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What you will get out of this tutorial

- Our view of what Bayesian models have to offer cognitive science
- In-depth examples of basic and advanced models: how the math works & what it buys you
- A sense for how to go about making your own Bayesian models
- Some (not extensive) comparison to other approaches
- Opportunities to ask questions

Resources...

- “Bayesian models of cognition” chapter in *Handbook of Computational Psychology*
- Tom’s Bayesian reading list:
 - <http://cocosci.berkeley.edu/tom/bayes.html>
 - tutorial slides will be posted there!
- *Trends in Cognitive Sciences* special issue on probabilistic models of cognition (vol. 10, iss. 7)
- IPAM graduate summer school on probabilistic models of cognition (with videos!)

Outline

- Morning
 - Introduction: Why Bayes? (Josh)
 - Basics of Bayesian inference (Josh)
 - How to build a Bayesian cognitive model (Tom)
- Afternoon
 - Hierarchical Bayesian models and learning structured representations (Charles)
 - Monte Carlo methods and nonparametric Bayesian models (Tom)

Why probabilistic models of cognition?

The big question

How does the mind get so much out of so little?

How do we make inferences, generalizations, models, theories and decisions about the world from impoverished (sparse, incomplete, noisy) data?

“The problem of induction”

Visual perception



X =	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49
Y																
58	171	169	167	167	166	165	166	164	167	171	171	174	174	175	173	171
57	168	168	168	167	166	167	167	165	169	168	174	176	175	175	175	172
56	168	167	167	165	166	166	167	167	168	170	178	177	176	174	174	173
55	168	168	165	169	167	168	167	165	168	175	177	177	175	175	172	171
54	169	170	167	169	169	168	163	166	172	169	174	173	175	178	173	173
53	171	169	170	168	169	168	169	168	168	170	175	173	175	177	178	176
52	172	171	170	168	169	169	167	168	173	172	173	177	174	175	178	176
51	172	174	171	170	166	168	167	168	172	172	172	177	179	172	175	175
50	171	167	176	169	170	169	168	169	171	172	174	174	173	173	174	178
49	174	172	173	173	173	174	171	171	172	174	172	172	172	169	173	173
48	173	173	173	176	178	172	171	174	174	173	175	175	175	173	173	171
47	173	175	178	173	173	171	171	175	175	177	178	175	174	173	175	178
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45	173	175	173	174	172	173	174	175	174	171	173	174	175	174	172	171
44	177	174	175	175	172	171	172	176	172	173	172	172	173	170	170	175
43	173	171	174	168	176	172	173	173	173	174	171	174	175	173	174	174
42	175	173	171	172	170	171	176	175	178	172	174	175	175	175	175	172
41	181	179	177	172	170	170	169	179	175	174	175	174	172	175	174	175
40	188	184	179	178	176	176	176	174	172	178	172	174	173	172	174	173
39	195	191	188	186	185	183	180	177	178	175	174	176	175	174	176	176
38	200	199	197	193	190	187	185	180	176	175	180	177	175	175	176	177
37	202	202	199	202	199	194	187	180	175	179	177	176	174	175	176	173

(Marr)

Learning the meanings of words



“horse”



“horse”



“horse”

The objects of planet Gazoob

“tufa”



“tufa”

“tufa”

The big question

How does the mind get so much out of so little?

- Perceiving the world from sense data
- Learning about kinds of objects and their properties
- Learning and interpreting the meanings of words, phrases, and sentences
- Inferring causal relations
- Inferring the mental states of other people (beliefs, desires, preferences) from observing their actions
- Learning social structures, conventions, and rules

The goal: A general-purpose computational framework for understanding of how people make these inferences, and how they can be successful.

The problems of induction

1. How does abstract knowledge guide inductive learning, inference, and decision-making from sparse, noisy or ambiguous data?
2. What is the form and content of our abstract knowledge of the world?
3. What are the origins of our abstract knowledge? To what extent can it be acquired from experience?
4. How do our mental models grow over a lifetime, balancing simplicity versus data fit (Occam), accommodation versus assimilation (Piaget)?
5. How can learning and inference proceed efficiently and accurately, even in the presence of complex hypothesis spaces?

A toolkit for reverse-engineering induction

1. Bayesian inference in probabilistic generative models
2. Probabilities defined over structured representations: graphs, grammars, predicate logic, schemas
3. Hierarchical probabilistic models, with inference at all levels of abstraction
4. Models of unbounded complexity (“nonparametric Bayes” or “infinite models”), which can grow in complexity or change form as observed data dictate.
5. Approximate methods of learning and inference, such as belief propagation, expectation-maximization (EM), Markov chain Monte Carlo (MCMC), and sequential Monte Carlo (particle filtering).

Grammar G



$$P(S | G)$$

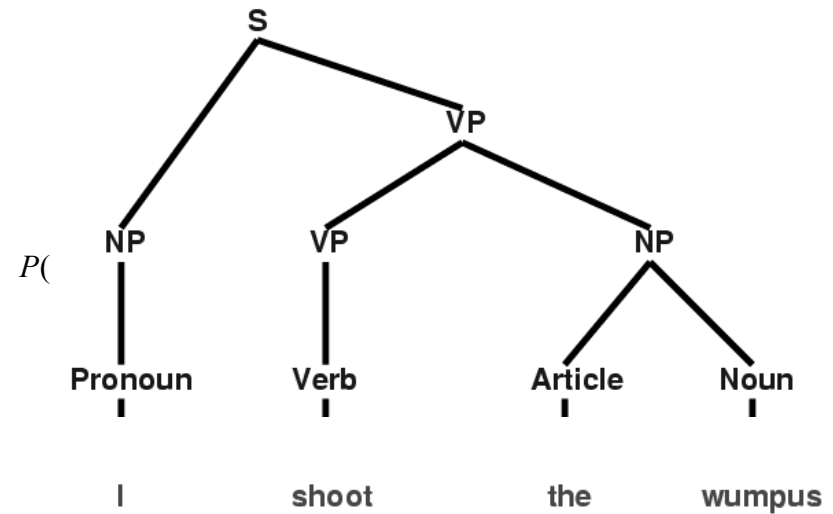
Phrase structure S



$$P(U | S)$$

Utterance U

$S \rightarrow NP VP$
 $NP \rightarrow Det [Adj] Noun [RelClause]$
 $RelClause \rightarrow [Rel] NP V$
 $VP \rightarrow VP NP$
 $VP \rightarrow Verb$



$$P(S | U, G) \sim P(U | S) \times P(S | G)$$

Bottom-up

Top-down

“Universal Grammar”

↓ $P(\text{grammar} \mid \text{UG})$

Grammar

↓ $P(\text{phrase structure} \mid \text{grammar})$

Phrase structure

↓ $P(\text{utterance} \mid \text{phrase structure})$

Utterance

↓ $P(\text{speech} \mid \text{utterance})$

Speech signal

Hierarchical phrase structure grammars (e.g., CFG, HPSG, TAG)

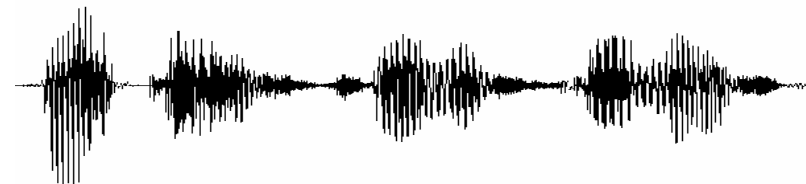
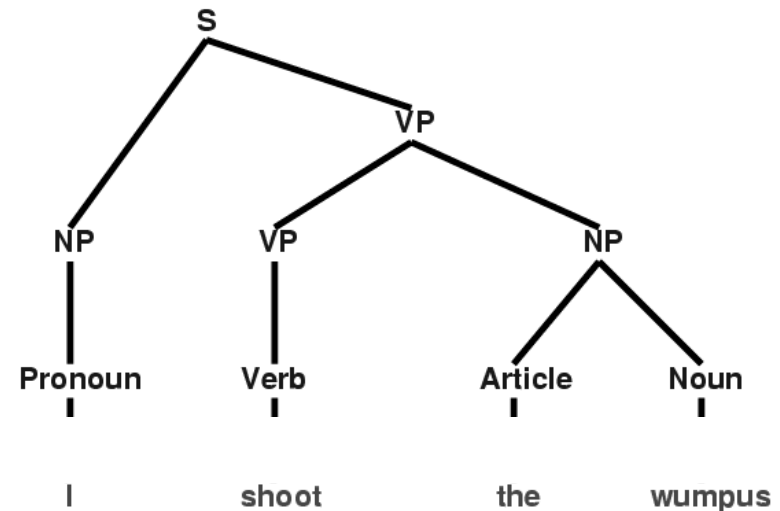
$S \rightarrow NP VP$

$NP \rightarrow Det [Adj] Noun [RelClause]$

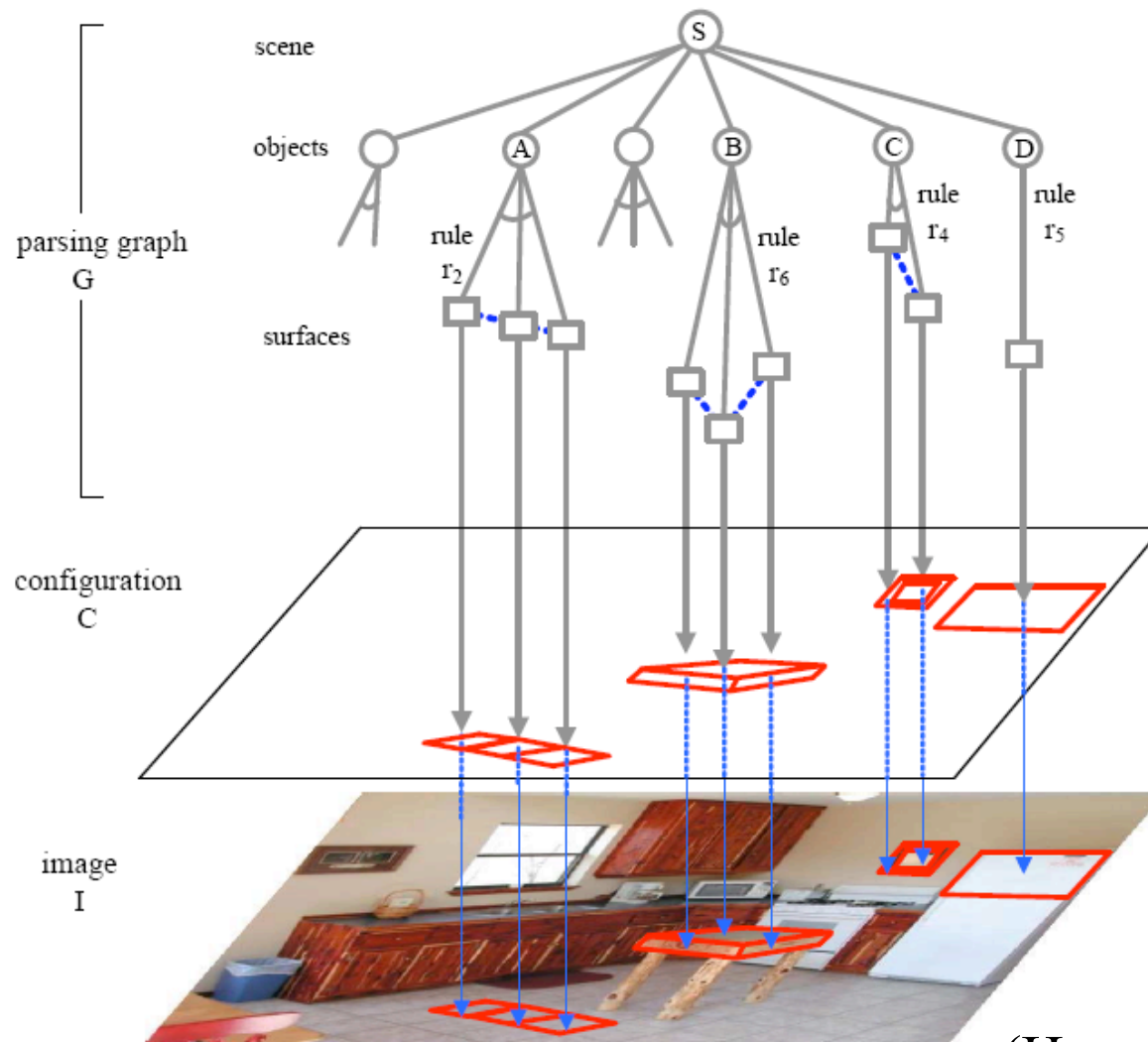
$RelClause \rightarrow [Rel] NP V$

$VP \rightarrow VP NP$

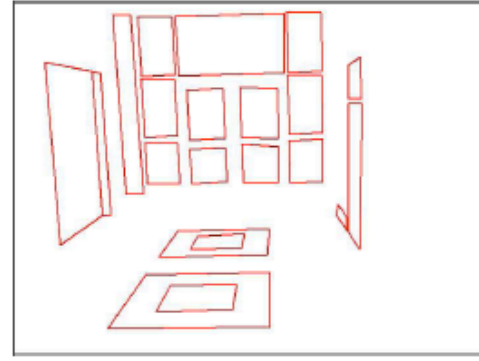
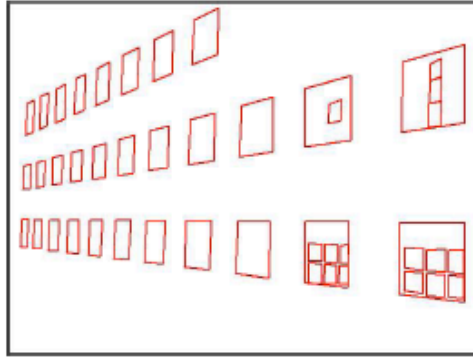
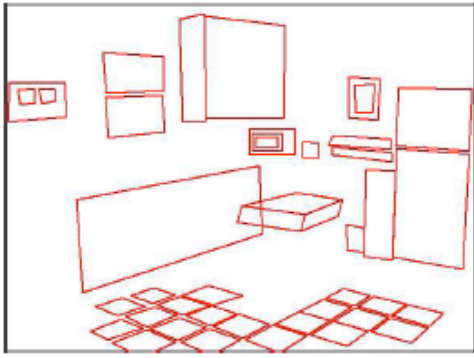
$VP \rightarrow Verb$



Vision as probabilistic parsing



(Han and Zhu, 2006)

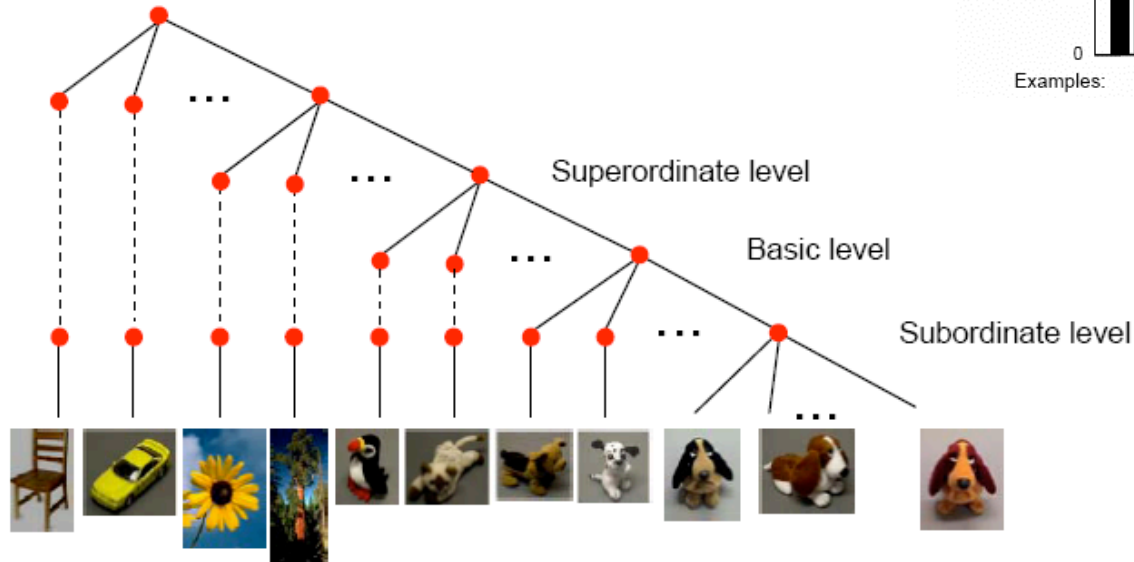


Learning word meanings

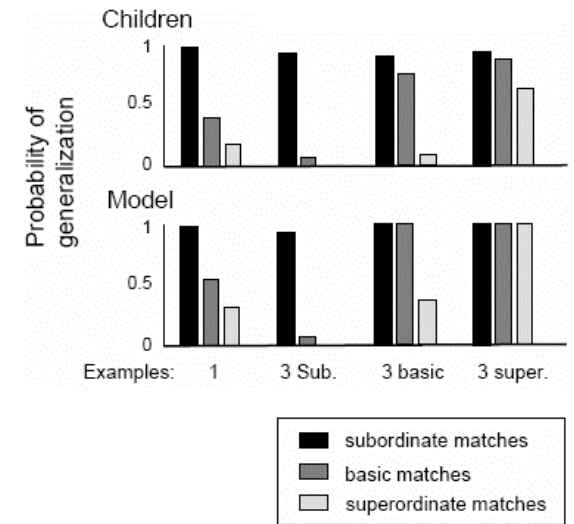
Principles

Whole-object principle
Shape bias
Taxonomic principle
Contrast principle
Basic-level bias

Structure



Data



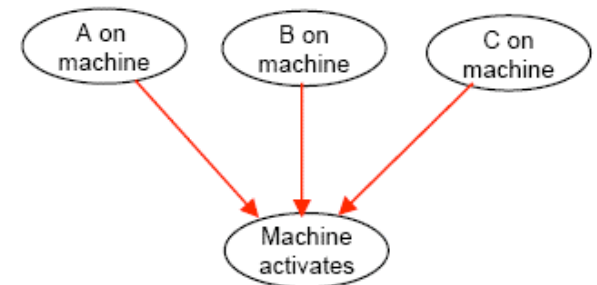
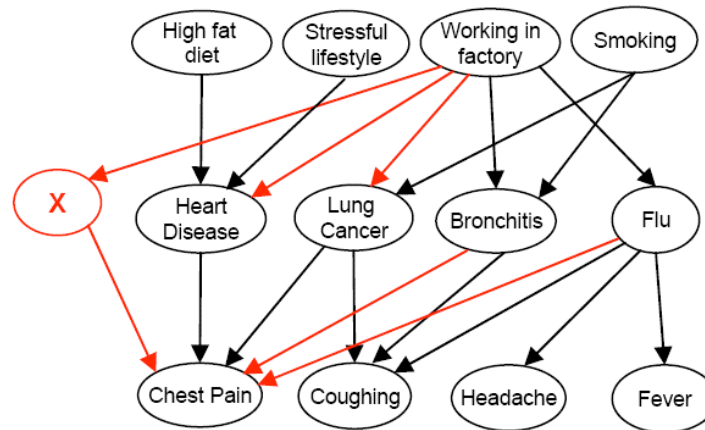
Causal learning and reasoning

Principles

Classes: {R, D, S} (Risks, Diseases, Symptoms)
Causal laws: $R \rightarrow D$, $D \rightarrow S$

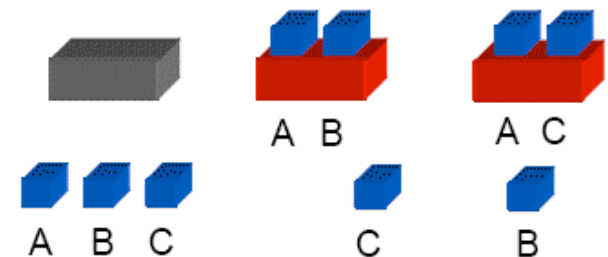
Objects can activate Machines
Activation requires contact
Machines are (near) deterministic

Structure

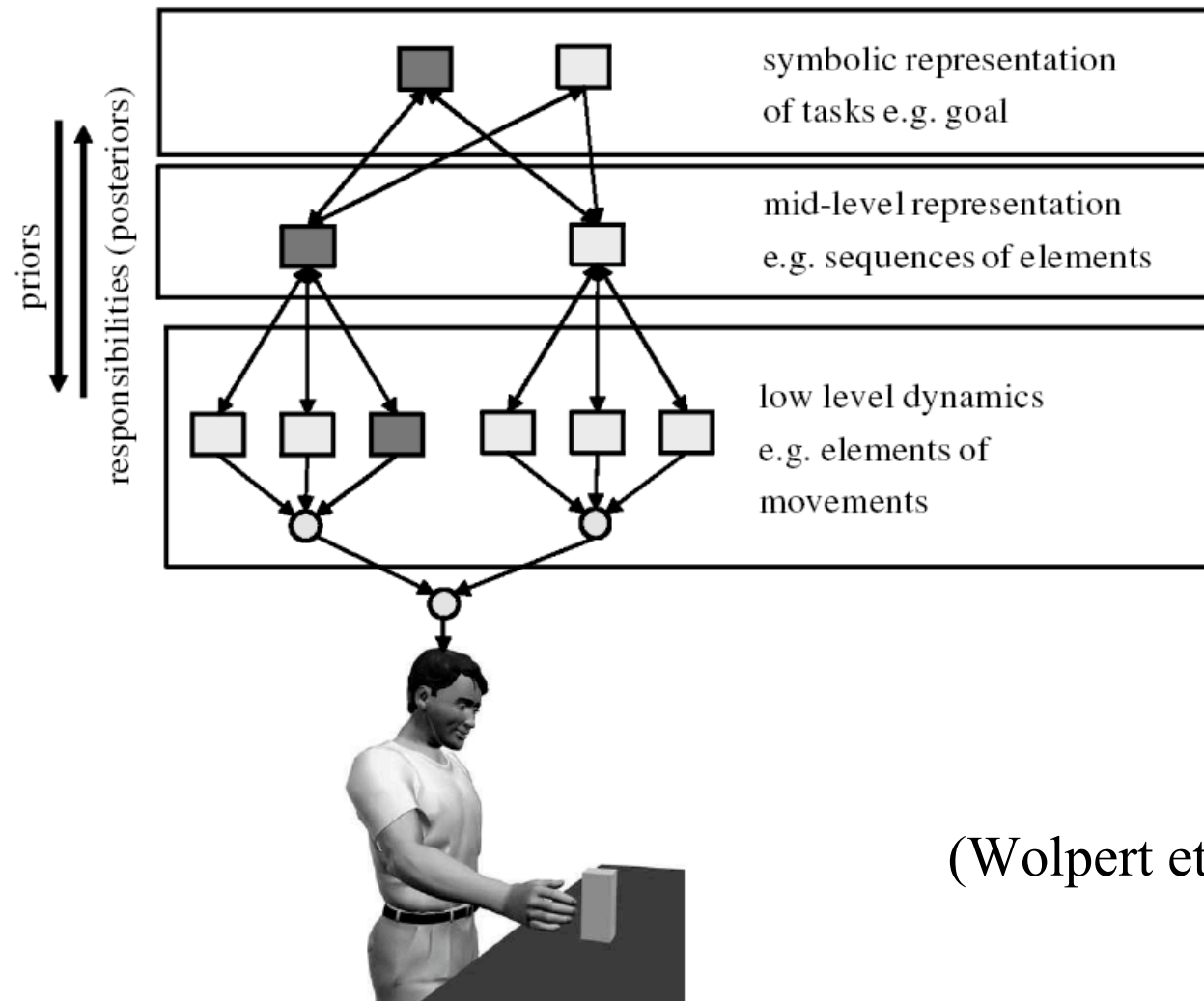


Data

Patient 1: Stressful lifestyle
Chest Pain
 Patient 2: Smoking
Coughing
 Patient 3: Working in factory
Chest Pain
 ...



Goal-directed action (production and comprehension)



(Wolpert et al., 2003)

Why Bayesian models of cognition?

- A framework for understanding how the mind can solve fundamental problems of induction.
- Strong, principled quantitative models of human cognition.
- Tools for studying people's implicit knowledge of the world.
- Beyond classic limiting dichotomies: “rules vs. statistics”, “nature vs. nurture”, “domain-general vs. domain-specific” .
- A unifying mathematical language for all of the cognitive sciences: AI, machine learning and statistics, psychology, neuroscience, philosophy, linguistics.... A bridge between engineering and “reverse-engineering”.

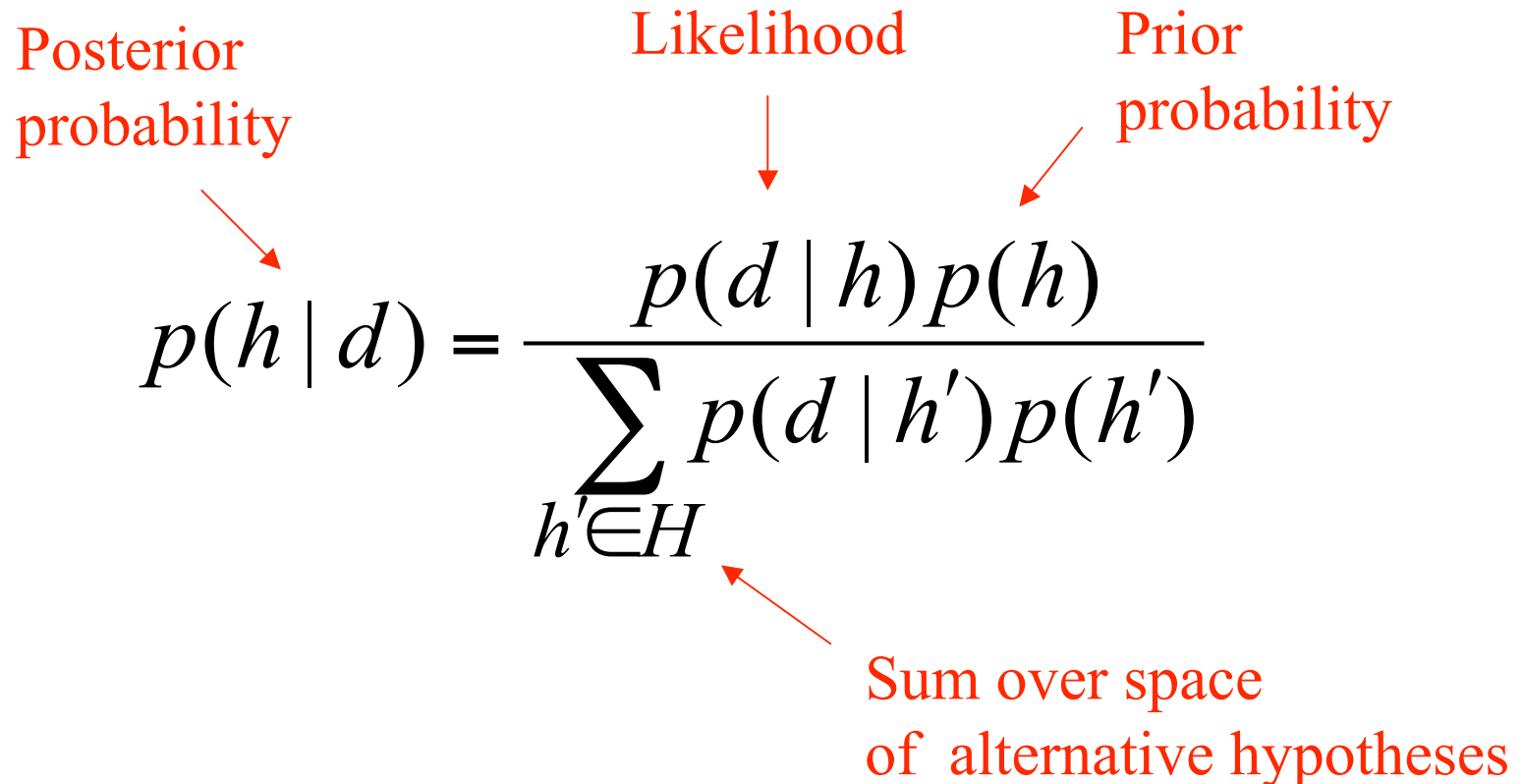
Why now? Much recent progress, in computational resources, theoretical tools, and interdisciplinary connections.

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 - Hierarchical Bayesian models & probabilistic models over structured representations (Charles)
 - Monte Carlo methods of approximate learning and inference; nonparametric Bayesian models (Tom)

Bayes' rule

For any hypothesis h and data d ,



The diagram illustrates Bayes' rule with the following components and annotations:

- Posterior probability**: Labeled in red text with an arrow pointing to the term $p(h | d)$ on the left side of the equation.
- Likelihood**: Labeled in red text with an arrow pointing to the term $p(d | h)$ in the numerator.
- Prior probability**: Labeled in red text with an arrow pointing to the term $p(h)$ in the numerator.
- Sum over space of alternative hypotheses**: Labeled in red text with an arrow pointing to the summation term $\sum_{h' \in H}$ in the denominator.

$$p(h | d) = \frac{p(d | h) p(h)}{\sum_{h' \in H} p(d | h') p(h')}$$

Bayesian inference

- Bayes' rule: $P(h | d) = \frac{P(h)P(d | h)}{\sum_{h_i} P(h_i)P(d | h_i)}$
- An example
 - Data: John is coughing
 - Some hypotheses:
 1. John has a cold
 2. John has lung cancer
 3. John has a stomach flu
 - Prior $P(h)$ favors 1 and 3 over 2
 - Likelihood $P(d|h)$ favors 1 and 2 over 3
 - Posterior $P(h|d)$ favors 1 over 2 and 3

Plan for this lecture

- Some basic aspects of Bayesian statistics
 - Comparing two hypotheses
 - Model fitting
 - Model selection
- Two (very brief) case studies in modeling human inductive learning
 - Causal learning
 - Concept learning

Coin flipping

- Comparing two hypotheses
 - data = HHTHT or HHHHH
 - compare two simple hypotheses:
 $P(H) = 0.5$ vs. $P(H) = 1.0$
- Parameter estimation (Model fitting)
 - compare many hypotheses in a parameterized family
 $P(H) = \theta$: Infer θ
- Model selection
 - compare qualitatively different hypotheses, often varying in complexity:
 $P(H) = 0.5$ vs. $P(H) = \theta$

Coin flipping

HHTHT

HHHHH

What process produced these sequences?

Comparing two hypotheses

- Contrast simple hypotheses:
 - h_1 : “fair coin”, $P(H) = 0.5$
 - h_2 : “always heads”, $P(H) = 1.0$

- Bayes’ rule:

$$P(h | d) = \frac{P(h)P(d | h)}{\sum_{h_i} P(h_i)P(d | h_i)}$$

- With two hypotheses, use odds form

Comparing two hypotheses

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{P(D | H_1)}{P(D | H_2)} \times \frac{P(H_1)}{P(H_2)}$$

D : HHTHT

H_1, H_2 : “fair coin”, “always heads”

$P(D|H_1) = 1/2^5$ $P(H_1) = ?$

$P(D|H_2) = 0$ $P(H_2) = 1-?$

Comparing two hypotheses

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{P(D | H_1)}{P(D | H_2)} \times \frac{P(H_1)}{P(H_2)}$$

D : HHTHT

H_1, H_2 : “fair coin”, “always heads”

$$P(D|H_1) = 1/2^5 \qquad P(H_1) = 999/1000$$

$$P(D|H_2) = 0 \qquad P(H_2) = 1/1000$$

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{1/32}{0} \times \frac{999}{1} = \text{infinity}$$

Comparing two hypotheses

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{P(D | H_1)}{P(D | H_2)} \times \frac{P(H_1)}{P(H_2)}$$

D : HHHHHH

H_1, H_2 : “fair coin”, “always heads”

$$P(D|H_1) = 1/2^5 \qquad P(H_1) = 999/1000$$

$$P(D|H_2) = 1 \qquad P(H_2) = 1/1000$$

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{1/32}{1} \times \frac{999}{1} \approx 30$$

Comparing two hypotheses

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{P(D | H_1)}{P(D | H_2)} \times \frac{P(H_1)}{P(H_2)}$$

D : HHHHHHHHHH

H_1, H_2 : “fair coin”, “always heads”

$$P(D|H_1) = 1/2^{10} \qquad P(H_1) = 999/1000$$

$$P(D|H_2) = 1 \qquad P(H_2) = 1/1000$$

$$\frac{P(H_1 | D)}{P(H_2 | D)} = \frac{1/1024}{1} \times \frac{999}{1} \approx 1$$

Measuring prior knowledge

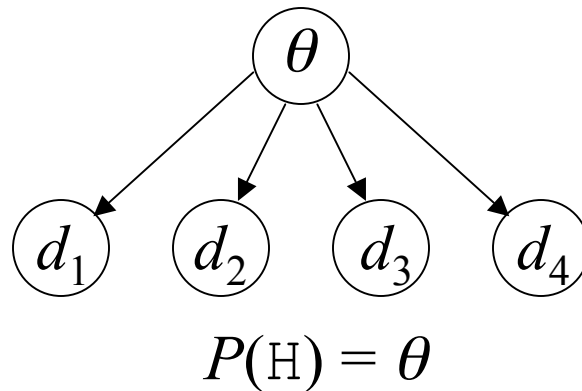
1. The fact that HHHHH looks like a “mere coincidence”, without making us suspicious that the coin is unfair, while HHHHHHHHHH does begin to make us suspicious, measures the strength of our prior belief that the coin is fair.
 - If θ is the threshold for suspicion in the posterior odds, and D^* is the shortest suspicious sequence, the prior odds for a fair coin is roughly $\theta/P(D^*|\text{“fair coin”})$.
 - If $\theta \sim 1$ and D^* is between 10 and 20 heads, prior odds are roughly between 1/1,000 and 1/1,000,000.
2. The fact that HHTHT looks representative of a fair coin, and HHHHH does not, reflects our prior knowledge about possible causal mechanisms in the world.
 - Easy to imagine how a trick all-heads coin could work: low (but not negligible) prior probability.
 - Hard to imagine how a trick “HHTHT” coin could work: extremely low (negligible) prior probability.

Coin flipping

- Basic Bayes
 - data = HHTHT or HHHHH
 - compare two hypotheses:
 $P(H) = 0.5$ vs. $P(H) = 1.0$
- Parameter estimation (Model fitting)
 - compare many hypotheses in a parameterized family
 $P(H) = \theta$: Infer θ
- Model selection
 - compare qualitatively different hypotheses, often varying in complexity:
 $P(H) = 0.5$ vs. $P(H) = \theta$

Parameter estimation

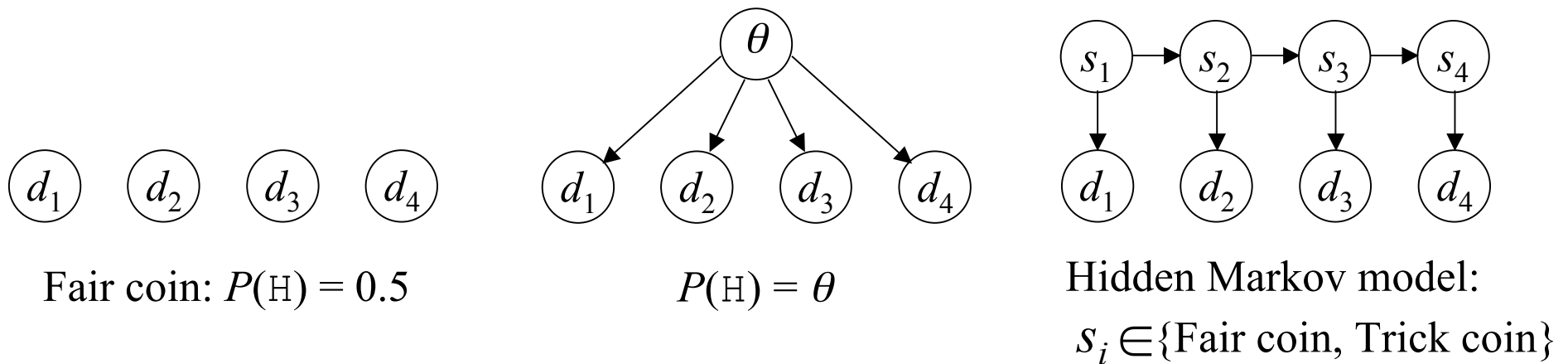
- Assume data are generated from a parameterized model:



- What is the value of θ ?
 - each value of θ is a hypothesis H
 - requires inference over infinitely many hypotheses

Model selection

- Assume hypothesis space of possible models:

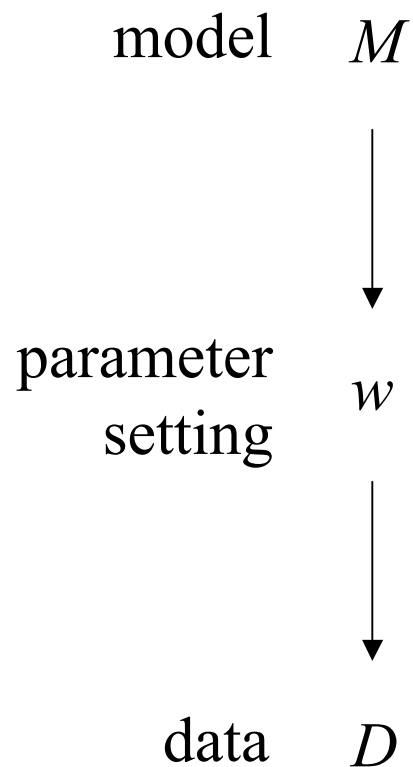


- Which model generated the data?
 - requires summing out hidden variables
 - requires some form of Occam's razor to trade off complexity with fit to the data.

Parameter estimation *vs.* Model selection across learning and development

- *Causality*: learning the strength of a relation *vs.* learning the existence and form of a relation
- *Language acquisition*: learning a speaker's accent, or frequencies of different words *vs.* learning a new tense or syntactic rule (or learning a new language, or the existence of different languages)
- *Concepts*: learning what horses look like *vs.* learning that there is a new species (or learning that there *are* species)
- *Intuitive physics*: learning the mass of an object *vs.* learning about gravity or angular momentum

A hierarchical learning framework



Parameter estimation:

$$p(w | D, M) \propto p(D | w, M) p(w | M)$$

A hierarchical learning framework

model class C



model M



parameter
setting w



data D

$$p(D | M) = \sum_w p(D | w, M) p(w | M)$$

Model selection:

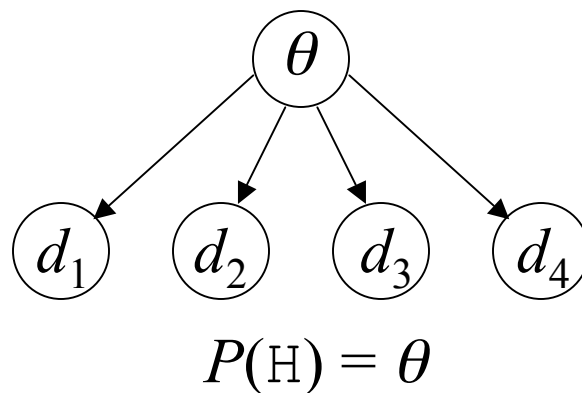
$$p(M | D, C) \propto p(D | M) p(M | C)$$

Parameter estimation:

$$p(w | D, M) \propto p(D | w, M) p(w | M)$$

Bayesian parameter estimation

- Assume data are generated from a model:



- What is the value of θ ?
 - each value of θ is a hypothesis H
 - requires inference over infinitely many hypotheses

Some intuitions

- $D = 10$ flips, with 5 heads and 5 tails.
 - $\theta = P(\text{H})$ on next flip? 50%
 - Why? $50\% = 5 / (5+5) = 5/10$.
 - Why? “The future will be like the past”
-
- Suppose we had seen 4 heads and 6 tails.
 - $P(\text{H})$ on next flip? Closer to 50% than to 40%.
 - Why? Prior knowledge.

Integrating prior knowledge and data

$$p(\theta | D) = \frac{p(D | \theta) p(\theta)}{\int p(D | \theta') p(\theta') d\theta'}$$

- Posterior distribution $P(\theta | D)$ is a probability density over $\theta = P(H)$
- Need to specify likelihood $P(D | \theta)$ and prior distribution $P(\theta)$.

Likelihood and prior

- Likelihood: **Bernoulli** distribution

$$P(D \mid \theta) = \theta^{N_H} (1-\theta)^{N_T}$$

- N_H : number of heads
- N_T : number of tails

- Prior:

$$P(\theta) \propto \quad ?$$

Some intuitions

- $D = 10$ flips, with 5 heads and 5 tails.
- $\theta = P(\text{H})$ on next flip? 50%
- Why? $50\% = 5 / (5+5) = 5/10$.
- Why? *Maximum likelihood*: $\hat{\theta} = \arg \max_{\theta} P(D | \theta)$
- Suppose we had seen 4 heads and 6 tails.
- $P(\text{H})$ on next flip? Closer to 50% than to 40%.
- Why? Prior knowledge.

A simple method of specifying priors

- Imagine some fictitious trials, reflecting a set of previous experiences
 - strategy often used with neural networks or building invariance into machine vision.
- e.g., $F = \{1000 \text{ heads}, 1000 \text{ tails}\} \sim$ strong expectation that any new coin will be fair
- In fact, this is a sensible statistical idea...

Likelihood and prior

- Likelihood: **Bernoulli(θ)** distribution

$$P(D \mid \theta) = \theta^{N_H} (1-\theta)^{N_T}$$

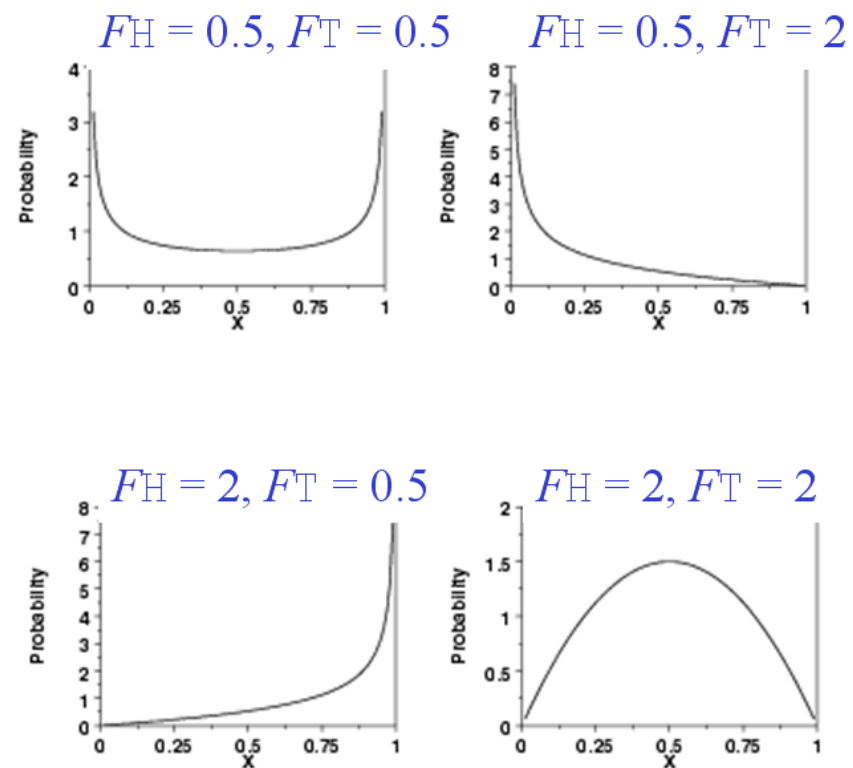
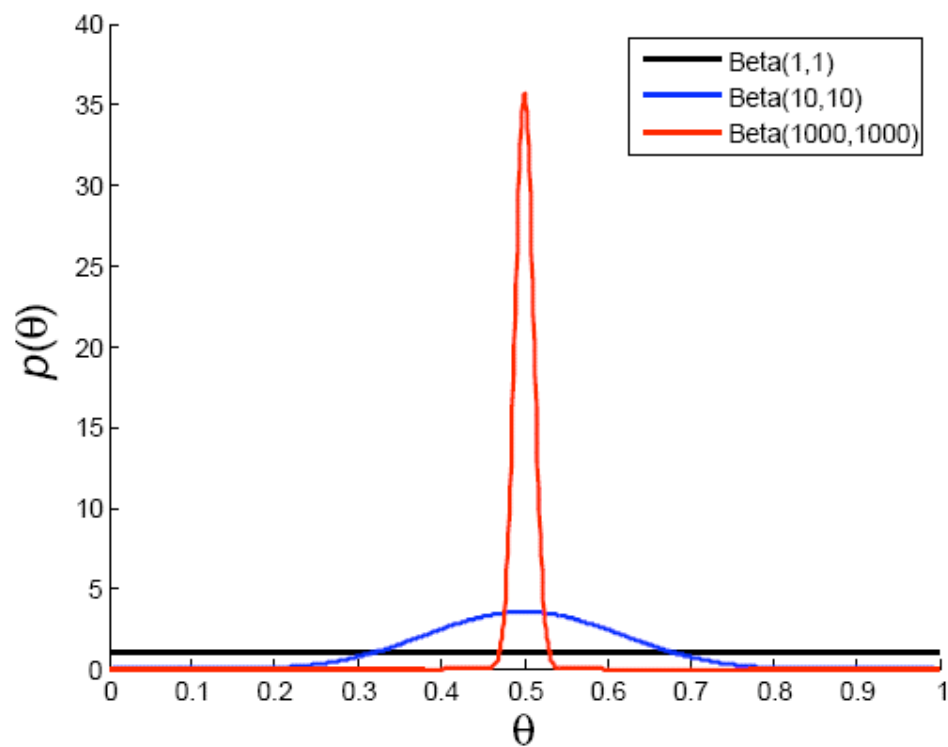
- N_H : number of heads
- N_T : number of tails

- Prior: **Beta(F_H, F_T)** distribution

$$P(\theta) \propto \theta^{F_H-1} (1-\theta)^{F_T-1}$$

- F_H : fictitious observations of heads
- F_T : fictitious observations of tails

Shape of the Beta prior



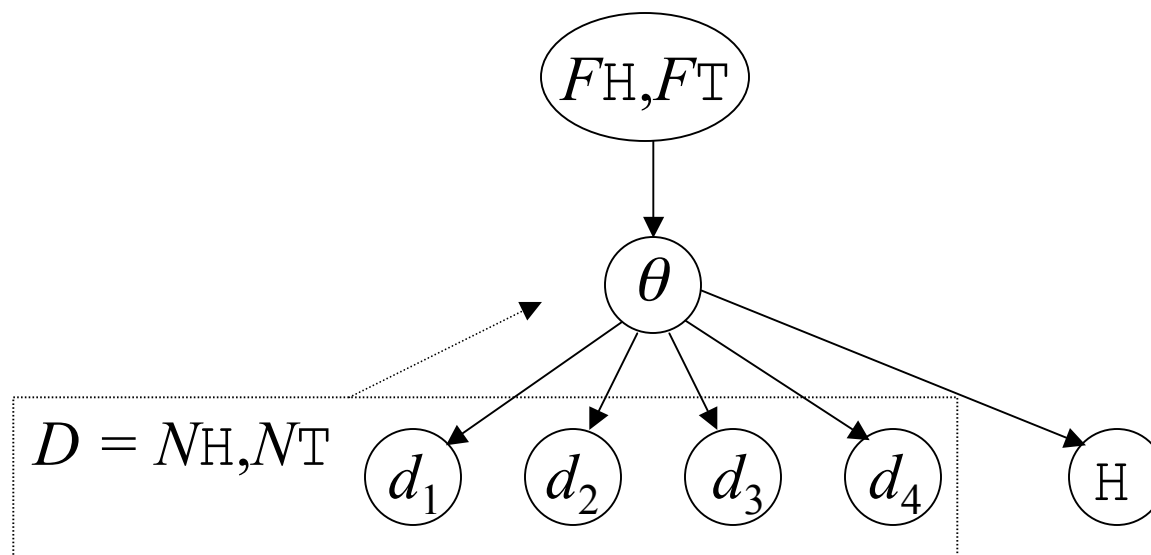
Bayesian parameter estimation

$$P(\theta \mid D) \propto P(D \mid \theta) P(\theta) = \theta^{N_H+F_H-1} (1-\theta)^{N_T+F_T-1}$$

- Posterior is $\text{Beta}(N_H+F_H, N_T+F_T)$
 - same form as prior!

Bayesian parameter estimation

$$P(\theta \mid D) \propto P(D \mid \theta) P(\theta) = \theta^{N_H + F_H - 1} (1 - \theta)^{N_T + F_T - 1}$$



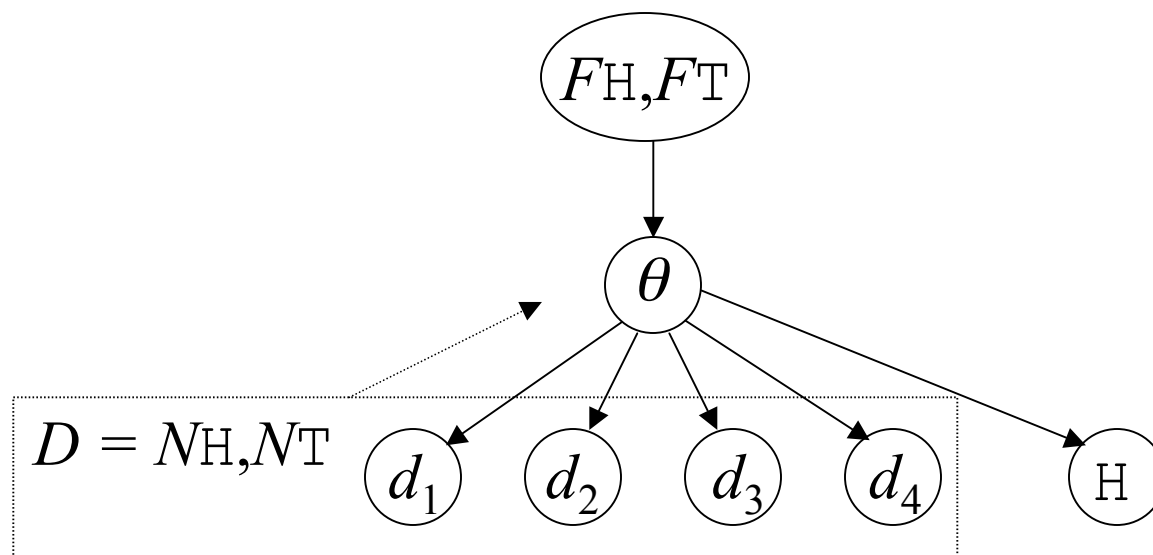
- Posterior predictive distribution:

$$P(H \mid D, F_H, F_T) = \int_0^1 P(H \mid \theta) P(\theta \mid D, F_H, F_T) d\theta$$

“hypothesis averaging”

Bayesian parameter estimation

$$P(\theta \mid D) \propto P(D \mid \theta) P(\theta) = \theta^{N_H + F_H - 1} (1 - \theta)^{N_T + F_T - 1}$$



- Posterior predictive distribution:

$$P(H \mid D, F_H, F_T) = \frac{(N_H + F_H)}{(N_H + F_H + N_T + F_T)}$$

Conjugate priors

- A prior $p(\theta)$ is *conjugate* to a likelihood function $p(D \mid \theta)$ if the posterior has the same functional form of the prior.
 - Parameter values in the prior can be thought of as a summary of “fictitious observations”.
 - Different parameter values in the prior and posterior reflect the impact of observed data.
 - Conjugate priors exist for many standard models (e.g., all exponential family models)

Some examples

- e.g., $F = \{1000 \text{ heads}, 1000 \text{ tails}\} \sim$ strong expectation that any new coin will be fair
- After seeing 4 heads, 6 tails, $P(H)$ on next flip = $1004 / (1004 + 1006) = 49.95\%$
- e.g., $F = \{3 \text{ heads}, 3 \text{ tails}\} \sim$ weak expectation that any new coin will be fair
- After seeing 4 heads, 6 tails, $P(H)$ on next flip = $7 / (7 + 9) = 43.75\%$

Prior knowledge too weak

But... flipping thumbtacks

- e.g., $F = \{4 \text{ heads}, 3 \text{ tails}\} \sim$ weak expectation that tacks are slightly biased towards heads
- After seeing 2 heads, 0 tails, $P(H)$ on next flip $= 6 / (6+3) = 67\%$
- Some prior knowledge is always necessary to avoid jumping to hasty conclusions...
- Suppose $F = \{ \}$: After seeing 1 heads, 0 tails, $P(H)$ on next flip $= 1 / (1+0) = 100\%$

Origin of prior knowledge

- Tempting answer: prior experience
- Suppose you have previously seen 2000 coin flips: 1000 heads, 1000 tails

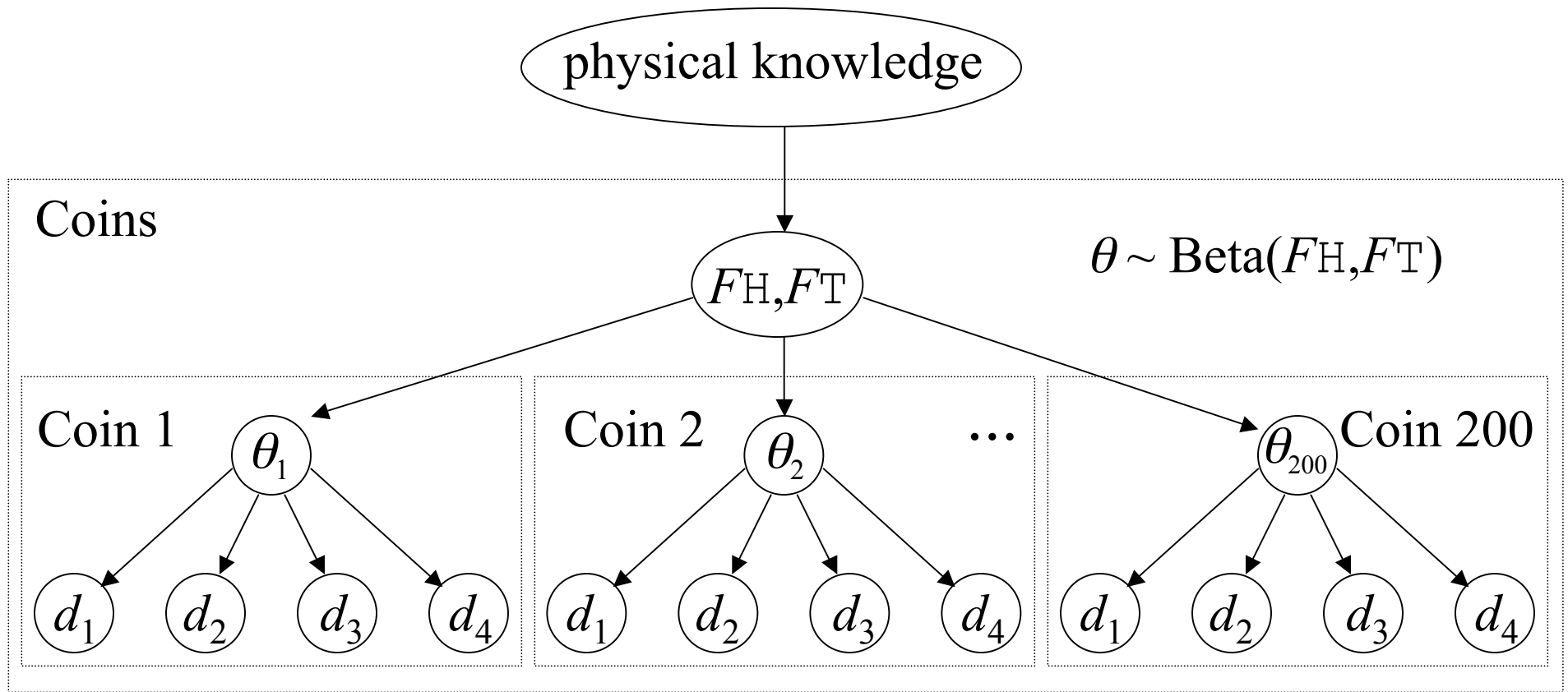
Problems with simple empiricism

- Haven't really seen 2000 coin flips, or *any* flips of a thumbtack
 - Prior knowledge is stronger than raw experience justifies
- Haven't seen exactly equal number of heads and tails
 - Prior knowledge is smoother than raw experience justifies
- Should be a difference between observing 2000 flips of a single coin versus observing 10 flips each for 200 coins, or 1 flip each for 2000 coins
 - Prior knowledge is more structured than raw experience

A simple theory

- “Coins are manufactured by a standardized procedure that is effective but not perfect, and symmetric with respect to heads and tails. Tacks are asymmetric, and manufactured to less exacting standards.”
 - Justifies generalizing from previous coins to the present coin.
 - Justifies smoother and stronger prior than raw experience alone.
 - Explains why seeing 10 flips each for 200 coins is more valuable than seeing 2000 flips of one coin.

A hierarchical Bayesian model



- Qualitative physical knowledge (symmetry) can influence estimates of continuous parameters (F_H, F_T).
- Explains why 10 flips of 200 coins are better than 2000 flips of a single coin: more informative about F_H, F_T .

Summary: Bayesian parameter estimation

- Learning the parameters of a generative model as Bayesian inference.
- Prediction by Bayesian hypothesis averaging.
- Conjugate priors
 - an elegant way to represent simple kinds of prior knowledge.
- Hierarchical Bayesian models
 - integrate knowledge across instances of a system, or different systems within a domain, to explain the origins of priors.

A hierarchical learning framework

model class C



model M



parameter
setting

w



data D

$$p(D | M) = \sum_w p(D | w, M) p(w | M)$$

Model selection:

$$p(M | D, C) \propto p(D | M) p(M | C)$$

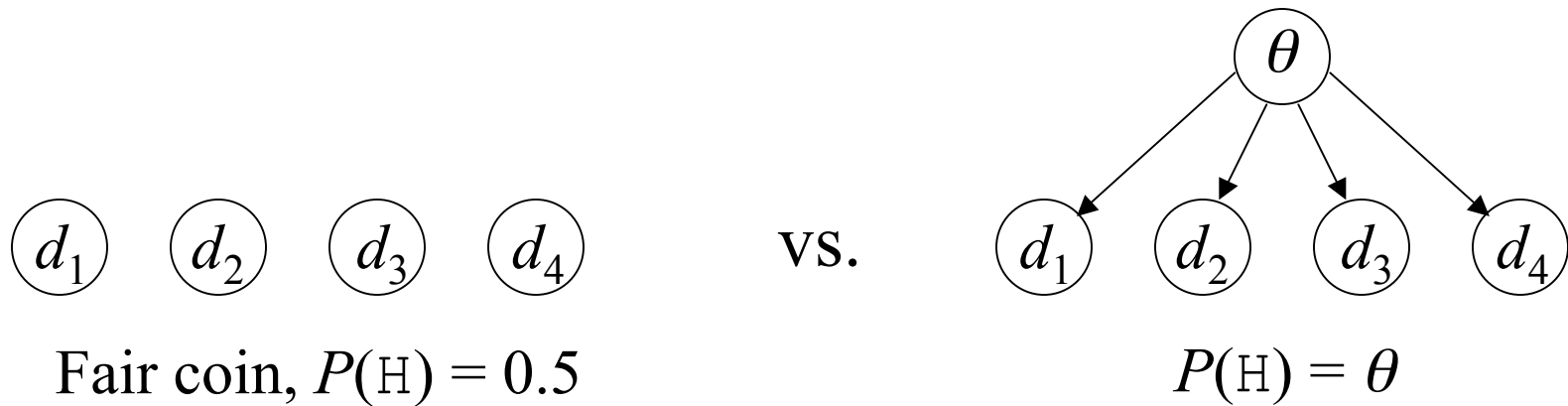
Model fitting:

$$p(w | D, M) \propto p(D | w, M) p(w | M)$$

Stability versus Flexibility

- Can all domain knowledge be represented with conjugate priors?
- Suppose you flip a coin 25 times and get all heads. *Something funny is going on ...*
- But with $F = \{1000 \text{ heads}, 1000 \text{ tails}\}$,
 $P(\text{heads})$ on next flip = $1025 / (1025 + 1000)$
 $= 50.6\%$. *Looks like nothing unusual.*
- How do we balance stability and flexibility?
 - Stability: 6 heads, 4 tails $\longrightarrow \theta \sim 0.5$
 - Flexibility: 25 heads, 0 tails $\longrightarrow \theta \sim 1$

Bayesian model selection



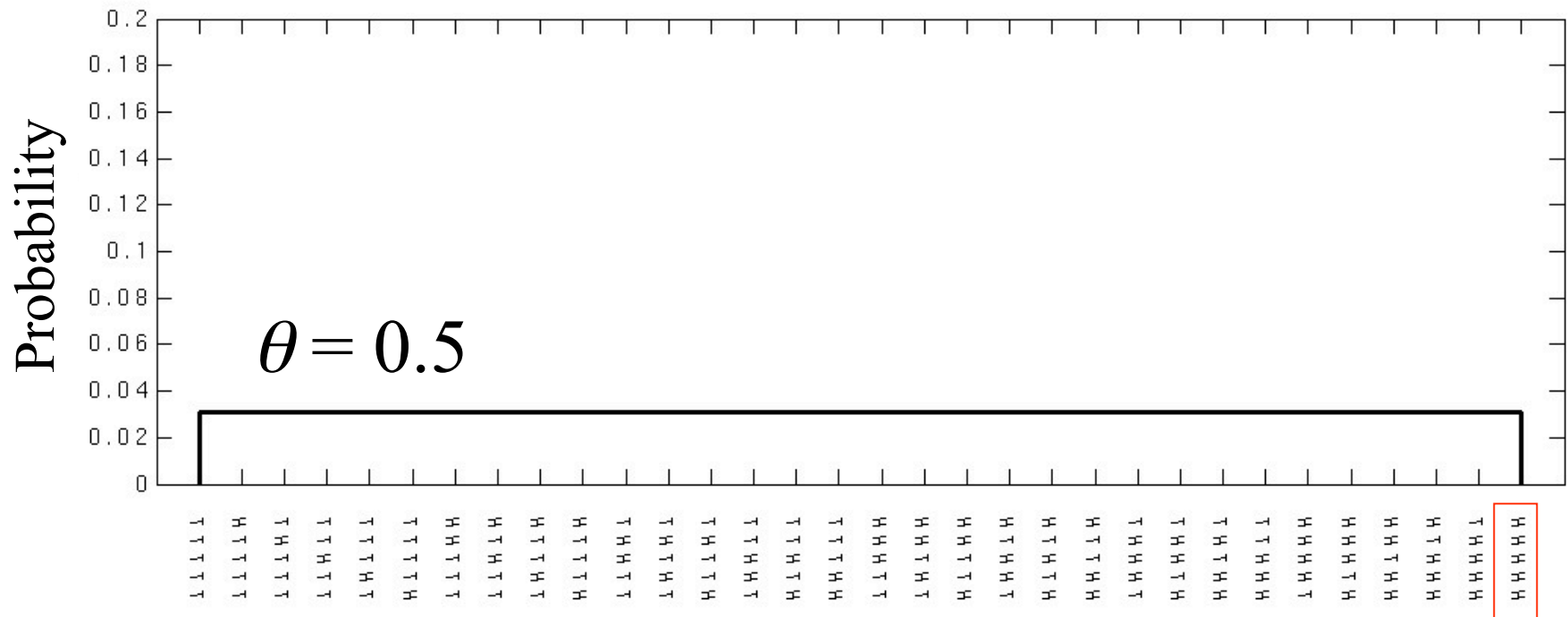
- Which provides a better account of the data: the simple hypothesis of a fair coin, or the complex hypothesis that $P(H) = \theta$?

Comparing simple and complex hypotheses

- $P(H) = \theta$ is more complex than $P(H) = 0.5$ in two ways:
 - $P(H) = 0.5$ is a special case of $P(H) = \theta$
 - for any observed sequence D , we can choose θ such that D is more probable than if $P(H) = 0.5$

Comparing simple and complex hypotheses

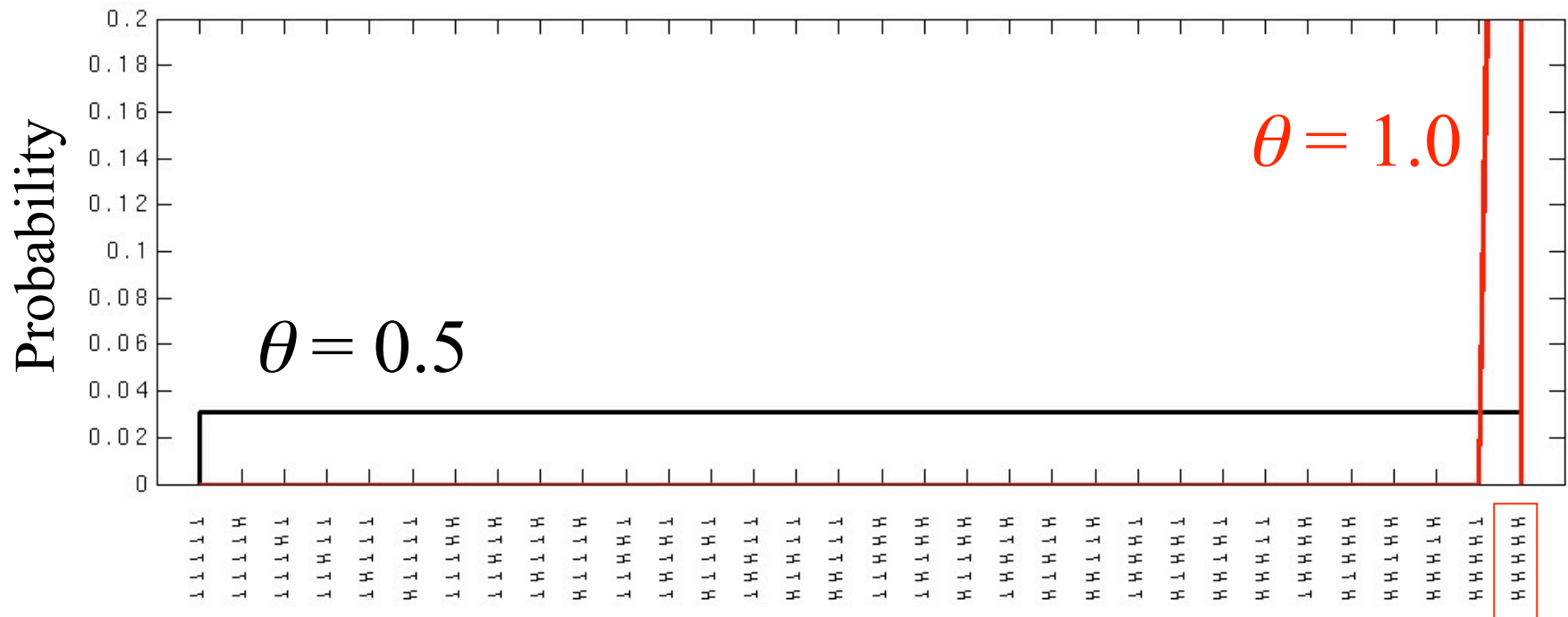
$$P(D \mid \theta) = \theta^n (1 - \theta)^{N-n}$$



$$D = \text{HHHHH}$$

Comparing simple and complex hypotheses

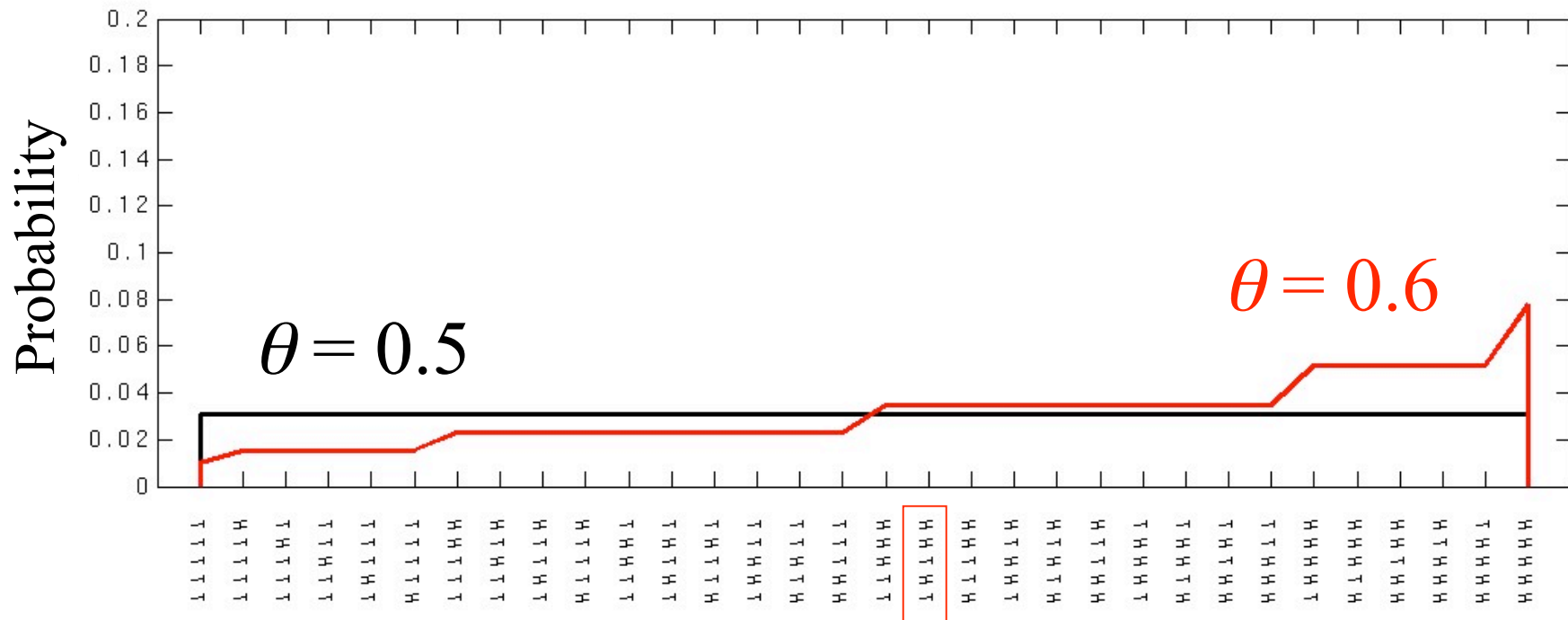
$$P(D \mid \theta) = \theta^n (1 - \theta)^{N-n}$$



$$D = \text{HHHHH}$$

Comparing simple and complex hypotheses

$$P(D \mid \theta) = \theta^n (1 - \theta)^{N-n}$$



$$D = \text{HHTHT}$$

Comparing simple and complex hypotheses

- $P(H) = \theta$ is more complex than $P(H) = 0.5$ in two ways:
 - $P(H) = 0.5$ is a special case of $P(H) = \theta$
 - for any observed sequence X , we can choose θ such that X is more probable than if $P(H) = 0.5$
- How can we deal with this?
 - Some version of Occam's razor?
 - Bayes: automatic version of Occam's razor follows from the “law of conservation of belief”.

Comparing simple and complex hypotheses

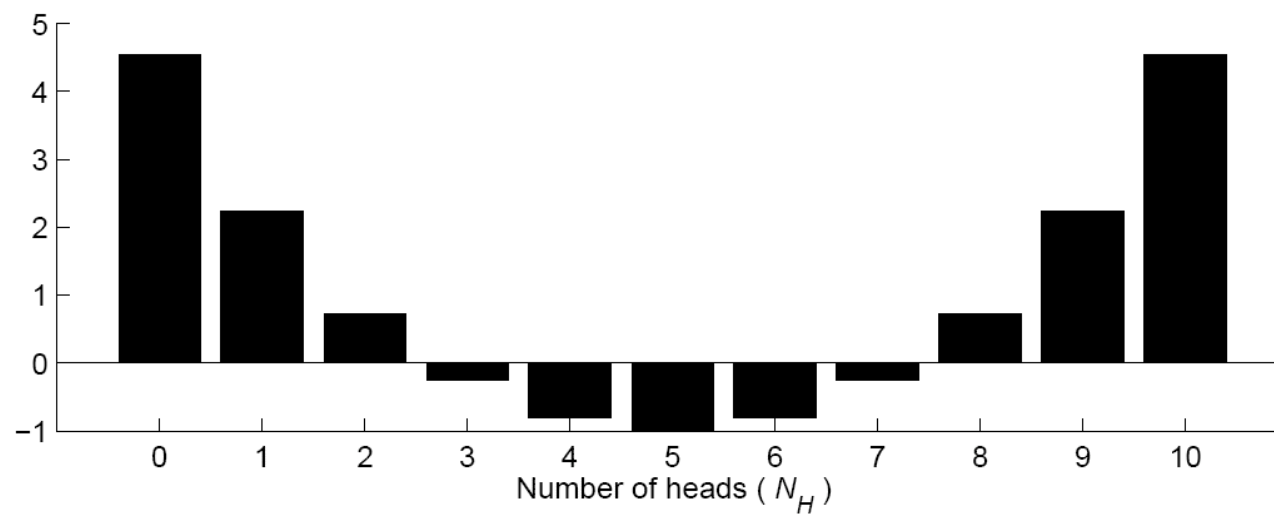
$$\frac{P(h_1|D)}{P(h_0|D)} = \frac{P(D|h_1)}{P(D|h_0)} \times \frac{P(h_1)}{P(h_0)}$$

$$P(D | h_0) = (1/2)^n (1 - 1/2)^{N-n} = 1/2^N$$

$$P(D | h_1) = \int_0^1 P(D | \theta, h_1) p(\theta | h_1) d\theta$$

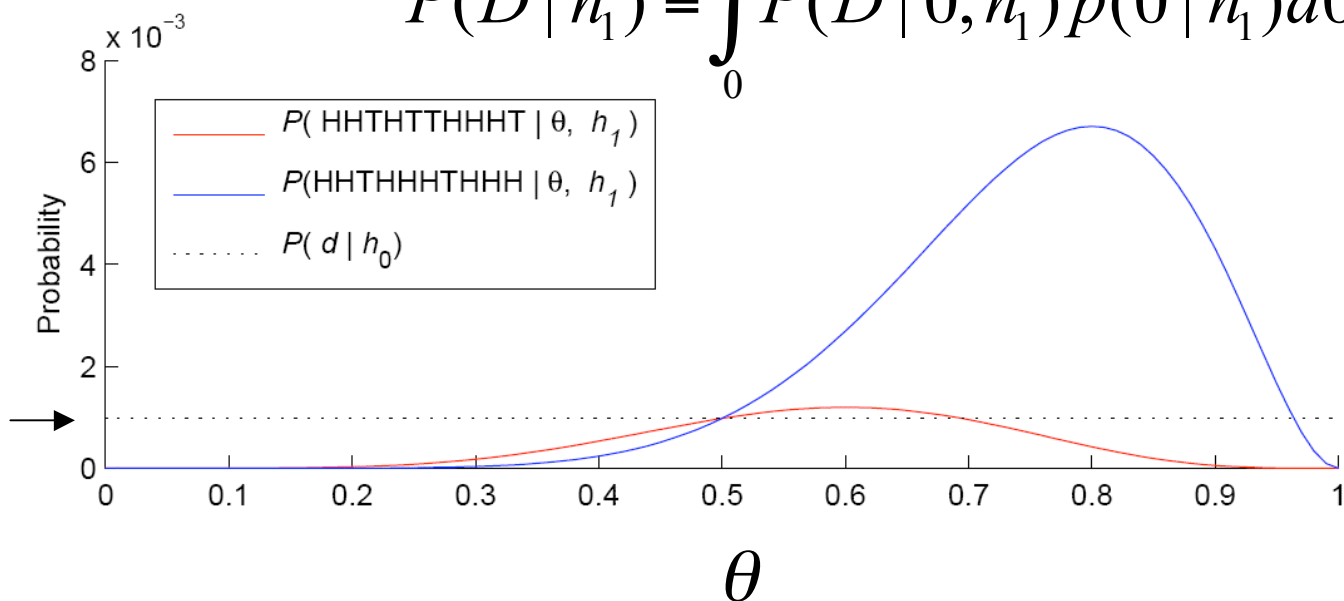
The “evidence” or “marginal likelihood”: The probability that *randomly selected* parameters from the prior would generate the data.

$$\log \frac{P(D | h_1)}{P(D | h_0)}$$



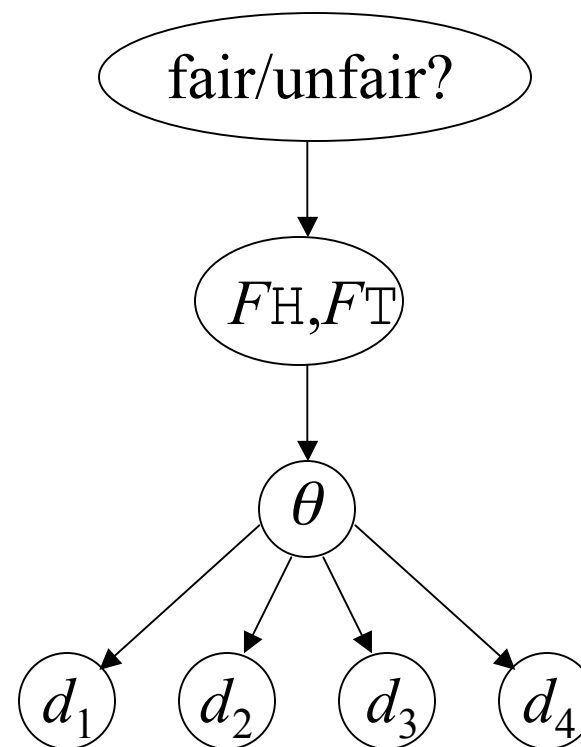
$$P(D | h_1) = \int_0^1 P(D | \theta, h_1) p(\theta | h_1) d\theta$$

$$P(D | h_0) = 1/2^N$$



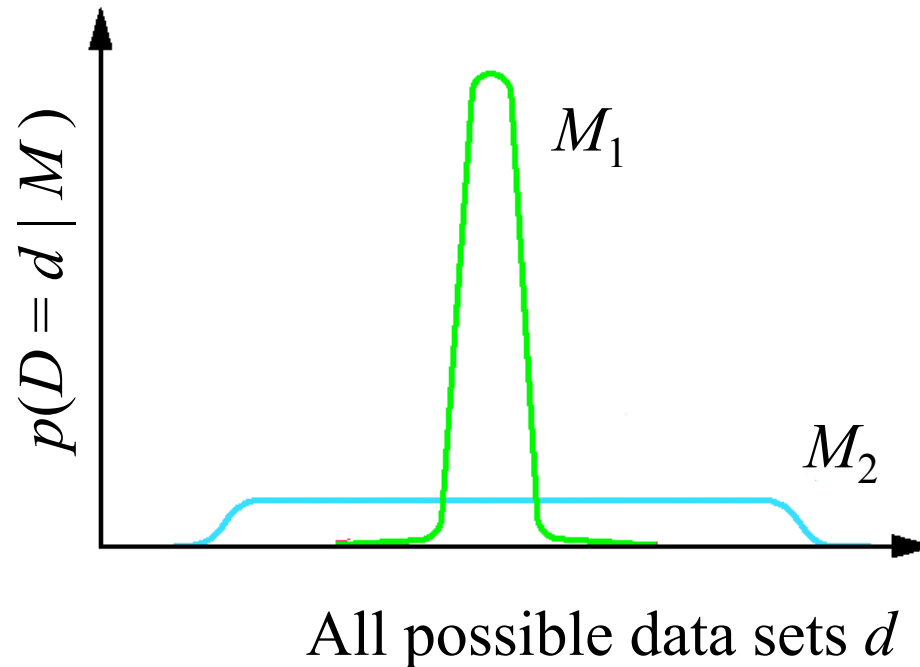
Stability versus Flexibility revisited

- Model class hypothesis: is this coin fair or unfair?
- Example probabilities:
 - $P(\text{fair}) = 0.999$
 - $P(\theta | \text{fair})$ is Beta(1000,1000)
 - $P(\theta | \text{unfair})$ is Beta(1,1)
- 25 heads in a row propagates up, affecting θ and then $P(\text{fair}|D)$



$$\frac{P(\text{fair}|25 \text{ heads})}{P(\text{unfair}|25 \text{ heads})} = \frac{P(25 \text{ heads}|\text{fair})}{P(25 \text{ heads}|\text{unfair})} \frac{P(\text{fair})}{P(\text{unfair})} \sim 0.001$$

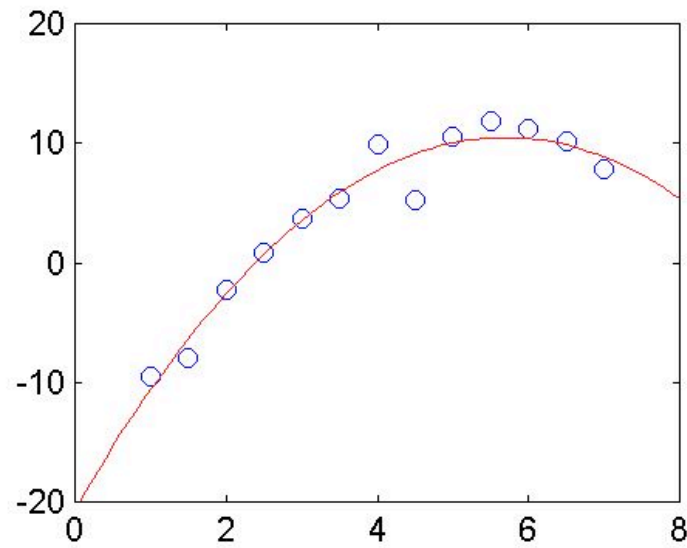
Bayesian Occam's Razor

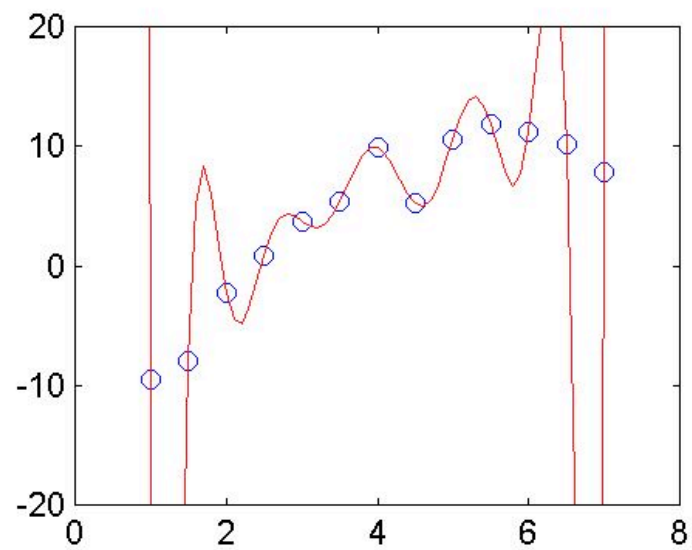
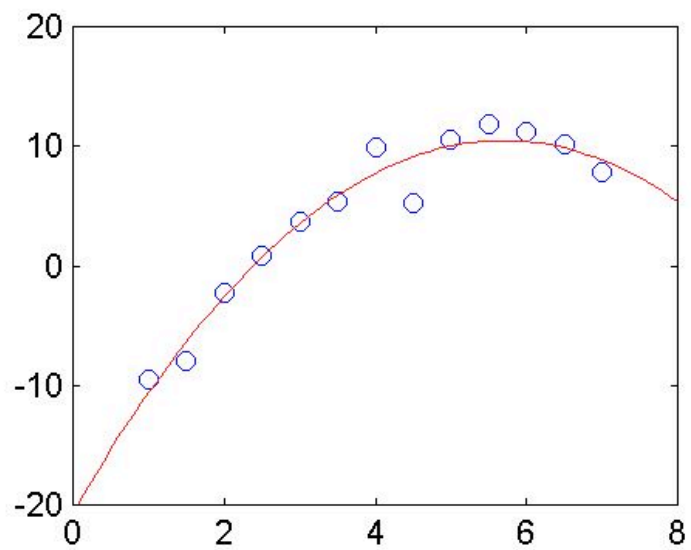
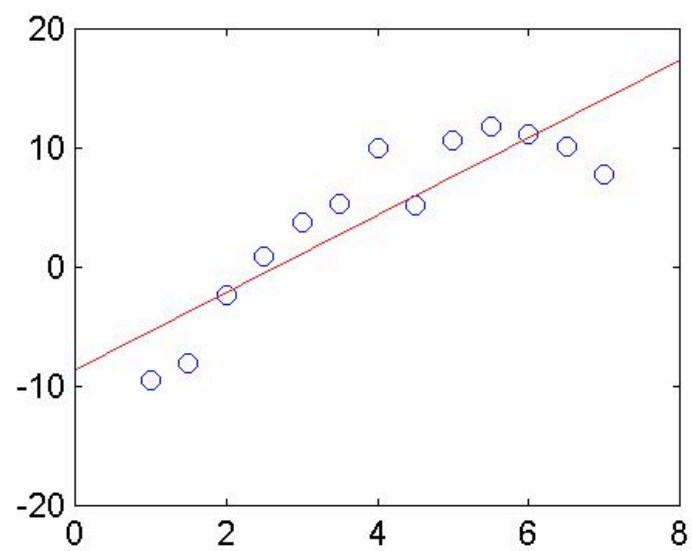
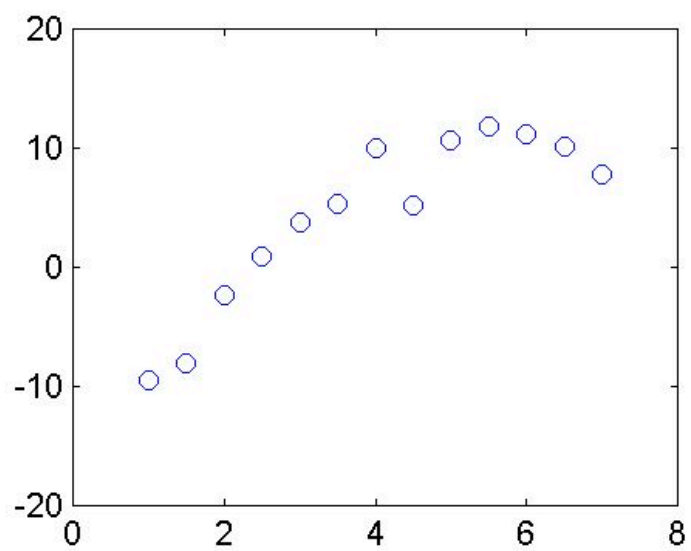


For any model M ,
$$\sum_{\text{all } d \in D} p(D = d | M) = 1$$

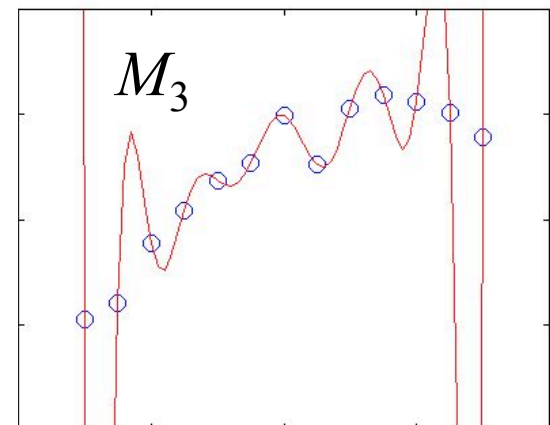
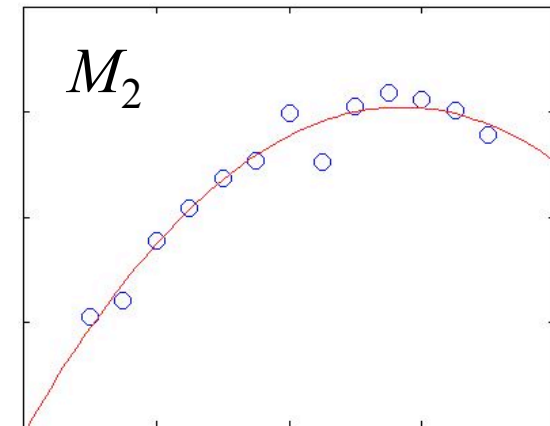
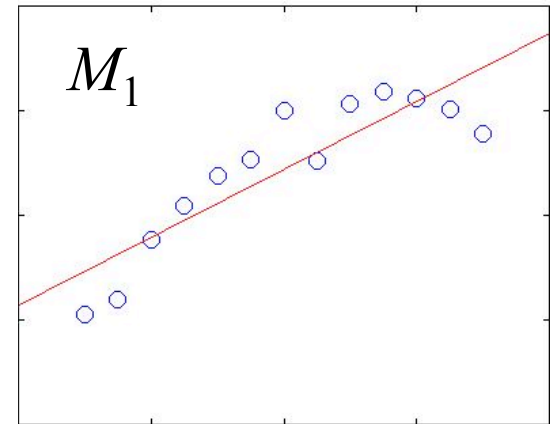
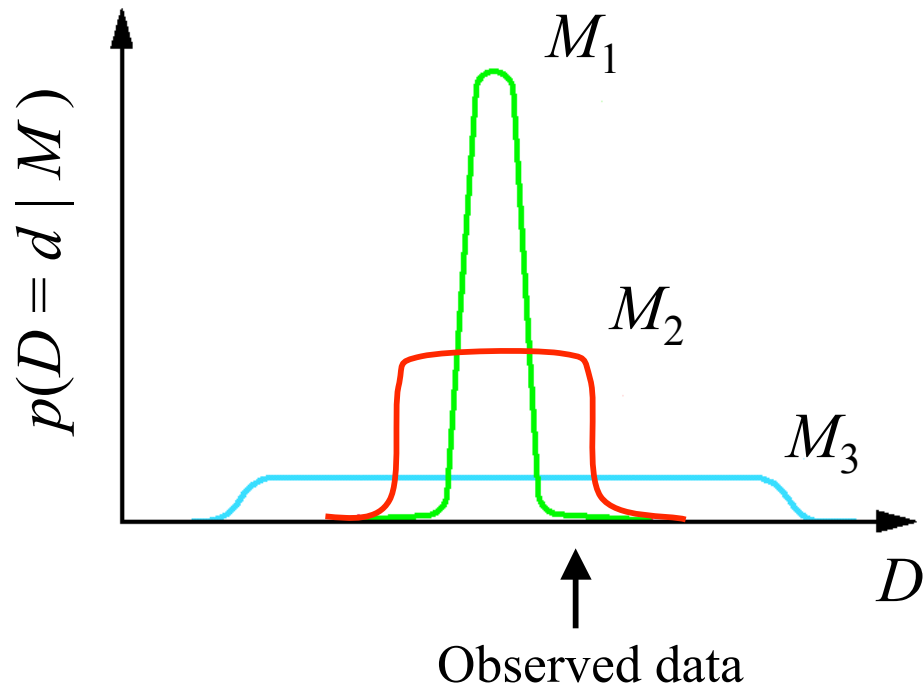
Law of “conservation of belief”: A model that can predict many possible data sets must assign each of them low probability.

Occam's Razor in curve fitting





$$\sum_{\text{all } d \in D} p(D = d \mid M) = 1$$



M_1 : A model that is *too simple* is unlikely to generate the data.

M_3 : A model that is *too complex* can generate many possible data sets, so it is unlikely to generate this particular data set at random.

Summary so far

- Three kinds of Bayesian inference
 - Comparing two simple hypotheses
 - Parameter estimation
 - The importance and subtlety of prior knowledge
 - Model selection
 - Bayesian Occam's razor, the blessing of abstraction
- Key concepts
 - Probabilistic generative models
 - Hierarchies of abstraction, with statistical inference at all levels
 - Flexibly structured representations

Plan for this lecture

- Some basic aspects of Bayesian statistics
 - Comparing two hypotheses
 - Model fitting
 - Model selection
- Two (very brief) case studies in modeling human inductive learning
 - Causal learning
 - Concept learning

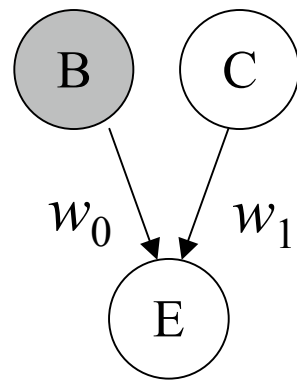
Learning causation from correlation

	C present (c^+)	C absent (c^-)
E present (e^+)	a	c
E absent (e^-)	b	d

“Does C cause E ?”
(rate on a scale from 0 to 100)

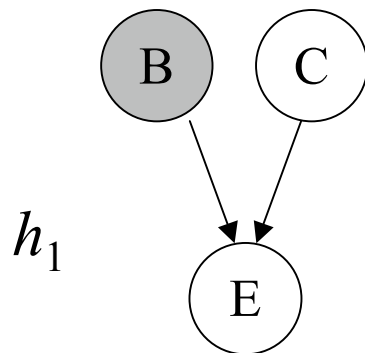
Learning with graphical models

- **Strength:** how strong is the relationship?

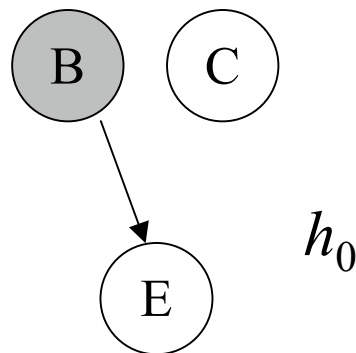


Delta-P, Power PC, ...

- **Structure:** does a relationship exist?

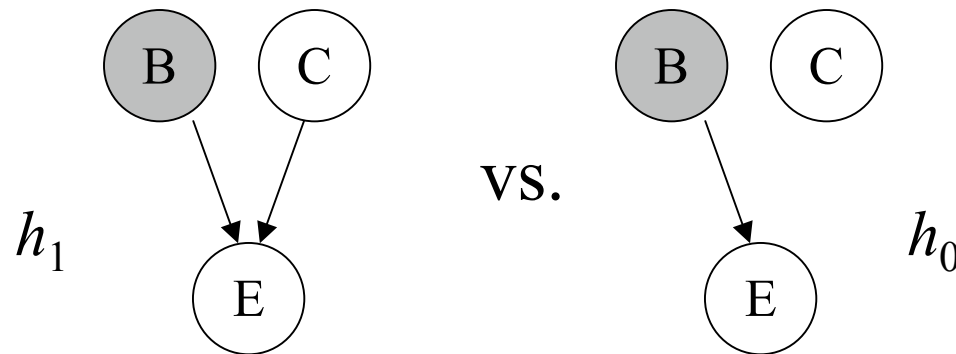


VS.



Bayesian learning of causal structure

- Hypotheses:



- Bayesian causal inference:

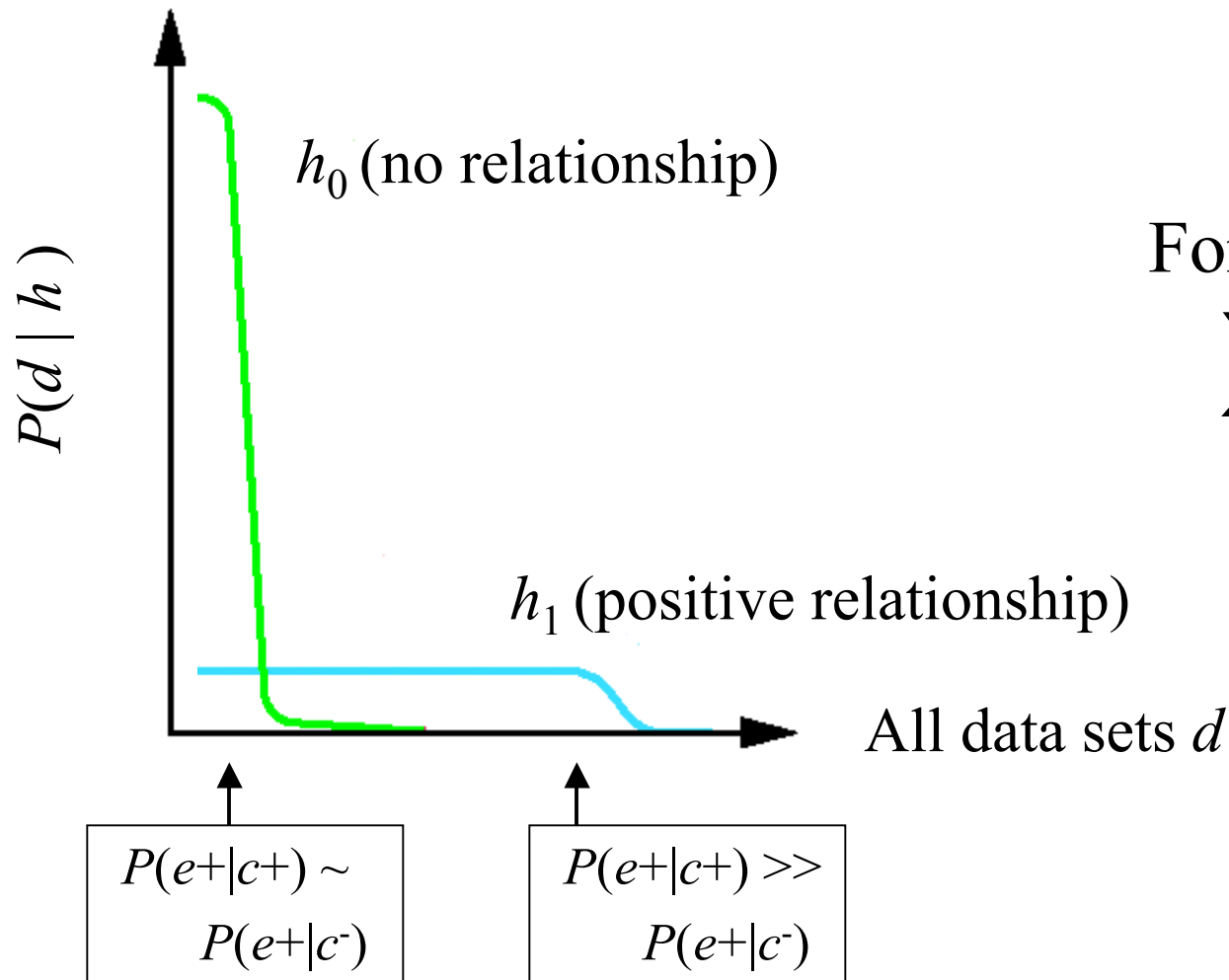
$$\text{support} = \log \frac{P(d|h_1)}{P(d|h_0)}$$

likelihood ratio (Bayes factor)
gives evidence in favor of h_1

$$P(d|h_1) = \int_0^1 \int_0^1 P(d|w_0, w_1) p(w_0, w_1|h_1) dw_0 dw_1$$

$$P(d|h_0) = \int_0^1 P(d|w_0) p(w_0|h_0) dw_0$$

Bayesian Occam's Razor

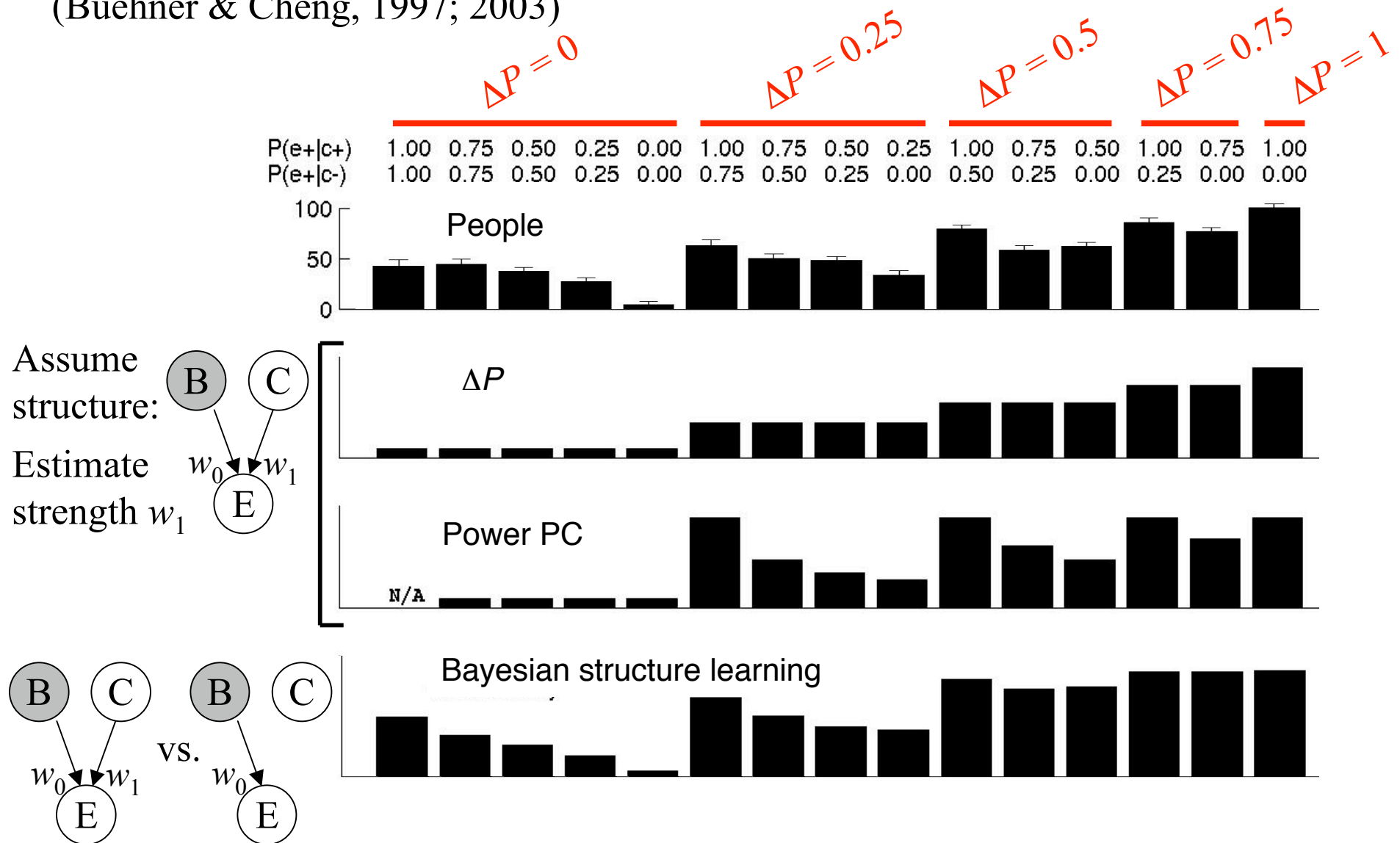


For any model h ,

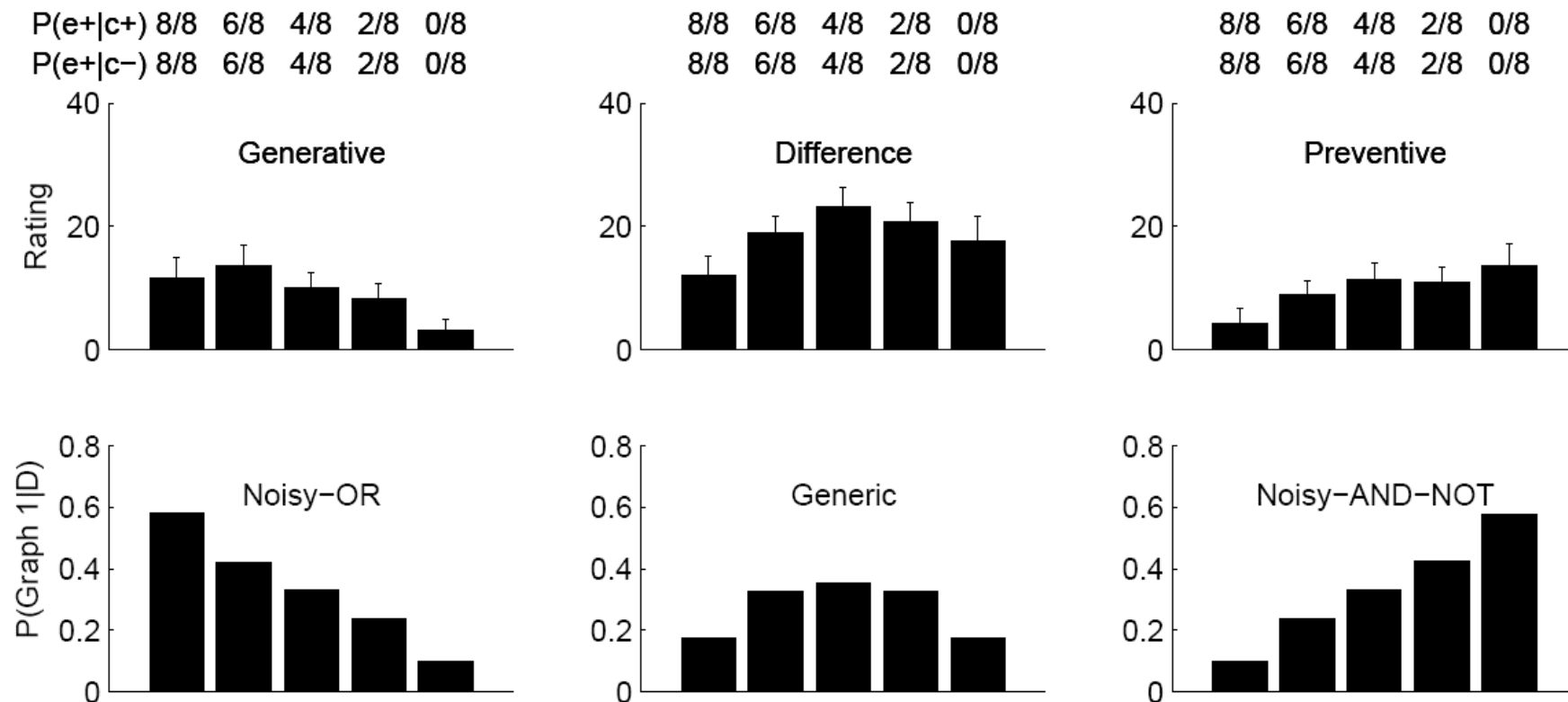
$$\sum_d P(d | h) = 1$$

Comparison with human judgments

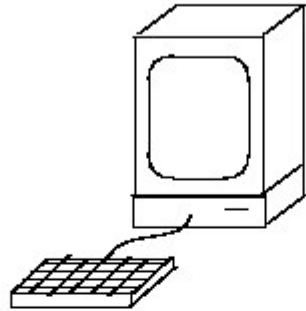
(Buehner & Cheng, 1997; 2003)



Inferences about causal structure depend on the functional form of causal relations



Concept learning: the number game



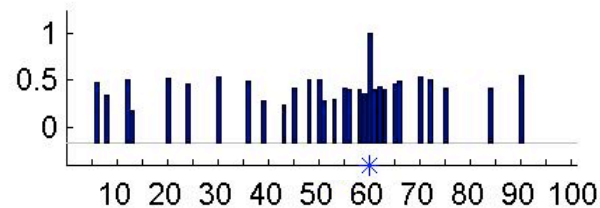
- Program input: number between 1 and 100
- Program output: “yes” or “no”
- Learning task:
 - Observe one or more positive (“yes”) examples.
 - Judge whether other numbers are “yes” or “no”.

Concept learning: the number game

Examples of
“yes” numbers

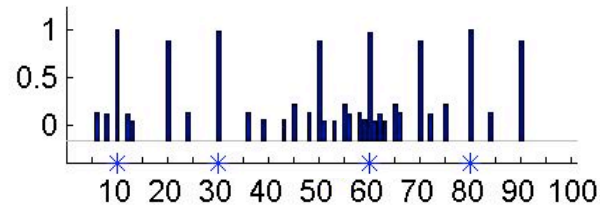
Generalization
judgments ($N = 20$)

60



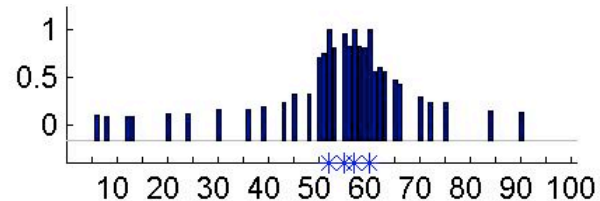
Diffuse similarity

60 80 10 30



Rule:
“multiples of 10”

60 52 57 55



Focused similarity:
numbers near 50-60

Bayesian model

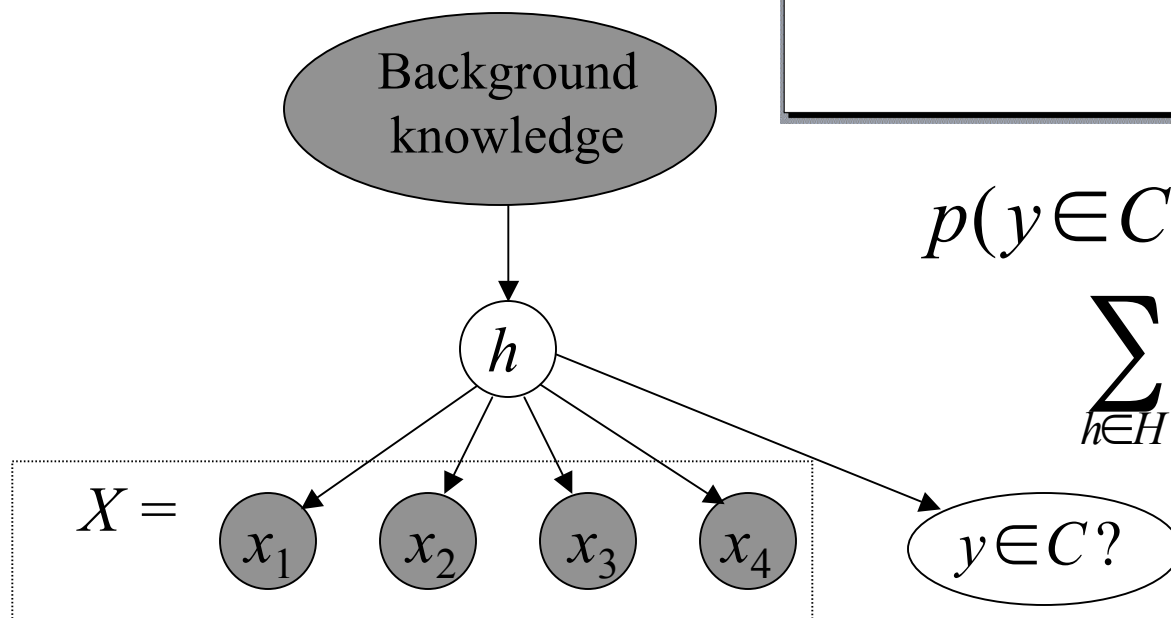
- H : Hypothesis space of possible concepts:
 - H^1 : Mathematical properties: multiples and powers of small numbers.
 - H^2 : Magnitude: intervals with endpoints between 1 and 100.
- $X = \{x_1, \dots, x_n\}$: n examples of a concept C .
- Evaluate hypotheses given data:

$$p(h | X) = \frac{p(X | h) p(h)}{\sum_{h' \in H} p(X | h') p(h')}$$

- $p(h)$ [prior]: domain knowledge, pre-existing biases
- $p(X|h)$ [likelihood]: statistical information in examples.
- $p(h|X)$ [posterior]: degree of belief that h is the true extension of C .

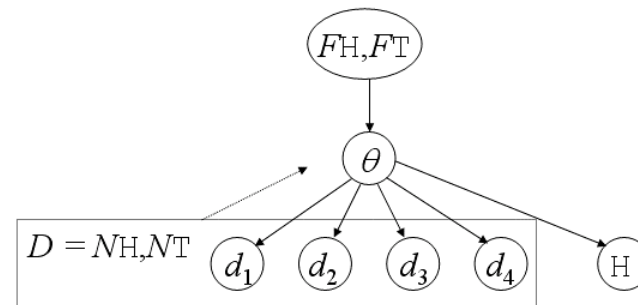
Generalizing

Given $p(h|X)$, how do we estimate the probability that a stimulus y ?



Bayesian parameter estimation

$$P(\theta | D) \propto P(D | \theta) P(\theta) = \theta^{N_H + F_H - 1} (1 - \theta)^{N_T + F_T - 1}$$



- Posterior predictive distribution:

$$\begin{aligned} P(H | D, F_H, F_T) &= \int_0^1 P(H | \theta) P(\theta | D, F_H, F_T) d\theta \\ &= \frac{(N_H + F_H)}{(N_H + F_H + N_T + F_T)} \end{aligned}$$

$$p(y \in C | X) = \sum_{h \in H} p(y \in C | h) p(h | X)$$

Likelihood: $p(X|h)$

- **Size principle:** Smaller hypotheses receive greater likelihood, and exponentially more so as n increases.

$$p(X | h) = \left[\frac{1}{\text{size}(h)} \right]^n \text{ if } x_1, \dots, x_n \in h$$
$$= 0 \text{ if any } x_i \notin h$$

- Follows from assumption of randomly sampled examples + law of “conservation of belief”:
$$\sum_{\text{all } d \in D} p(D = d | M) = 1$$
- Captures the intuition of a “representative” sample.

Illustrating the size principle

A diagram illustrating the size principle. It features a large rectangle containing a 10x5 grid of numbers from 2 to 100. The numbers are arranged in columns: the first four columns contain numbers from 2 to 98 in increments of 2, and the fifth column contains numbers from 10 to 100 in increments of 10. A smaller rectangle is drawn around the fifth column. An arrow labeled h_1 points to the left side of the large rectangle, and an arrow labeled h_2 points to the right side of the large rectangle.

2	4	6	8	10
12	14	16	18	20
22	24	26	28	30
32	34	36	38	40
42	44	46	48	50
52	54	56	58	60
62	64	66	68	70
72	74	76	78	80
82	84	86	88	90
92	94	96	98	100

Illustrating the size principle

A 10x5 grid of numbers from 2 to 100, arranged in rows of 10. The numbers are: 2, 4, 6, 8, 10, 12, 14, 16, 18, 20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50, 52, 54, 56, 58, 60, 62, 64, 66, 68, 70, 72, 74, 76, 78, 80, 82, 84, 86, 88, 90, 92, 94, 96, 98, 100. The number 60 is circled in red. An arrow labeled h_1 points to the left side of the grid, and an arrow labeled h_2 points to the right side. The grid is enclosed in a large rectangle, and a smaller rectangle highlights the rightmost column.

2	4	6	8	10
12	14	16	18	20
22	24	26	28	30
32	34	36	38	40
42	44	46	48	50
52	54	56	58	60
62	64	66	68	70
72	74	76	78	80
82	84	86	88	90
92	94	96	98	100

Data slightly more of a coincidence under h_1

Illustrating the size principle

A 10x5 grid of numbers from 2 to 100. The fifth column is circled in red. Arrows labeled h_1 and h_2 point to the first and fifth columns respectively.

2	4	6	8	10
12	14	16	18	20
22	24	26	28	30
32	34	36	38	40
42	44	46	48	50
52	54	56	58	60
62	64	66	68	70
72	74	76	78	80
82	84	86	88	90
92	94	96	98	100

Data *much* more of a coincidence under h_1

Prior: $p(h)$

- Choice of hypothesis space embodies a strong prior: effectively, $p(h) \sim 0$ for many logically possible but conceptually unnatural hypotheses.
- Prevents overfitting by highly specific but unnatural hypotheses, e.g. “multiples of 10 except 50 and 70”.

e.g., $X = \{60\ 80\ 10\ 30\}$:

$$p(X \mid \text{multiples of } 10) = \left[\frac{1}{10} \right]^4 = 0.0001$$

$$p(X \mid \text{multiples of } 10 \text{ except } 50, 70) = \left[\frac{1}{8} \right]^4 = 0.00024$$

Posterior:
$$p(h | X) = \frac{p(X | h) p(h)}{\sum_{h' \in H} p(X | h') p(h')}$$

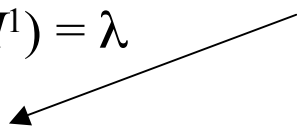
- $X = \{60, 80, 10, 30\}$
- Why prefer “multiples of 10” over “even numbers”? $p(X|h)$.
- Why prefer “multiples of 10” over “multiples of 10 except 50 and 20”? $p(h)$.
- Why does a good generalization need both high prior and high likelihood? $p(h|X) \sim p(X|h) p(h)$

Prior: $p(h)$

- Choice of hypothesis space embodies a strong prior: effectively, $p(h) \sim 0$ for many logically possible but conceptually unnatural hypotheses.
- Prevents overfitting by highly specific but unnatural hypotheses, e.g. “multiples of 10 except 50 and 70”.
- $p(h)$ encodes relative weights of alternative theories:

H : Total hypothesis space

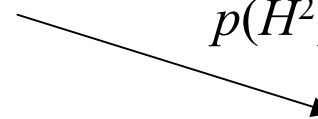
$$p(H^1) = \lambda$$



H^1 : Mathematical properties (24)

- even numbers
- powers of two
- multiples of three
- ... $p(h) = \lambda / 24$

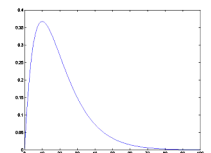
$$p(H^2) = 1 - \lambda$$



H^2 : Magnitude intervals (5050)

- 10-15
- 20-32
- 37-54

$$\dots p(h) = 1 - \lambda / 5050 * \text{Gamma}(s; \sigma)$$

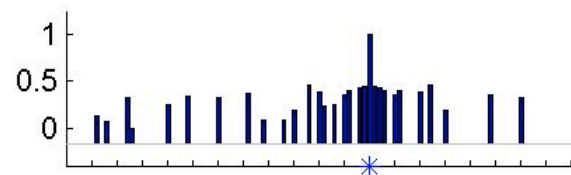
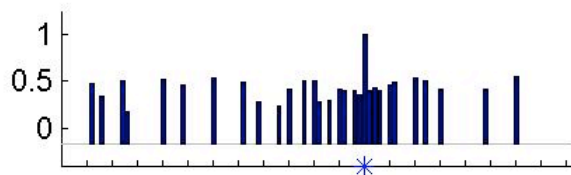


+ Examples

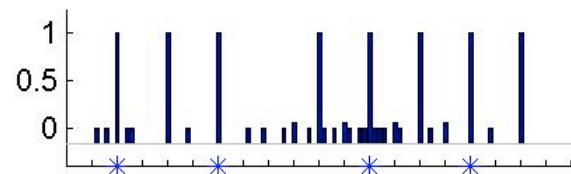
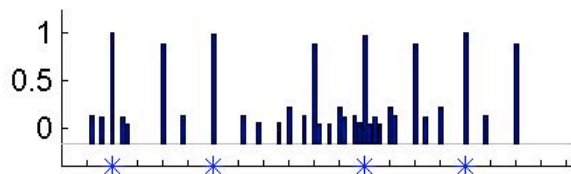
Human generalization

Bayesian Model

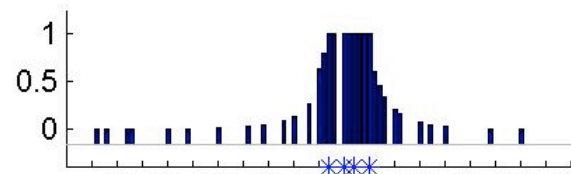
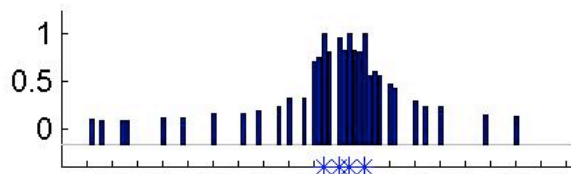
60



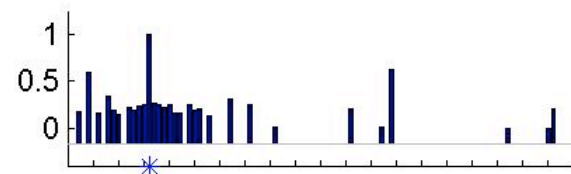
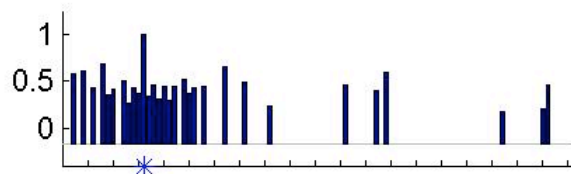
60 80 10 30



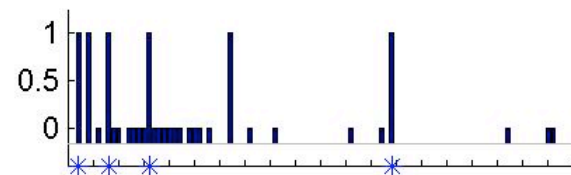
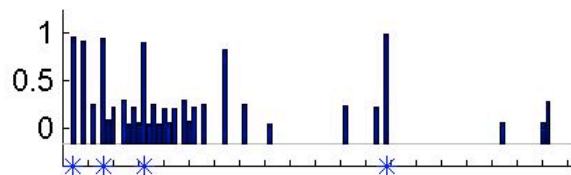
60 52 57 55



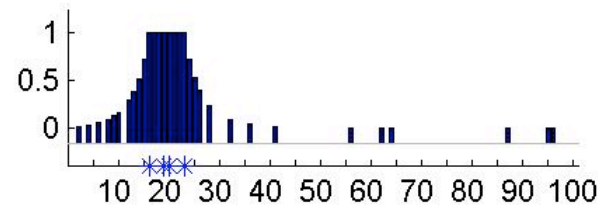
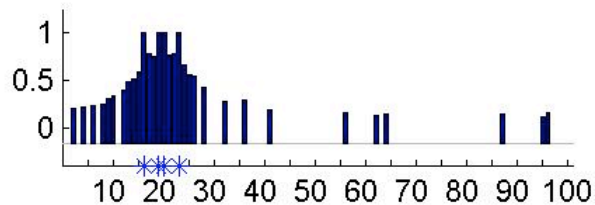
16



16 8 2 64

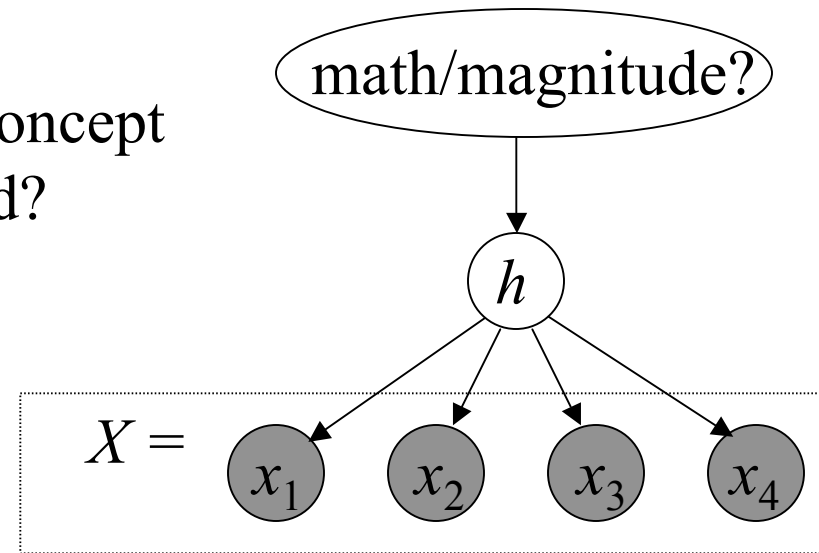


16 23 19 20



Stability versus Flexibility

- Higher-level hypothesis: is this concept mathematical or magnitude-based?
- Example probabilities:
 - $P(\text{math}) = \lambda$
 - $P(h \mid \text{math}) \dots$
 - $P(h \mid \text{magnitude}) \dots$
- Just a few examples may be sufficient to infer the kind of concept, under the size-principle likelihood
 - if an *a priori* reasonable hypothesis of one kind fits much more tightly than all reasonable hypothesis of the other kind.
- Just a few examples can give all-or-none, “rule-like” generalization or more graded, “similarity-like” generalization.
 - More all-or-none when the smallest consistent hypothesis is much smaller than all other reasonable hypotheses; otherwise more graded.



Conclusion:

Contributions of Bayesian models

- A framework for understanding how the mind can solve fundamental problems of induction.
- Strong, principled quantitative models of human cognition.
- Tools for studying people's implicit knowledge of the world.
- Beyond classic limiting dichotomies: “rules vs. statistics”, “nature vs. nurture”, “domain-general vs. domain-specific” .
- A unifying mathematical language for all of the cognitive sciences: AI, machine learning and statistics, psychology, neuroscience, philosophy, linguistics.... A bridge between engineering and “reverse-engineering”.

A toolkit for reverse-engineering induction

1. Bayesian inference in probabilistic generative models
2. Probabilities defined over structured representations: graphs, grammars, predicate logic, schemas
3. Hierarchical probabilistic models, with inference at all levels of abstraction
4. Models of unbounded complexity (“nonparametric Bayes” or “infinite models”), which can grow in complexity or change form as observed data dictate.
5. Approximate methods of learning and inference, such as belief propagation, expectation-maximization (EM), Markov chain Monte Carlo (MCMC), and sequential Monte Carlo (particle filtering).