late. “Pragmatic loosening” occurs anytime the listener’s posterior is nonzero; this effect requires a relatively high λ parameter. Incorporating utterance costs as suggested by Wilson and Sperber (2002b) would expand the range of parameter space in which the effect size is found.

Figure B3

Parameter sensitivity in the “Telling the Time” example.



Note. Line plot showing the speaker’s probability of rounding as a function of context and the λ parameter, assuming $\beta_S = \beta_L = 10$. Solid lines show the model predictions and dashed lines show empirically observed rates of rounding. $\lambda > .5$ is required to obtain rounding effects, and the empirical rounding behavior in both conditions is found when $\lambda = .9$.

Appendix C

Experiment 1

Methods Details

Feature Randomizations

To mitigate perceptual biases, the feature-value mappings were randomized for each participant. One set of features (color or texture) was assigned values in $[-1, 0, 1]$ without replacement, while the other was assigned values from $[-2, 0, 2]$ without replacement. Fig. C1A shows the “canonical” feature-value mapping, while Fig. C1B shows one of the randomized feature-value mappings seen by participants. For analysis purposes, we present all results mapped back to the “canonical” features. The ordering of trials was randomized. The order of actions in each trial (e.g. left-center-right) was randomized. To avoid response bias, the ordering of features was randomized (keeping textures and colors grouped); the ordering of values was randomized between ascending and descending.

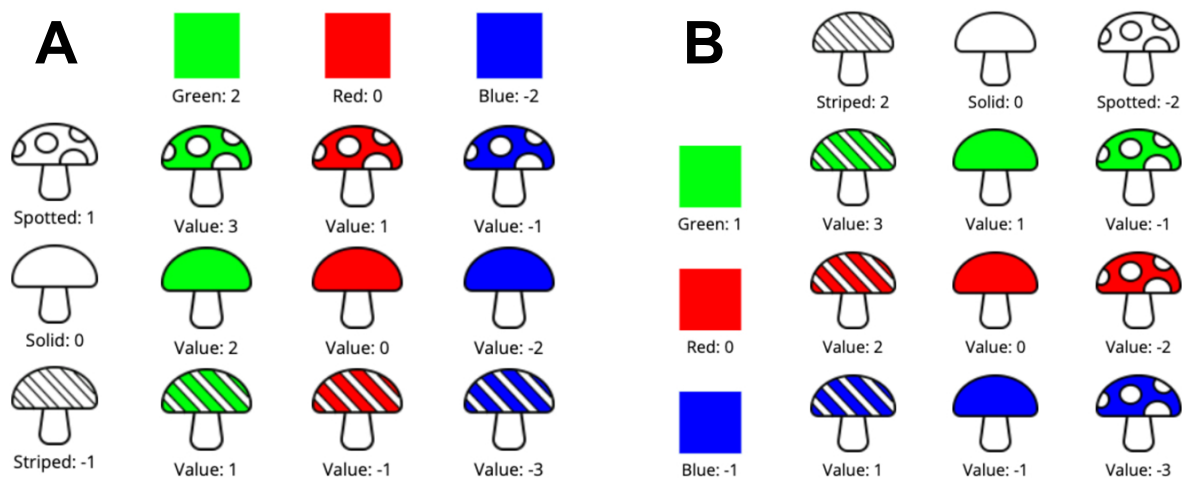


Figure C1

Signaling bandits cast in a mushroom foraging setting. A: the “canonical” feature mapping, equivalent to Fig. C1A and used for analysis throughout. B: an example of a randomized feature mapping used in the experiment. At any point during the main experiment (after passing the quiz), participants could access this view by clicking on the “View Mushroom Info” button visible in other screenshots.

Attention Checks

In addition to the 28 experimental trials, we included eight attention checks which were identical across all participants. These trials followed the same basic structure as the experimental trials: a tourist was shown visiting a patch of three mushrooms. However, in these trials, the participants’ choice of utterance was constrained to a single feature and two possible values. The contexts and features were selected to ensure that *truthfulness* and *relevance* objectives were aligned: the true utterance (e.g. “Spots are +1”) always had positive decision-theoretic utility, while the false option (e.g. “Spots are -1”) had negative decision-theoretic utility. A cooperative speaker should always choose the true-and-useful message. Participants had to select the correct answer on at least 75% (6/8) of the attention checks. 273 of 285 participants (96%) passed the attention checks; the remaining 12 were still paid the \$2 completion bonus but were excluded from the analysis.

Results Details

Manipulation Checks

We first obtain maximum likelihood estimates for each condition separately (Table C1). The ordering of the λ parameter matches our expectations: $\lambda_{\text{Relevance-biased}} > \lambda_{\text{Unbiased}} > \lambda_{\text{Truth-biased}}$. To confirm that these results are significant, we perform a model comparison across conditions. We obtain marginal likelihoods for three models: (1) a *single* λ parameter for all participants across all conditions; (2) *independent* λ parameters for each condition, (3) *ordinal* λ parameters for each condition, restricted to our hypothesis that $\lambda_{\text{Relevance-biased}} > \lambda_{\text{Unbiased}} > \lambda_{\text{Truth-biased}}$. We use a gridsearch over the same range of β parameters: $\beta_S \in [1, 10]$ and $\beta_L \in [1, 10]$.

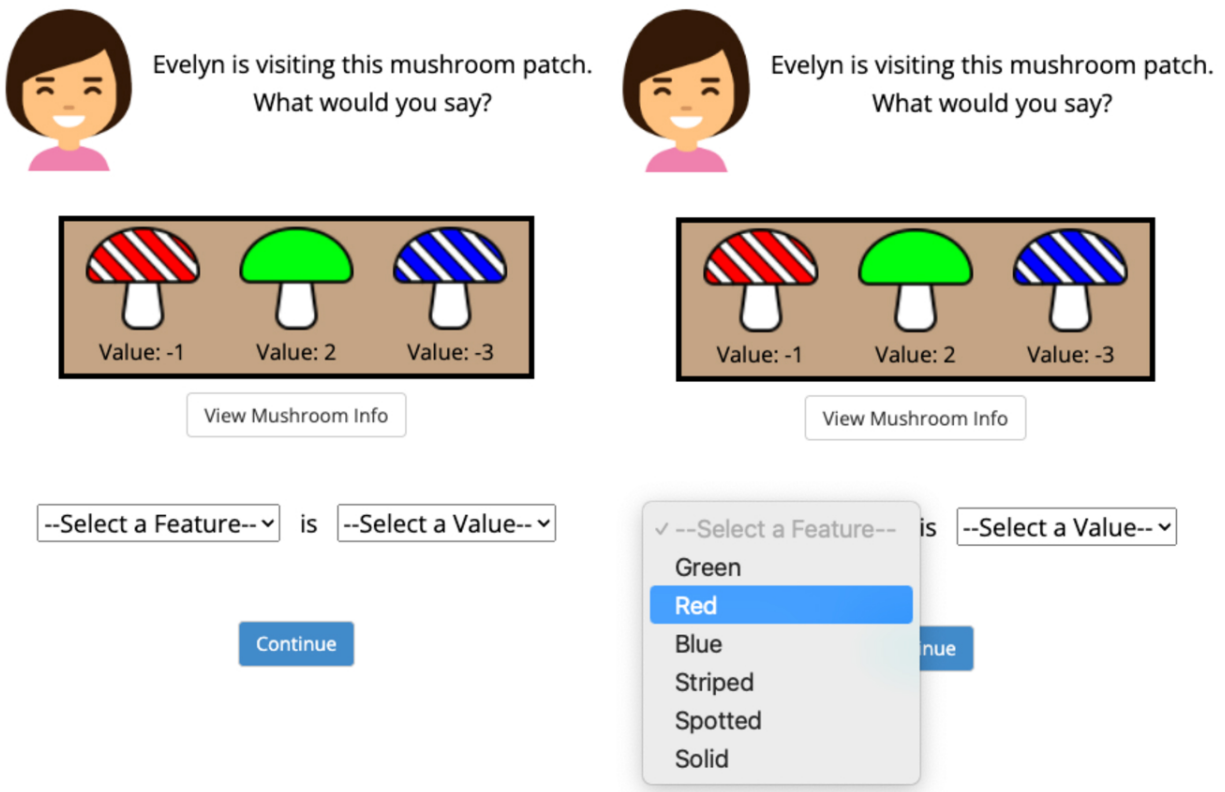
We find evidence in favor of the ordinal model in both cases: for ordinal-vs-single, the $\log \text{BF} = 1019.40$; for the ordinal-vs-independent, the $\log \text{BF} = 2.09$ ($\text{BF}=8.07$).

Likelihood Ratio Tests

Setting the λ parameter (Eq. 9) to 0 yields a purely truthful speaker; setting it to 1 yields a pure relevance speaker; intermediate values yield a combined speaker. We use the

Figure C2

Example trial from Experiment 1.



Note. Left: participants were presented with a tourist visiting a particular mushroom patch (e.g. decision context). Right: participants selected utterances using drop-down menus.

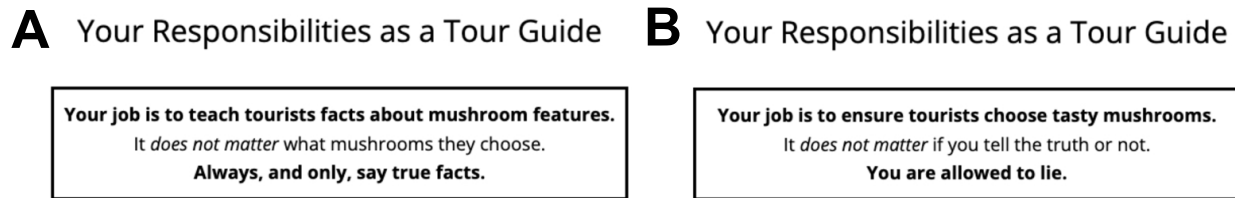
maximum-likelihood estimates obtained from gridsearch (Table C1) to perform likelihood ratio tests on the Unbiased condition. These confirm the results obtained by Bayes factors in the main text: the “Combined” model is significantly better than the “Relevance only” model ($\chi^2(1) = 2956.62, p < .0001$) and the “Truthfulness only” model ($\chi^2(2) = 3026.66, p < .0001$).

Modeling Utterance Cost (Valence Bias)

Model residuals (Fig. 8, C5) suggest that participants favored *positive* utterances (e.g., “Green, +2”) at higher rates than predicted by the model, and disfavored negative ones (e.g. “Blue, -2”). Intuitively, this may be explained by greater processing effort associated with

Figure C3

Instructions given to control conditions.



Note. Conditions were biased towards the theoretical speaker models. A: Screenshot from “Truth-biased” instructions. B: Same for “Relevance-biased” instructions. “Unbiased” participants skipped this instruction page. See the experiment URL for the full instructions in context.

negative-valence utterances: because they tell the listener to *avoid* certain actions, it requires an additional step to reason about which actions they are more likely to choose.

We tested a variant of the model including an additional cost term favoring positive-valence utterances (e.g. any utterance with a value of +1 or +2) and disfavoring negative-valence ones (-1 or -2):

$$C(u) = \begin{cases} \nu & \text{if } u_{\mathcal{R}} > 0 \\ -\nu & \text{if } u_{\mathcal{R}} < 0 \\ 0 & \text{if } u_{\mathcal{R}} = 0 \end{cases} \quad (\text{C1})$$

We used this term directly in Combined speaker (Eq. 9) and ran the same gridsearch as above, including the additional parameter $\nu \in [0, .25, .5, .75, 1]$. We found that $\nu = .25$ improved the model fit and accounted for this residual structure (Fig. C6, C7). However, it did not substantially change the resulting maximum-likelihood parameters for the model. The full MLE for the Unbiased condition was $\lambda = .55, \beta_S = 3, \beta_L = 2, \nu = .25$.

Response Times

Table C1*Maximum likelihood estimates for different models and conditions in Experiment 1.*

Condition	N	Model	Maximum Likelihood			
			λ	β_S	β_L	Log LH
Truth Biased	87	Truth Only	-	2	-	-5005
		Relevance Only	-	2	1	-6890
		Combined	.35	3	1	-4556
Unbiased	95	Truth Only	-	2	-	-6570
		Relevance Only	-	2	2	-6535
		Combined	.55	3	3	-5057
Relevance Biased	91	Truth Only	-	2	-	-7346
		Relevance Only	-	3	2	-4768
		Combined	.85	4	2	-4403

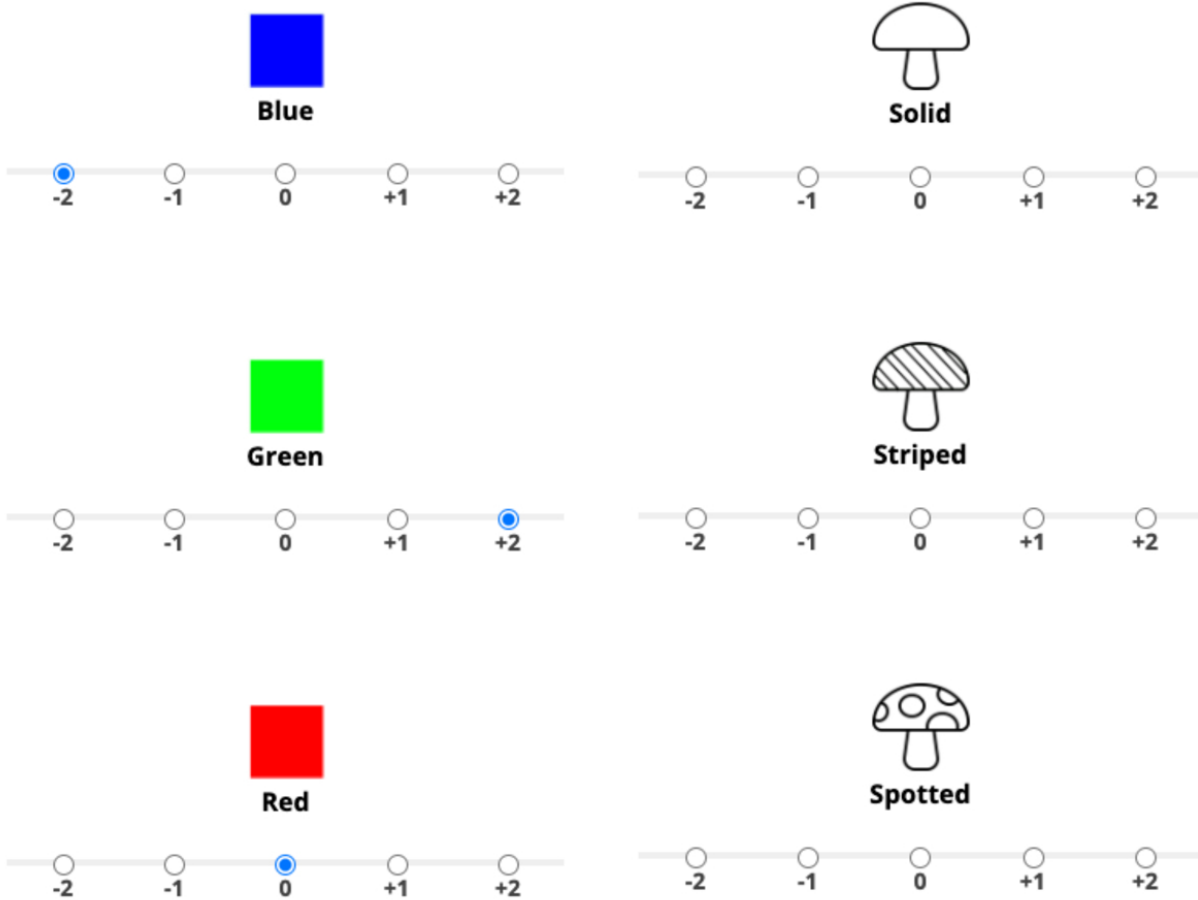
Table C2*Predicting per-trial response times.*

	Effect	Group	Term	Estimate	Std Error	Statistic	DOF	p-value
1	Fixed		(Intercept)	10.73	0.56	19.27	271.00	<0.001
2	Fixed		λ	2.99	0.90	3.32	271.00	<0.01
3	Random	workerid	sd_Int	4.54				
4	Random	Residual	sd_Obs	10.13				

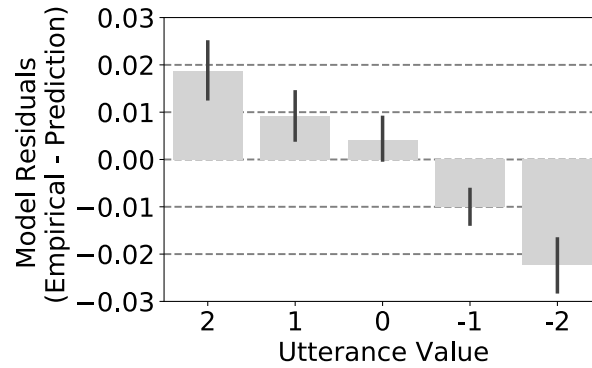
Note. Linear mixed-effects model to predict per-trial response time with a fixed effect of the participant's inferred λ parameter and random effects for each participant. λ correlates positively and significantly with response times.

Figure C4

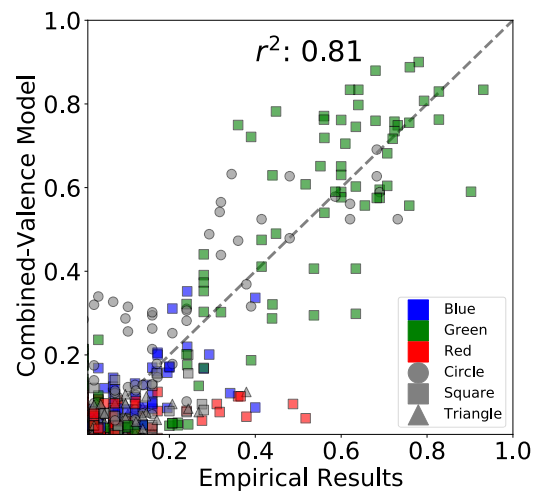
Example comprehension questions.



Note. All participants took a 16-question comprehension quiz requiring them to learn the feature-value mapping, as well as important gameplay dynamics. The six questions regarding feature values are shown here. This ensured that all participants knew the true world state w .

Figure C5*Model residuals.*

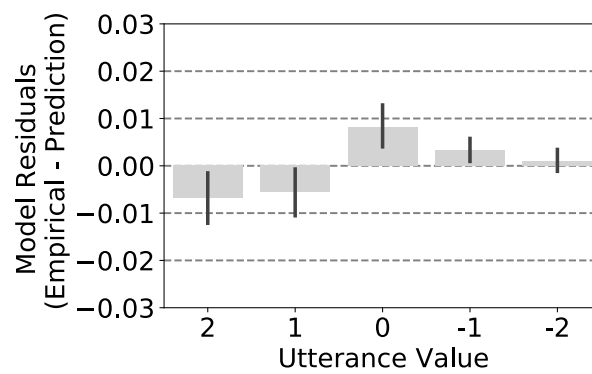
Note. Model residuals (empirical - prediction) grouped by utterance *value* and *feature*. Participants displayed a bias for positive-valence features and utterances.

Figure C6*Modeling a preference for positive-valued utterances.*

Note. Variance explained when incorporating an additional parameter favoring positive utterances and down-weighting negative ones.

Figure C7

Model residuals after incorporating utterance costs.



Note. Incorporating an additional parameter reflecting a bias towards positive-valence utterances substantially reduced residual structure (cf. Fig. [C5](#) for residuals without this parameter).

Appendix D

Experiment 2

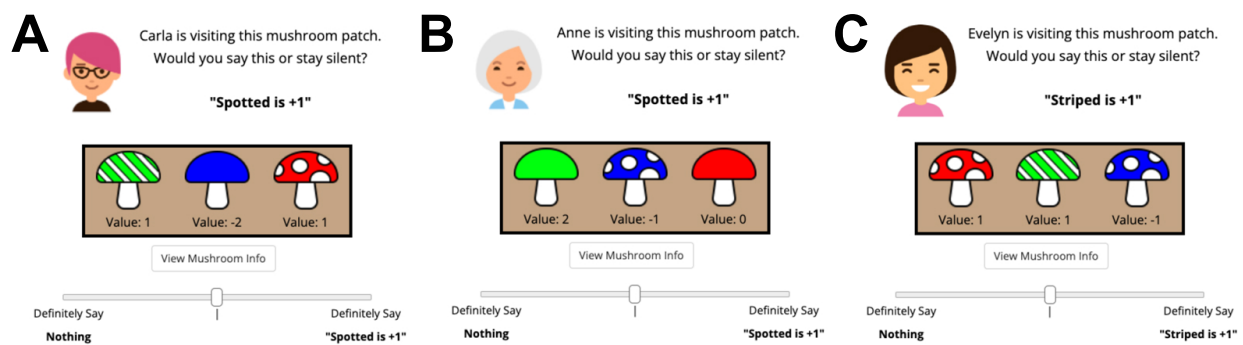
Methods Details

Generating Utterance-Context Pairs

To generate a set of utterances for Experiment 2, we first needed to assign each an decision-theoretic utility. We did so by simulating the behavior of a listener with $\beta_L = 3$ (we chose this value based on MLE estimates for “Unbiased” Exp 1 pilot data). This gave us 2,250 possible utterance-context pairs (30 utterances \times 84 contexts).

Figure D1

Screenshots of actual user interface from Experiment 2.



Note. (A) an “aligned” utterance that is true (the “Spotted” feature is actually worth +1) and has positive decision-theoretic utility. (B) a “conflicted” utterance that is true but has negative decision-theoretic utility. (C) a “conflicted” utterance that is false but has positive decision-theoretic utility.

We next identified the theoretically interesting context-utterance pairs that put the objectives in “conflict” (false messages with positive decision-theoretic utility, or true messages with negative decision-theoretic utility). These consisted of utterances about “weak” features (whose true value was +1 or -1) or “neutral” features (whose true value was 0). We stratified these by (feature, value, decision-theoretic utility), and sampled one message from each. This yielded 72 “conflicting” context-utterance pairs with decision-theoretic utility in the range [-1.5, 2.3]. We balanced these using a similar procedure for “aligned” context-utterance pairs (i.e. true

messages with positive or zero decision-theoretic utility, or false messages with negative decision-theoretic utility). We filtered for utterances in the decision-theoretic utility range $[-1.5, 2.3]$, stratified by (feature, value, decision-theoretic utility) and took one sample from each, yielding 94 pairs. We randomly sampled 72 of these, yielding a total of 144 utterances.

Finally, to ensure each participant saw a balanced set of utterances, we grouped them by feature, truthfulness and sorted them by decision-theoretic utility, then round-robin assigned them into four sets of 36. Participants were randomly assigned one of these sets. The ordering of trials was randomized.

Attention Checks

Attention checks follow the same structure as experimental trials. However there were two key differences: first, they were constant across all participants; and second, rather than a graded slider, participants were asked to make a binary choice between endorsing the utterance or stay silent. Attention check trials were selected to align the two speaker objectives: false utterances that were negative utility, and true utterances that were positive utility. As a result, cooperative speakers should always choose to say the true messages and not say the false ones.

Results Details

Manipulation Checks

We follow the same procedure for manipulation checks as Experiment 1. Table [D1](#) shows the maximum-likelihood estimates for each model and each condition. We then use a model comparison to test whether the ordering of the λ parameter matches our expectations: $\lambda_{\text{Relevance-biased}} > \lambda_{\text{Unbiased}} > \lambda_{\text{Truth-biased}}$. We again obtain marginal likelihoods for a model with (1) a single λ parameter, (2) λ parameters for each condition, (3) ordinal λ parameters for each condition $\lambda_{\text{Relevance-biased}} > \lambda_{\text{Unbiased}} > \lambda_{\text{Truth-biased}}$. We use a gridsearch over the same range of β parameters: $\beta_S \in [1, 10]$ and $\beta_L \in [1, 10]$.

We find evidence in favor of the ordinal model in both cases: for ordinal-vs-single, the $\log \text{BF} = 1801.49$; for the ordinal-vs-independent, the $\log \text{BF} = 2.09$ ($\text{BF}=8.07$).

Likelihood Ratio Tests

We followed the same procedure as Experiment 1, using the maximum-likelihood estimates obtained from gridsearch (Table D1) to perform likelihood ratio tests on the “Unbiased” condition. These confirm the results obtained by Bayes factors in the main text: the “Combined” model is significantly better than the “Relevance Only” model ($\chi^2(1) = 556.36, p < .0001$) and the “Truthfulness only” model ($\chi^2(2) = 1701.03, p < .0001$).

Table D1

Maximum likelihood estimates for Experiment 2.

Condition	N	Model	Maximum Likelihood			
			λ	β_S	β_L	Log LH
Truth-biased	71	Truthfulness Only	-	3	-	-11832
		Relevance Only	-	1	1	-14410
		Combined	.15	3	1	-11813
Unbiased	78	Truthfulness Only	-	1	-	-14962
		Relevance Only	-	2	1	-14390
		Combined	.75	3	1	-14112
Relevance-biased	79	Truthfulness Only	-	1	-	-15838
		Relevance Only	-	4	1	-13740
		Combined	.90	3	2	-13709

Note. The decision-theoretic utility of an utterance-context pair depends on the inferred β_L parameter, as this determines how much the utterance will affect the listener’s policy. In order to use the same x-axis in all plots, Fig. 10 assumes $\beta_L = 1$. To generate the model predictions for the Relevance-biased condition, we use a different set of model parameters: $\lambda = .95, \beta_S = 4, \beta_L = 1$. This was the second-best parameter set from our grid search, with a negative log-likelihood of -13711.

Testing for Bimodality

The distribution of individually-estimated λ parameters in the “Unbiased” condition appeared qualitatively bimodal (Fig. 10, bottom center), relative to the responses in Experiment

Table D2*Model comparison for bimodality in Exp 2*

Model	λ	Bayes factor
Combined	$\lambda \sim \text{Uniform}(0, 1)$	-
Bimodal	$\lambda \sim \{0, 1\}$	6.27×10^{13}

1 which appeared uniform (Fig. 7 bottom center).

If responses in the “Unbiased” condition were sufficiently bimodal, the truthfulness-only and relevance-only models would provide the best explanation for individual participants’ response patterns: any individual could be modeled as *either* truth- or relevance-focused. Our finding that the “Combined” model is necessary to explain condition-level responses (Table 5) would be explained by population heterogeneity rather than individual participants blending the two utilities. In contrast, if the “Unbiased” condition was *not* strongly bimodal, this suggests that—even in our two-alternative forced-choice paradigm—*individuals* implement the “Combined” model and make graded tradeoffs between these two utilities.

To test for this bimodality, we fit two different condition-level models. Both allowed λ to vary by participant, but the *bimodal* model forced $\lambda \sim \{0, 1\}$ while the *combined* model allowed $\lambda \sim \text{Uniform}(0, 1)$. In each model, we fit a single β_S and β_L parameter for the population. The models were otherwise identical to those used in Experiment 2. Because the models now contain 80 parameters (78 participant-level λ parameters, β_S and β_L) we were not able to use the same grid search methodology to do a model comparison. We instead used annealed importance sampling (Grosse et al., 2016) to obtain likelihoods for each model. We ran MCMC chains with 100,000 samples, averaged the likelihood for each model across 50 such chains, and then used Bayes Factors to compare them (Table D2).

We found strong evidence in favor of the more flexible “Combined” model allowing $\lambda \sim \text{Uniform}(0, 1)$. Even in an experimental setting encouraging separation of the two speaker models, the “Combined” model still provides a better explanation for participant responses than the component models alone. *Individual* participants still made graded tradeoffs between truthfulness and relevance.

Appendix E

Experiment 3

In addition to the two experiments described in the main text, we pre-registered and ran a third experiment intended to test the hypothesis that *uncertainty* over the listener’s decision context would bias participants towards truthfulness.¹⁹ We followed the same endorsement paradigm and used the same trials as Experiment 2, and placed all participants in the “Unbiased” condition.

We then used a between participant manipulation to vary participants’ uncertainty in three conditions: “no” uncertainty, “moderate” uncertainty, and “high” uncertainty. Participants in the “no uncertainty” condition were told that tourists always visit a single mushroom patch, and—as in Experiments 1 and 2—each trial showed a patch with visible mushrooms. Participants in the “moderate uncertainty” condition were told that tourists always visit 2 patches (and take one mushroom from each). Each trial showed one known patch with visible mushrooms, and one unknown patch where the mushrooms are not visible. Finally, participants in the “high uncertainty” condition were told that tourists always visit 4 patches. Each trial showed one known patch and three unknown patches (Fig. E1).

Our key prediction was that increasing uncertainty (i.e. more unknown patches) would make participants less willing to lie (i.e. the inferred λ parameter would decrease as the uncertainty increased). However, our manipulation proved ineffective: participants in the “moderate” and “high” uncertainty conditions reported confusion about the “unknown” patches. All three conditions largely replicated the “Unbiased” condition from Experiment 2 (Fig. E2).

Methods Summary

We recruited 299 participants using Prolific (www.prolific.co), using the same qualifications and compensation structure. 22 participants failed the comprehension check and 63 failed attention checks during the experiment, leaving a final sample size of 214. On average, participants spent about 16 minutes on the experiment ($M=16.01$, $SD=6.82$) and earned an hourly wage of \$14.42.

Unfortunately, participant responses on the exit survey indicated confusion about the

¹⁹ Pre-registration: https://aspredicted.org/ZHC_MZQ

presence of the additional mushroom patches in “Moderate” and “High” uncertainty conditions (Fig. E1), e.g. “I wasn’t really sure about what the mystery patch meant or what relevance that had.”

Results Summary

MLE estimates are provided in Table E1. Our pre-registered analysis followed a similar procedure as our manipulation checks in Experiment 1 and 2. We used a model comparison to test whether the ordering of the λ parameter matches our predictions:

$\lambda_{\text{No Uncertainty}} > \lambda_{\text{Moderate Uncertainty}} > \lambda_{\text{High Uncertainty}}$. We again obtain marginal likelihoods for a model with (1) a single λ parameter, (2) λ parameters for each condition, (3) ordinal λ parameters for each condition $\lambda_{\text{No Uncertainty}} > \lambda_{\text{Moderate Uncertainty}} > \lambda_{\text{High Uncertainty}}$. We use a gridsearch over the same range of β parameters: $\beta_S \in [1, 10]$ and $\beta_L \in [1, 10]$. We find no evidence in favor of the ordinal model either case: for ordinal-vs-single, the $\text{BF} = 5.58e - 12$; for the ordinal-vs-independent, the $\text{BF} = 6.03e - 25$.

Figure E1

Example trial in the “High Uncertainty” condition.



Note. We hypothesized that the presence of additional “unknown” patches would bias participants towards truthfulness. However, participants reported confusion about the “unknown” patches and our results across conditions largely replicated Experiment 2’s Unbiased condition.

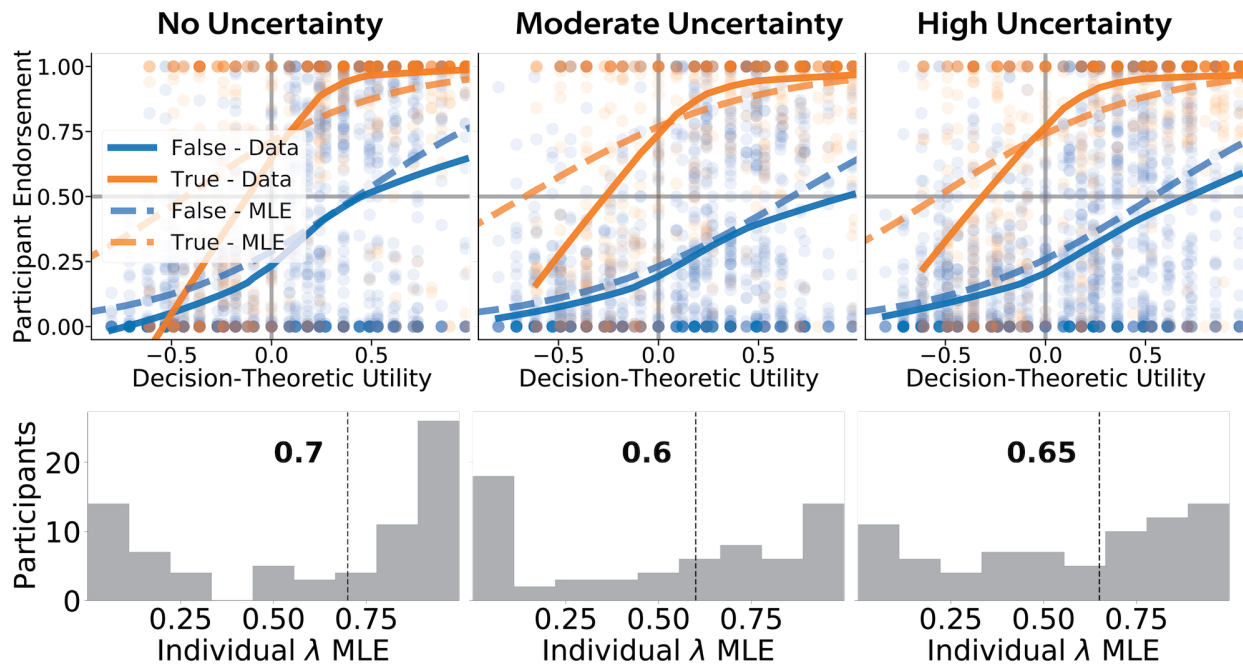
Table E1*Maximum likelihood estimates for Experiment 3.*

Uncertainty	N	Model	Maximum Likelihood			
			λ	β_S	β_L	Log LH
“None”	74	Belief	-	1	-	-14006
		Action	-	2	1	-13954
		Comb.	.70	3	1	-13437
“Moderate”	64	Belief	-	1	-	-11712
		Action	-	1	1	-12081
		Comb.	.60	3	1	-11444
“High”	76	Belief	-	1	-	-13965
		Action	-	1	2	-14297
		Comb.	.65	3	1	-13606

Note. Maximum likelihood estimates for different models and conditions in Experiment 3. Our “Uncertainty” manipulation had minimal effect on participant responses, likely due to reported confusion over the experimental user interface.

Figure E2

Results from Experiment 3.



Note. Top: response patterns across conditions. Scatterplots show individual responses, solid lines are nonparametric (locally-weighted) regressions summarizing the data, and dotted lines are MLE predictions. Participants displayed similar patterns across all three conditions. The most notable difference was a greater willingness to endorse true but negative decision-theoretic utterances under “Moderate” and “High” uncertainty (note that the yellow line’s Y-intercept is positive in both of these conditions). Bottom: MLE estimates for individual participants (histograms) and conditions (dashed lines and bolded text). Under “No” uncertainty (left), a substantial fraction of participants are nearly-pure “Relevance” speakers ($\lambda \approx 1$). Under “Moderate” and “High” uncertainty, fewer participants are pure “Relevance” speakers; however, this only results in a small shift in condition-level MLE estimates.